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LAMPIRAN

Lampiran 1. Titik Kesetimbangan, Analisis Kestabilan Lokal, dan Analisis Kestabilan Global dari E_K

```

> restart
> with(LinearAlgebra) :
>
> r1 := 0.44;
  r2 := 0.18;
  r3 := 0.0245;
  b1 := 9.8 * 10^(-8);
  b2 := 1 * 10^(-9);
  b3 := 1 * 10^(-10);
  rho1 := 1.1 * 10^(-10);
  rho2 := 4.8 * 10^(-10);
  mu1 := 0.01;
  mu2 := 0.0412;
  alpha1 := 1.101 * 10^(-7);
  alpha2 := 3.422 * 10^(-10);
  betaa := 6.2 * 10^(-9);
  gamma1 := 0.01;
  q1 := 0.9;
  q2 := 1 * 10^(-12);
  q3 := 1 * 10^(-5);
  q4 := 2 * 10^(-11);
  delta1 := 0.0357;
  u0 := 0.5;
>
> EKC := 0;
  EKH := (r2 * gamma1 - mu1 * gamma1 - q2 * delta1 * u0) / (r2 * b2 * gamma1);
  EKIP := (mu2 * gamma1 + q4 * delta1 * u0) / (betaa * gamma1);
  EKIS := (r3 * betaa * gamma1 - r3 * b3 * mu2 * gamma1 - r3 * b3 * q4 * delta1 * u0 - betaa
    * q3 * delta1 * u0) / ((betaa)^2 * gamma1);
  EKDK := (delta1 * u0) / gamma1;
                                EKC := 0
                                EKH := 9.444444444 108
                                EKIP := 6.645161297 106
                                EKIS := 3.946107960 106
                                EKDK := 1.785000000
(I)
> xi1 := r1 - 2 * r1 * b1 * EKC - rho1 * EKH - alpha1 * EKIS - q1 * EKDK;
  xi2 := -rho1 * EKC;
  xi3 := -alpha1 * EKC;
  xi4 := -q1 * EKC;
  xi5 := -rho2 * EKH;
  xi6 := r2 - 2 * r2 * b2 * EKH - mu1 - rho2 * EKC - q2 * EKDK;
  xi7 := -q2 * EKIH;
  xi8 := r3 - 2 * r3 * b3 * EKIP - betaa * EKIS - q3 * EKDK;
  xi9 := -betaa * EKIP;
  xi10 := -q3 * EKIP;
  xi11 := -alpha2 * EKIS;

```



```

xi12 := betaa * EKIS;
xi13 := betaa * EKIP - mu2 - alpha2 * EKC - q4 * EKDK;
xi14 := -q4 * EKIS;
xi15 := -gamma1;
>
> j1 := -(xi13 + xi15 + xi6 + xi8 + xi1) / 2;
j2 := ((xi1 + xi15 + xi6 + xi8) * xi13 + (xi1 + xi6 + xi8) * xi15 + (xi6 + xi8) * xi1 - xi5 * xi2
      - xi11 * xi3 + xi8 * xi6 - xi12 * xi9) / 4;
j3 := (((-xi1 - xi13 - xi8) * xi6 + (-xi1 - xi13) * xi8 - xi13 * xi1 + xi5 * xi2 + xi11 * xi3 + xi12
      * xi9) * xi15 + ((-xi1 - xi13) * xi8 - xi13 * xi1 + xi11 * xi3 + xi12 * xi9) * xi6 + (-xi1 * xi13
      + xi11 * xi3 + xi2 * xi5) * xi8 + xi1 * xi12 * xi9 + xi13 * xi2 * xi5) / 8;
j4 := (((xi1 + xi13) * xi8 + xi13 * xi1 - xi11 * xi3 - xi12 * xi9) * xi6 + (xi1 * xi13 - xi11 * xi3 - xi2
      * xi5) * xi8 - xi1 * xi12 * xi9 - xi13 * xi2 * xi5) * xi15 + ((xi1 * xi13 - xi11 * xi3) * xi8 - xi1 * xi12
      * xi9) * xi6 - xi5 * xi2 * (-xi12 * xi9 + xi13 * xi8) / 16;
j5 := -(xi15 * (-xi1 * xi12 * xi6 * xi9 + xi1 * xi13 * xi6 * xi8 - xi11 * xi3 * xi6 * xi8 + xi12 * xi2
      * xi5 * xi9 - xi13 * xi2 * xi5 * xi8) / 32;

> QK1 := j1;
QK2 := j1 * j2 - j3;
QK3 := j1 * j2 * j3 + j1 * j5 - (((j3)^2) + ((j1)^2) * j4);
QK4 := j1 * j2 * j3 * j4 + 2 * j1 * j4 * j5 + j2 * j3 * j5 - ((j1)^2) * ((j4)^2) - ((j3)^2) * j4
      - ((j5)^2) - j1 * ((j2)^2) * j5;
QK5 := j1 * j2 * j3 * j4 * j5 + ((j3)^3) * (2 * j1 * j4 + j2 * j3) - j5 * ((j1)^2) * ((j4)^2)
      + ((j3)^2) * j4 + ((j5)^2) + j1 * ((j2)^2) * j5;

QK1 := 0.9424358278
QK2 := 0.07234711297
QK3 := 0.00002625427262
QK4 := 8.86742499 10-13
QK5 := 1.798933273 10-14
(2)

> JK := [ [ xi1 xi2 0 xi3 xi4
            xi5 xi6 0 0 xi7
            0 0 xi8 xi9 xi10
            xi11 0 xi12 xi13 xi14
            0 0 0 0 xi15 ] ];
JK := [ [ -1.704855375, -0., 0, -0., -0. ],
        [ -0.4533333333, -0.1700000000, 0, 0, -1/100000000000000 * EKIH ],
        [ 0, 0, -0.00001628064036, -0.04120000004, -66.45161297 ],
        [ -0.001350358144, 0, 0.02446586935, 4.30000000 10-12, -0.00007892215920 ],
        [ 0, 0, 0, 0, -0.01 ] ]
(3)

```



> $JKT := \text{Transpose}(JK);$
 $JKT := \begin{bmatrix} -1.704855375, -0.4533333333, 0, -0.001350358144, 0 \end{bmatrix},$ (4)

$\begin{bmatrix} -0., -0.1700000000, 0, 0, 0 \end{bmatrix},$

$\begin{bmatrix} 0, 0, -0.00001628064036, 0.02446586935, 0 \end{bmatrix},$

$\begin{bmatrix} -0., 0, -0.04120000004, 4.30000000 \cdot 10^{-12}, 0 \end{bmatrix},$

$\begin{bmatrix} -0., -\frac{1}{1000000000000} EKIH, -66.45161297, -0.00007892215920, -0.01 \end{bmatrix}]]$

> $RK := \text{IdentityMatrix}(5);$

$$RK := \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$
 (5)

> $PK_Matlab := [[10.7099068494393, -3.24289408172308, -46.0926015395673,$
 $-453.686768255177, -637967.949433706],$
 $[-3.24289408172308, 2.94117647061912, 0, 0, -0.0154320987655851],$
 $[-46.0926015395673, 0, 48948.667659411, 12.1359223195922, -29370459.1628123],$
 $[-453.686768255177, 0, 12.1359223195922, 82428.5161360171, 120924996.150701],$
 $[-637967.949433706, -0.0154320987655851, -29370459.1628123, 120924996.150701,$
 $195170484160.659]]$

> $PK := PK_Matlab;$

$PK := [[10.7099068494393, -3.24289408172308, -46.0926015395673,$ (6)
 $-453.686768255177, -6.37967949433706 \cdot 10^5],$
 $[-3.24289408172308, 2.94117647061912, 0, 0, -0.0154320987655851],$
 $[-46.0926015395673, 0, 48948.667659411, 12.1359223195922, -2.93704591628123 \cdot 10^7$
 $],$
 $[-453.686768255177, 0, 12.1359223195922, 82428.5161360171, 1.20924996150701 \cdot 10^8],$
 $[-6.37967949433706 \cdot 10^5, -0.0154320987655851, -2.93704591628123 \cdot 10^7,$
 $1.20924996150701 \cdot 10^8, 1.95170484160659 \cdot 10^{11}]]$

> $PKT := \text{Transpose}(PK);$

$PKT := [[10.7099068494393, -3.24289408172308, -46.0926015395673,$ (7)
 $-453.686768255177, -6.37967949433706 \cdot 10^5],$
 $[-3.24289408172308, 2.94117647061912, 0, 0, -0.0154320987655851],$
 $[-46.0926015395673, 0, 48948.667659411, 12.1359223195922, -2.93704591628123 \cdot 10^7$
 $],$



```

[-453.686768255177, 0, 12.1359223195922, 82428.5161360171, 1.20924996150701 108],
[-6.37967949433706 105, -0.0154320987655851, -2.93704591628123 107,
1.20924996150701 108, 1.95170484160659 1011]]
> DetSubMatPk1 := PK(1, 1);
DetSubMatPk1 := 10.7099068494393 (8)
> DetSubMatPk2 := Determinant(PK(1..2, 1..2));
DetSubMatPk2 := 20.98336400 (9)
> DetSubMatPk3 := Determinant(PK(1..3, 1..3));
DetSubMatPk3 := 1.020859099 106 (10)
> DetSubMatPk4 := Determinant(PK(1..4, 1..4));
DetSubMatPk4 := 5.451648852 1010 (11)
> DetSubMatPk5 := Determinant(PK )
DetSubMatPk5 := 6.849711091 1018 (12)
> f1 := r1*C - r1*b1*C*C - rho1*H*C - alpha1*IS*C - q1*DK*C;
f2 := r2*H - r2*b2*H*H - mu1*H - rho2*C*H - q2*DK*H;
f3 := r3*IP - r3*b3*IP*IP - betaa*IS*IP - q3*DK*IP;
f4 := betaa*IP*IS - mu2*IS - alpha2*C*IS - q4*DK*IS;
f5 := delta1*u0 - gamma1*DK;
> f :=  $\begin{bmatrix} f1 \\ f2 \\ f3 \\ f4 \\ f5 \end{bmatrix}$ ;
> fT := Transpose(f);
> fTP := fT.PK;
>
> VK1 := fTP(1, 1);
VK1 := -4.618111834 10-7 C2 - 9.638916165 C DK + 3.78499405 10-10 C H (13)
- 0.000001023909132 C IS + 4.712359014 C + 3.242894082 10-12 DK H
+ 5.837209348 10-10 H2 - 0.5512919939 H + 0.0004609260154 DK IP
+ 1.129268738 10-10 IP2 - 0.000002527083834 IP IS - 1.129268738 IP
+ 9.073735366 10-9 DK IS + 18.69189485 IS + 6379.679494 DK - 11387.72790
> VK2 := fTP(1, 2);
VK2 := 1.398335928 10-7 C2 + 2.918604674 C DK - 1.055046357 10-9 C H (14)
+ 3.570426384 10-7 C IS - 1.426873396 C - 2.941176471 10-12 DK H
- 5.294117648 10-10 H2 + 0.5000000001 H - 0.0002754629630 + 0.0001543209877 DK
> VK3 := fTP(1, 3);
VK3 := 0.000001987512978 C2 + 41.48334139 C DK + 5.070186169 10-9 C H (15)
+ 0.000005070642517 C IS - 20.28074468 C - 5.242626960 105 - 0.4894866766 DK IP

```



$$-1.199242358 \cdot 10^{-7} IP^2 - 0.0003034064968 IP IS + 1199.242358 IP$$

$$- 2.427184464 \cdot 10^{-10} DK IS - 0.4999999996 IS + 2.937045916 \cdot 10^5 DK$$

> VK4 := fTP(1, 4);

$$VK4 := 0.00001956297345 C^2 + 408.3180915 C DK + 4.990554451 \cdot 10^{-8} C H$$

$$+ 0.00002174387497 C IS - 199.6221781 C + 2.158511182 \cdot 10^6$$

$$- 0.0001213592232 DK IP - 2.973300968 \cdot 10^{-11} IP^2 + 0.0005109815574 IP IS$$

$$+ 0.2973300968 IP - 0.000001648570323 DK IS - 3396.054865 IS$$

$$- 1.209249962 \cdot 10^6 DK$$

> VK5 := fTP(1, 5);

$$VK5 := 0.02750917798 C^2 + 5.741711545 \cdot 10^5 C DK + 0.00007017648184 C H$$

$$+ 0.02885973753 C IS - 2.807058977 \cdot 10^5 C + 1.543209877 \cdot 10^{-14} DK H$$

$$+ 2.777777779 \cdot 10^{-12} IP^2 - 0.002623456791 H + 293.7045916 DK IP$$

$$+ 0.00007195762494 IP^2 + 0.9318318232 IP IS - 7.195762494 \cdot 10^5 IP$$

$$- 0.002418499924 DK IS - 4.982109843 \cdot 10^6 IS - 1.951704842 \cdot 10^9 DK$$

$$+ 3.483793143 \cdot 10^9$$

> AI := f(1, 1);

$$AI := -4.312000000 \cdot 10^{-8} C^2 - 0.9 C DK - 1.100000000 \cdot 10^{-10} C H - 1.101000000 \cdot 10^{-7} C IS$$

$$+ 0.44 C$$

> A2 := f(2, 1);

$$A2 := -4.800000000 \cdot 10^{-10} C H - \frac{1}{1000000000000} DK H - 1.800000000 \cdot 10^{-10} IP^2 + 0.17 H$$

> A3 := f(3, 1);

$$A3 := -\frac{1}{100000} DK IP - 2.450000000 \cdot 10^{-12} IP^2 - 6.200000000 \cdot 10^{-9} IP IS + 0.0245 IP$$

> A4 := f(4, 1);

$$A4 := -3.422000000 \cdot 10^{-10} C IS - \frac{1}{500000000000} DK IS + 6.200000000 \cdot 10^{-9} IP IS - 0.0412 IS$$

> A5 := f(5, 1);

$$A5 := -0.01 DK + 0.01785$$

> VK := fTPf;

$$VK := (-4.618111834 \cdot 10^{-7} C^2 - 9.638916165 C DK + 3.78499405 \cdot 10^{-10} C H$$

$$- 0.000001023909132 C IS + 4.712359014 C + 3.242894082 \cdot 10^{-12} DK H$$

$$+ 5.837209348 \cdot 10^{-10} H^2 - 0.5512919939 H + 0.0004609260154 DK IP$$

$$+ 1.129268738 \cdot 10^{-10} IP^2 - 0.000002527083834 IP IS - 1.129268738 IP$$

$$+ 9.073735366 \cdot 10^{-9} DK IS + 18.69189485 IS + 6379.679494 DK - 11387.72790) ($$

$$-4.312000000 \cdot 10^{-8} C^2 - 0.9 C DK - 1.100000000 \cdot 10^{-10} C H - 1.101000000 \cdot 10^{-7} C IS$$

$$+ 0.44 C) + (1.398335928 \cdot 10^{-7} C^2 + 2.918604674 C DK - 1.055046357 \cdot 10^{-9} C H$$

$$+ 3.570426384 \cdot 10^{-7} C IS - 1.426873396 C - 2.941176471 \cdot 10^{-12} DK H$$

$$- 5.294117648 \cdot 10^{-10} H^2 + 0.5000000001 H - 0.0002754629630 + 0.0001543209877 DK)$$



$$\begin{aligned}
& \left(-4.800000000 \cdot 10^{-10} C H - \frac{1}{1000000000000} DKH - 1.800000000 \cdot 10^{-10} H^2 + 0.17 H \right) \\
& + \left(0.000001987512978 C^2 + 41.48334139 C DK + 5.070186169 \cdot 10^{-9} C H \right. \\
& + 0.000005070642517 C IS - 20.28074468 C - 5.242626960 \cdot 10^5 - 0.4894866766 DK IP \\
& - 1.199242358 \cdot 10^{-7} IP^2 - 0.0003034064968 IP IS + 1199.242358 IP \\
& \left. - 2.427184464 \cdot 10^{-10} DK IS - 0.4999999996 IS + 2.937045916 \cdot 10^5 DK \right) \left(\right. \\
& \left. - \frac{1}{100000} DK IP - 2.450000000 \cdot 10^{-12} IP^2 - 6.200000000 \cdot 10^{-9} IP IS + 0.0245 IP \right) \\
& + \left(0.00001956297345 C^2 + 408.3180915 C DK + 4.990554451 \cdot 10^{-8} C H \right. \\
& + 0.00002174387497 C IS - 199.6221781 C + 2.158511182 \cdot 10^6 \\
& - 0.0001213592232 DK IP - 2.973300968 \cdot 10^{-11} IP^2 + 0.0005109815574 IP IS \\
& + 0.2973300968 IP - 0.000001648570323 DK IS - 3396.054865 IS \\
& \left. - 1.209249962 \cdot 10^6 DK \right) \left(-3.422000000 \cdot 10^{-10} C IS - \frac{1}{50000000000} DK IS \right. \\
& \left. + 6.200000000 \cdot 10^{-9} IP IS - 0.0412 IS \right) + \left(0.02750917798 C^2 + 5.741711545 \cdot 10^5 C DK \right. \\
& + 0.00007017648184 C H + 0.02885973753 C IS - 2.807058977 \cdot 10^5 C \\
& + 1.543209877 \cdot 10^{-14} DKH + 2.777777779 \cdot 10^{-12} H^2 - 0.002623456791 H \\
& + 293.7045916 DK IP + 0.00007195762494 IP^2 + 0.9318318232 IP IS \\
& - 7.195762494 \cdot 10^5 IP - 0.002418499924 DK IS - 4.982109843 \cdot 10^6 IS \\
& \left. - 1.951704842 \cdot 10^9 DK + 3.483793143 \cdot 10^9 \right) (-0.01 DK + 0.01785)
\end{aligned}$$



Lampiran 2. Matriks P_K

```

clc; close all;
%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);
gamma1 = 0.01;
q1 = 0.08;
q2 = 1*10^(-12);
q3 = 1*10^(-5);
q4 = 2*10^(-11);
delta1 = 0.0357;
u0 = 0.5;
%EK
EKC = 0;
EKH = (r2*gamma1-mu1*gamma1-q2*delta1*u0)/(r2*b2*gamma1);
EKIP = (mu2*gamma1+q4*delta1*u0)/(beta*gamma1);
EKIS = (r3*beta*gamma1-r3*b3*mu2*gamma1-r3*b3*q4*delta1*u0-
beta*q3*delta1*u0)/((beta)^2)*gamma1);
EKDK = (delta1*u0)/gamma1;
%Nilai JK
xi1 = r1-2*r1*b1*EKC-rho1*EKH-alpha1*EKIS-q1*EKDK;
xi2 = -rho1*EKC;
xi3 = -alpha1*EKC;
xi4 = -q1*EKC;
xi5 = -rho2*EKH;
xi6 = r2-2*r2*b2*EKH-mu1-rho2*EKC-q2*EKDK;
xi7 = -q2*E1H;
xi8 = r3-2*r3*b3*EKIP-beta*EKIS-q3*EKDK;
xi9 = -beta*EKIP;
xi10= -q3*EKIP;
xi11= -alpha2*EKIS;
xi12= beta*EKIS;
xi13= beta*EKIP-mu2-alpha2*EKC-q4*EKDK;
xi14= -q4*EKIS;
xi15= -gamma1;
%Matriks JK
JK = [xi1 xi2 0 xi3 xi4; xi5 xi6 0 0 xi7; 0 0 xi8 xi9 xi10; xi11 0
xi12 xi13 xi14; 0 0 0 0 xi15]
JKT = transpose(JK);
%Matriks RK
RK = eye(5);
% s P by Lyapunov Eq
Lyap(JKT,RK);
a(PK_Ly,15)

```



Lampiran 3. Titik Keseimbangan, Analisis Kestabilan Lokal, dan Analisis Kestabilan Global dari E_I

```

> restart
> with(LinearAlgebra) :
> r1 := 0.44;
  r2 := 0.18;
  r3 := 0.0245;
  b1 := 9.8 * 10^(-8);
  b2 := 1 * 10^(-9);
  b3 := 1 * 10^(-10);
  rho1 := 1.1 * 10^(-10);
  rho2 := 4.8 * 10^(-10);
  mu1 := 0.01;
  mu2 := 0.0412;
  alpha1 := 1.101 * 10^(-7);
  alpha2 := 3.422 * 10^(-10);
  betaa := 6.2 * 10^(-9);
  gamma2 := 0.02;
  s1 := 1 * 10^(-2);
  s2 := 1 * 10^(-5);
  delta2 := 0.0179;
  v0 := 0.4;

>
> EIC := 0;
  EIH := (r2-mu1) / (r2*b2);
  EIIP := (mu2*gamma2 + s2*delta2*v0) / (betaa*gamma2);
  EIS := (r3*betaa*gamma2 - r3*b3*mu2*gamma2 + r3*b3*s2*delta2*v0 + betaa*s1
    *delta2*v0) / ((betaa)^2)*gamma2;
  EIDI := (delta2*v0) / gamma2;

      EIC := 0
      EIH := 9.444444444 108
      EIIP := 6.645738710 106
      EIS := 4.526406575 106
      EIDI := 0.3580000000
(1)

> ze1 := r1 - 2*r1*b1*EIC - rho1*EIH - alpha1*EIS;
  ze2 := -rho1*EIC;
  ze3 := -alpha1*EIC;
  ze4 := -rho2*EIH;
  ze5 := r2 - 2*r2*b2*EIH - mu1 - rho2*EIC;
  ze6 := r3 - 2*r3*b3*EIIP - betaa*EIS + s1*EIDI;
  ze7 := -betaa*EIIP;
  ze8 := s1*EIIP;
  ze9 := -alpha2*EIS;
  ze10 := betaa*EIS;
  ze11 := betaa*EIIP - mu2 - alpha2*EIC + s2*EIDI;
  ze12 := s2*EIS;
  ze13 := -gamma2;

```



```

> k1 := -(ze1 + ze5 + ze6 + ze11 + ze13) / 2;
k2 := ((ze1 + ze13 + ze5 + ze6) * ze11 + (ze1 + ze5 + ze6) * ze13 + (ze5 + ze6) * ze1 - ze2
* ze4 - ze3 * ze9 + ze6 * ze5 - ze10 * ze7) / 4;
k3 := (((-ze1 - ze11 - ze6) * ze5 + (-ze1 - ze11) * ze6 - ze11 * ze1 + ze4 * ze2 + ze9 * ze3 + ze10
* ze7) * ze13 + ((-ze1 - ze11) * ze6 - ze11 * ze1 + ze9 * ze3 + ze10 * ze7) * ze5 + (-ze1 * ze11
+ ze2 * ze4 + ze3 * ze9) * ze6 + ze1 * ze10 * ze7 + ze11 * ze2 * ze4) / 8;
k4 := (((ze1 + ze11) * ze6 + ze11 * ze1 - ze9 * ze3 - ze10 * ze7) * ze5 + (ze1 * ze11 - ze2 * ze4
- ze3 * ze9) * ze6 - ze1 * ze10 * ze7 - ze11 * ze2 * ze4) * ze13 + ((ze1 * ze11 - ze3 * ze9) * ze6 - ze1
* ze10 * ze7) * ze5 - ze2 * ze4 * (-ze10 * ze7 + ze11 * ze6)) / 16;
k5 := (ze13 * (ze1 * ze10 * ze5 * ze7 - ze1 * ze11 * ze5 * ze6 - ze10 * ze2 * ze4 * ze7 + ze11 * ze2 * ze4
* ze6 + ze3 * ze5 * ze6 * ze9)) / 32;

> QI1 := k1;
QI2 := k1 * k2 - k3;
QI3 := k1 * k2 * k3 + k1 * k5 - ((k3)^2) - ((k1)^2) * k4;
QI4 := k1 * k2 * k3 * k4 + 2 * k1 * k4 * k5 + k2 * k3 * k5 - ((k1)^2) * ((k4)^2) - ((k3)^2) * k4
- ((k5)^2) - k1 * ((k2)^2) * k5;
QI5 := k1 * k2 * k3 * k4 * k5 + ((k3)^3) * (2 * k1 * k4 + k2 * k3) - k5 * ((k1)^2) * ((k4)^2)
+ ((k3)^2) * k4 + ((k5)^2) + k1 * ((k2)^2) * k5;

QI1 := 0.1761276888
QI2 := 0.001438220417
QI3 := 9.922177293 10-8
QI4 := 1.3181127 10-16
QI5 := 3.330398808 10-18 (2)

> JI := 
$$\begin{bmatrix} ze1 & ze2 & 0 & ze3 & 0 \\ ze4 & ze5 & 0 & 0 & 0 \\ 0 & 0 & ze6 & ze7 & ze8 \\ ze9 & 0 & ze10 & ze11 & ze12 \\ 0 & 0 & 0 & 0 & ze13 \end{bmatrix};$$

JI := [[-0.1622462528, -0., 0, -0., 0],
[-0.4533333333, -0.1700000000, 0, 0, 0],
[0, 0, -0.000016284880, -0.04120358000, 66457.38710],
[-0.001548936330, 0, 0.02806372076, 0.000007160000000, 45.26406575],
[0, 0, 0, 0, -0.02]] (3)

> JIT := Transpose(JI);
JIT := 
$$\begin{bmatrix} -0.1622462528 & -0.4533333333 & 0 & -0.001548936330 & 0 \\ -0. & -0.1700000000 & 0 & 0 & 0 \\ 0 & 0 & -0.000016284880 & 0.02806372076 & 0 \\ -0. & 0 & -0.04120358000 & 0.000007160000000 & 0 \\ 0 & 0 & 66457.38710 & 45.26406575 & -0.02 \end{bmatrix}$$
 (4)

```

```

> RI := IdentityMatrix(5);
                                     (5)
                                     RI :=  $\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$ 

> PI_Matlab := [[ 26.1024026539695, -4.01308764745829, -214.250828184631,
-1236.81689436281, 1297965612.57463 ],
[-4.01308764745829, 2.94117647058824, 0, 0, 0],
[-214.250828184631, 0, 92116.1433076938, 35.6367993722714, 78785600321.2914],
[-1236.81689436281, 0, 35.6367993722714, 135246.328753909, -161945909555.493 ],
[ 1297965612.57463, 0, 78785600321.2914, -161945909555.493, 2.61427740395228e17]]
                                     (6)

> P_I := PI_Matlab;
P_I := [[26.1024026539695, -4.01308764745829, -214.250828184631,
-1236.81689436281, 1.29796561257463 109],
[-4.01308764745829, 2.94117647058824, 0, 0, 0],
[-214.250828184631, 0, 92116.1433076938, 35.6367993722714, 7.87856003212914 1010],
[-1236.81689436281, 0, 35.6367993722714, 1.35246328753909 105,
-1.61945909555493 1011],
[1.29796561257463 109, 0, 7.87856003212914 1010, -1.61945909555493 1011,
2.61427740395228 1017]]
                                     (7)

> P_IT := Transpose(P_I);
P_IT := [[26.1024026539695, -4.01308764745829, -214.250828184631,
-1236.81689436281, 1.29796561257463 109],
[-4.01308764745829, 2.94117647058824, 0, 0, 0],
[-214.250828184631, 0, 92116.1433076938, 35.6367993722714, 7.87856003212914 1010],
[-1236.81689436281, 0, 35.6367993722714, 1.35246328753909 105,
-1.61945909555493 1011],
[1.29796561257463 109, 0, 7.87856003212914 1010, -1.61945909555493 1011,
2.61427740395228 1017]]
                                     (8)

>
> DetSubMatPi1 := P_I(1, 1);
                                     DetSubMatPi1 := 26.1024026539695
                                     (9)
> DetSubMatPi2 := Determinant(P_I(1..2, 1..2));

```



```

DetSubMatPi2 := 60.66690005 (10)
> DetSubMatPi3 := Determinant(P_I(1..3, 1..3));
DetSubMatPi3 := 5.453390808 106 (11)
> DetSubMatPi4 := Determinant(P_I(1..4, 1..4));
DetSubMatPi4 := 3.231608495 1011 (12)
> DetSubMatPi5 := Determinant(P_I(1..5, 1..5));
DetSubMatPi5 := 1.750427973 1025 (13)

> g1 := r1*C - r1*b1*C*C - rho1*H*C - alpha1*IS*C - q1*DK*C;
g2 := r2*H - r2*b2*H*H - mu1*H - rho2*C*H - q2*DK*H;
g3 := r3*IP - r3*b3*IP*IP - betaa*IS*IP - q3*DK*IP;
g4 := betaa*IP*IS - mu2*IS - alpha2*C*IS - q4*DK*IS;
g5 := delta1*u0 - gamma1*DK;

> g := [
g1
g2
g3
g4
g5
];

> gT := Transpose(g);
> gTP := gT.P_I;
> VII := gTP(1, 1);
VII := -26.1024026539695 q1 DK C - 0.000001125535602 C2 - 9.44982221 10-10 C H
- 0.000002450635791 C IS + 11.48505717 C + 4.01308764745829 q2 DK H
+ 7.223557765 10-10 H2 - 0.6822249000 H + 214.250828184631 q3 DK IP
+ 5.249145291 10-10 IP2 - 0.000006339909608 IP IS - 5.249145291 IP
+ 1236.81689436281 q4 DK IS + 50.95685603 IS - 1.29796561257463 109 DK γ
+ 1.29796561257463 109 δI u0 (14)

> VI2 := gTP(1, 2);
VI2 := 4.01308764745829 q1 DK C + 1.730443393 10-7 C2 - 9.703250648 10-10 C H
+ 4.418409499 10-7 C IS - 1.765758565 C - 2.94117647058824 q2 DK H
- 5.294117648 10-10 H2 + 0.5000000001 H (15)

> VI3 := gTP(1, 3);
VI3 := 214.250828184631 q1 DK C + 0.000009238495712 C2 + 2.356759110 10-8 C H
+ 0.00002357682127 C IS - 94.27036441 C - 92116.1433076938 q3 DK IP
- 2.256845511 10-7 IP2 - 0.0005708991403 IP IS + 2256.845511 IP
- 35.6367993722714 q4 DK IS - 1.468236134 IS - 7.87856003212914 1010 DK γ
+ 7.87856003212914 1010 δI u0 (16)

> VI4 := gTP(1, 4);
VI4 := 1236.81689436281 q1 DK C + 0.00005333154447 C2 + 1.360498583 10-7 C H (17)

```



$$\begin{aligned}
& + 0.00008989224628 C IS - 544.1994334 C - 35.6367993722714 q3 DK IP \\
& - 8.731015846 10^{-11} IP^2 + 0.0008383062904 IP IS + 0.8731015846 IP \\
& - 1.35246328753909 10^5 q4 DK IS - 5572.148747 IS + 1.61945909555493 10^{11} DK \gamma \\
& - 1.61945909555493 10^{11} \delta I u0
\end{aligned}$$

$$\begin{aligned}
> VIS &:= gTP(1, 5); \\
VIS &:= -1.29796561257463 10^9 q1 DK C - 55.96827723 C^2 - 0.1427762174 C H & (18) \\
& - 87.48812373 C IS + 5.711048697 10^8 C - 7.87856003212914 10^{10} q3 DK IP \\
& - 0.1930247208 IP^2 - 1492.535362 IP IS + 1.930247208 10^9 IP \\
& + 1.61945909555493 10^{11} q4 DK IS + 6.672171476 10^9 IS \\
& - 2.61427740395228 10^{17} DK \gamma + 2.61427740395228 10^{17} \delta I u0
\end{aligned}$$

$$\begin{aligned}
> B1 &:= g(1, 1); \\
B1 &:= -q1 DK C - 4.312000000 10^{-8} C^2 - 1.100000000 10^{-10} C H - 1.101000000 10^{-7} C IS & (19) \\
& + 0.44 C
\end{aligned}$$

$$\begin{aligned}
> B2 &:= g(2, 1); \\
B2 &:= -q2 DK H - 4.800000000 10^{-10} C H - 1.800000000 10^{-10} H^2 + 0.17 H & (20)
\end{aligned}$$

$$\begin{aligned}
> B3 &:= g(3, 1); \\
B3 &:= -q3 DK IP - 2.450000000 10^{-12} IP^2 - 6.200000000 10^{-9} IP IS + 0.0245 IP & (21)
\end{aligned}$$

$$\begin{aligned}
> B4 &:= g(4, 1); \\
B4 &:= -q4 DK IS - 3.422000000 10^{-10} C IS + 6.200000000 10^{-9} IP IS - 0.0412 IS & (22)
\end{aligned}$$

$$\begin{aligned}
> B5 &:= g(5, 1); \\
B5 &:= -DK \gamma + \delta I u0 & (23)
\end{aligned}$$

$$\begin{aligned}
> VI &:= gTP.g; \\
VI &:= (-26.1024026539695 q1 DK C - 0.000001125535602 C^2 - 9.44982221 10^{-10} C H & (24) \\
& - 0.000002450635791 C IS + 11.48505717 C + 4.01308764745829 q2 DK H \\
& + 7.223557765 10^{-10} H^2 - 0.6822249000 H + 214.250828184631 q3 DK IP \\
& + 5.249145291 10^{-10} IP^2 - 0.000006339909608 IP IS - 5.249145291 IP \\
& + 1236.81689436281 q4 DK IS + 50.95685603 IS - 1.29796561257463 10^9 DK \gamma \\
& + 1.29796561257463 10^9 \delta I u0) (-q1 DK C - 4.312000000 10^{-8} C^2 \\
& - 1.100000000 10^{-10} C H - 1.101000000 10^{-7} C IS + 0.44 C) \\
& + (4.01308764745829 q1 DK C + 1.730443393 10^{-7} C^2 - 9.703250648 10^{-10} C H \\
& + 4.418409499 10^{-7} C IS - 1.765758565 C - 2.94117647058824 q2 DK H \\
& - 5.294117648 10^{-10} H^2 + 0.5000000001 H) (-q2 DK H - 4.800000000 10^{-10} C H \\
& - 1.800000000 10^{-10} H^2 + 0.17 H) + (214.250828184631 q1 DK C \\
& + 0.000009238495712 C^2 + 2.356759110 10^{-8} C H + 0.00002357682127 C IS \\
& - 94.27036441 C - 92116.1433076938 q3 DK IP - 2.256845511 10^{-7} IP^2 \\
& - 0.0005708991403 IP IS + 2256.845511 IP - 35.6367993722714 q4 DK IS \\
& - 1.468236134 IS - 7.87856003212914 10^{10} DK \gamma + 7.87856003212914 10^{10} \delta I u0) (
\end{aligned}$$



$$\begin{aligned}
& -q3 DK IP - 2.450000000 10^{-12} IP^2 - 6.200000000 10^{-9} IP IS + 0.0245 IP) \\
& + (1236.81689436281 q1 DK C + 0.00005333154447 C^2 + 1.360498583 10^{-7} CH \\
& + 0.00008989224628 C IS - 544.1994334 C - 35.6367993722714 q3 DK IP \\
& - 8.731015846 10^{-11} IP^2 + 0.0008383062904 IP IS + 0.8731015846 IP \\
& - 1.35246328753909 10^5 q4 DK IS - 5572.148747 IS + 1.61945909555493 10^{11} DK \gamma \\
& - 1.61945909555493 10^{11} \delta I u0) (-q4 DK IS - 3.422000000 10^{-10} C IS \\
& + 6.200000000 10^{-9} IP IS - 0.0412 IS) + (-1.29796561257463 10^9 q1 DK C \\
& - 55.96827723 C^2 - 0.1427762174 CH - 87.48812373 C IS + 5.711048697 10^8 C \\
& - 7.87856003212914 10^{10} q3 DK IP - 0.1930247208 IP^2 - 1492.535362 IP IS \\
& + 1.930247208 10^9 IP + 1.61945909555493 10^{11} q4 DK IS + 6.672171476 10^9 IS \\
& - 2.61427740395228 10^{17} DK \gamma + 2.61427740395228 10^{17} \delta I u0) (-DK \gamma + \delta I u0)
\end{aligned}$$



Lampiran 4. Matriks P_I

```
clc; close all;
%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);
gamma2 = 0.02;
s1 = 1*10^(-2);
s2 = 1*10^(-5);
delta2 = 0.0179;
v0 = 0.4;
%EI
EIC = 0;
EIH = (r2-mu1)/(r2*b2);
EIIP = (mu2*gamma2+s2*delta2*v0)/(beta*gamma2);
EIIS = (r3*beta*gamma2-
r3*b3*mu2*gamma2+r3*b3*s2*delta2*v0+beta*s1*delta2*v0)/(((beta)^2
*gamma2);
EIDI = (delta2*v0)/gamma2;
%Nilai JI
ze1 = r1-2*r1*b1*EIC-rho1*EIH-alpha1*EIIS;
ze2 = -rho1*EIC;
ze3 = -alpha1*EIC;
ze4 = -rho2*EIH;
ze5 = r2-2*r2*b2*EIH-mu1-rho2*EIC;
ze6 = r3-2*r3*b3*EIIP-beta*EIIS+s1*EIDI;
ze7 = -beta*EIIP;
ze8 = s1*EIIP;
ze9 = -alpha2*EIIS;
ze10= beta*EIIS;
ze11= beta*EIIP-mu2-alpha2*EIC+s2*EIDI;
ze12= s2*EIIS;
ze13= -gamma2;
%Matriks JI dan JIT
JI = [ze1 ze2 0 ze3 0; ze4 ze5 0 0 0; 0 0 ze6 ze7 ze8; ze9 0 ze10
ze11 ze12; 0 0 0 0 ze13]
JIT = transpose(JI);
%Matriks RI
RI = eye(5);
%Matriks PI by Lyapunov Eq
PI_Ly = lyap(JIT,RI);
PI = expm(PI_Ly,15)
```



Lampiran 5. Penjabaran j_1, j_2, \dots, j_5 pada Analisis Kestabilan Lokal E_K

```

> restart
> with(LinearAlgebra) :
> JI := 
$$\begin{bmatrix} \xi_1 & \xi_2 & 0 & \xi_3 & \xi_4 \\ \xi_5 & \xi_6 & 0 & 0 & \xi_7 \\ 0 & 0 & \xi_8 & \xi_9 & \xi_{10} \\ \xi_{11} & 0 & \xi_{12} & \xi_{13} & \xi_{14} \\ 0 & 0 & 0 & 0 & \xi_{15} \end{bmatrix};$$

> MI := IdentityMatrix(5)
> PI := JI - MI·λ

```

$$PI := \begin{bmatrix} -\lambda + \xi_1 & \xi_2 & 0 & \xi_3 & \xi_4 \\ \xi_5 & -\lambda + \xi_6 & 0 & 0 & \xi_7 \\ 0 & 0 & -\lambda + \xi_8 & \xi_9 & \xi_{10} \\ \xi_{11} & 0 & \xi_{12} & -\lambda + \xi_{13} & \xi_{14} \\ 0 & 0 & 0 & 0 & -\lambda + \xi_{15} \end{bmatrix} \quad (1)$$

```

> CI := CharacteristicPolynomial(PI, λ)
CI := λ5 - (-5 λ + ξ15 + ξ13 + ξ8 + ξ6 + ξ1) λ4 - (-10 λ2 + 4 λ ξ1 + 4 λ ξ13 + 4 λ ξ15
+ 4 λ ξ6 + 4 λ ξ8 - ξ1 ξ13 - ξ1 ξ15 - ξ1 ξ6 - ξ1 ξ8 + ξ11 ξ3 + ξ12 ξ9 - ξ13 ξ15
- ξ13 ξ6 - ξ13 ξ8 - ξ15 ξ6 - ξ15 ξ8 + ξ2 ξ5 - ξ6 ξ8) λ3 - (-10 λ3 + 6 λ2 ξ1 + 6 λ2 ξ13
+ 6 λ2 ξ15 + 6 λ2 ξ6 + 6 λ2 ξ8 - 3 λ ξ1 ξ13 - 3 λ ξ1 ξ15 - 3 λ ξ1 ξ6 - 3 λ ξ1 ξ8
+ 3 λ ξ11 ξ3 + 3 λ ξ12 ξ9 - 3 λ ξ13 ξ15 - 3 λ ξ13 ξ6 - 3 λ ξ13 ξ8 - 3 λ ξ15 ξ6
- 3 λ ξ15 ξ8 + 3 λ ξ2 ξ5 - 3 λ ξ6 ξ8 - ξ1 ξ12 ξ9 + ξ1 ξ13 ξ15 + ξ1 ξ13 ξ6 + ξ1 ξ13 ξ8
+ ξ1 ξ15 ξ6 + ξ1 ξ15 ξ8 + ξ1 ξ6 ξ8 - ξ11 ξ15 ξ3 - ξ11 ξ3 ξ6 - ξ11 ξ3 ξ8 - ξ12 ξ15 ξ9
- ξ12 ξ6 ξ9 + ξ13 ξ15 ξ6 + ξ13 ξ15 ξ8 - ξ13 ξ2 ξ5 + ξ13 ξ6 ξ8 - ξ15 ξ2 ξ5 + ξ15 ξ6 ξ8
- ξ2 ξ5 ξ8) λ2 - (-3 ξ15 λ2 ξ1 - 3 ξ15 λ2 ξ13 - 3 ξ15 λ2 ξ6 - 3 ξ15 λ2 ξ8 + 3 λ2 ξ11 ξ3
+ 3 λ2 ξ12 ξ9 - 3 λ2 ξ1 ξ13 - 3 λ2 ξ1 ξ6 - 3 λ2 ξ1 ξ8 - 3 λ2 ξ13 ξ6 - 3 λ2 ξ13 ξ8
+ 3 λ2 ξ2 ξ5 - 3 λ2 ξ6 ξ8 + 4 ξ15 λ3 + 4 λ3 ξ1 + 4 λ3 ξ13 + 4 λ3 ξ6 + 4 λ3 ξ8
- 2 λ ξ1 ξ12 ξ9 - 2 λ ξ11 ξ3 ξ6 - 2 λ ξ11 ξ3 ξ8 - 2 λ ξ12 ξ6 ξ9 + ξ1 ξ12 ξ6 ξ9
+ ξ11 ξ3 ξ6 ξ8 - ξ12 ξ2 ξ5 ξ9 + 2 λ ξ1 ξ13 ξ6 + 2 λ ξ1 ξ13 ξ8 + 2 λ ξ1 ξ6 ξ8
- 2 λ ξ13 ξ2 ξ5 + 2 λ ξ13 ξ6 ξ8 - 2 λ ξ2 ξ5 ξ8 - ξ1 ξ13 ξ6 ξ8 + ξ13 ξ2 ξ5 ξ8
+ 2 ξ15 λ ξ1 ξ13 + 2 ξ15 λ ξ1 ξ6 + 2 ξ15 λ ξ1 ξ8 - 2 ξ15 λ ξ11 ξ3 λ - 2 ξ15 λ ξ12 ξ9 λ
+ 2 ξ15 λ ξ13 ξ6 + 2 ξ15 λ ξ13 ξ8 - 2 ξ15 λ ξ2 ξ5 + 2 ξ15 λ ξ6 ξ8 + ξ15 ξ1 ξ12 ξ9

```



$$\begin{aligned}
& -\xi_{15} \xi_1 \xi_{13} \xi_6 - \xi_{15} \xi_1 \xi_{13} \xi_8 - \xi_{15} \xi_1 \xi_6 \xi_8 + \xi_{15} \xi_{11} \xi_3 \xi_6 + \xi_{15} \xi_{11} \xi_3 \xi_8 \\
& + \xi_{15} \xi_{12} \xi_6 \xi_9 + \xi_{15} \xi_{13} \xi_2 \xi_5 - \xi_{15} \xi_{13} \xi_6 \xi_8 + \xi_{15} \xi_2 \xi_5 \xi_8 - 5\lambda^4) \lambda + (\lambda - \xi_{15}) (\\
& -\lambda^2 \xi_{11} \xi_3 - \lambda^2 \xi_{12} \xi_9 + \lambda^2 \xi_1 \xi_{13} + \lambda^2 \xi_1 \xi_6 + \lambda^2 \xi_1 \xi_8 + \lambda^2 \xi_{13} \xi_6 + \lambda^2 \xi_{13} \xi_8 \\
& -\lambda^2 \xi_2 \xi_5 + \lambda^2 \xi_6 \xi_8 - \lambda^3 \xi_1 - \lambda^3 \xi_{13} - \lambda^3 \xi_6 - \lambda^3 \xi_8 + \lambda \xi_1 \xi_{12} \xi_9 + \lambda \xi_{11} \xi_3 \xi_6 \\
& + \lambda \xi_{11} \xi_3 \xi_8 + \lambda \xi_{12} \xi_6 \xi_9 - \xi_1 \xi_{12} \xi_6 \xi_9 - \xi_{11} \xi_3 \xi_6 \xi_8 + \xi_{12} \xi_2 \xi_5 \xi_9 - \lambda \xi_1 \xi_{13} \xi_6 \\
& - \lambda \xi_1 \xi_{13} \xi_8 - \lambda \xi_1 \xi_6 \xi_8 + \lambda \xi_{13} \xi_2 \xi_5 - \lambda \xi_{13} \xi_6 \xi_8 + \lambda \xi_2 \xi_5 \xi_8 + \xi_1 \xi_{13} \xi_6 \xi_8 \\
& - \xi_{13} \xi_2 \xi_5 \xi_8 + \lambda^4)
\end{aligned}$$

$$> C11 := \frac{CI}{\text{coeff}(CI, \lambda^5)}$$

$$\begin{aligned}
C11 := & \frac{1}{32} \lambda^5 - \frac{1}{32} (-5\lambda + \xi_{15} + \xi_{13} + \xi_8 + \xi_6 + \xi_1) \lambda^4 - \frac{1}{32} (-10\lambda^2 + 4\lambda \xi_1 \\
& + 4\lambda \xi_{13} + 4\lambda \xi_{15} + 4\lambda \xi_6 + 4\lambda \xi_8 - \xi_1 \xi_{13} - \xi_1 \xi_{15} - \xi_1 \xi_6 - \xi_1 \xi_8 + \xi_{11} \xi_3 \\
& + \xi_{12} \xi_9 - \xi_{13} \xi_{15} - \xi_{13} \xi_6 - \xi_{13} \xi_8 - \xi_{15} \xi_6 - \xi_{15} \xi_8 + \xi_2 \xi_5 - \xi_6 \xi_8) \lambda^3 - \frac{1}{32} (\\
& -10\lambda^3 + 6\lambda^2 \xi_1 + 6\lambda^2 \xi_{13} + 6\lambda^2 \xi_{15} + 6\lambda^2 \xi_6 + 6\lambda^2 \xi_8 - 3\lambda \xi_1 \xi_{13} - 3\lambda \xi_1 \xi_{15} \\
& - 3\lambda \xi_1 \xi_6 - 3\lambda \xi_1 \xi_8 + 3\lambda \xi_{11} \xi_3 + 3\lambda \xi_{12} \xi_9 - 3\lambda \xi_{13} \xi_{15} - 3\lambda \xi_{13} \xi_6 - 3\lambda \xi_{13} \xi_8 \\
& - 3\lambda \xi_{15} \xi_6 - 3\lambda \xi_{15} \xi_8 + 3\lambda \xi_2 \xi_5 - 3\lambda \xi_6 \xi_8 - \xi_1 \xi_{12} \xi_9 + \xi_1 \xi_{13} \xi_{15} + \xi_1 \xi_{13} \xi_6 \\
& + \xi_1 \xi_{13} \xi_8 + \xi_1 \xi_{15} \xi_6 + \xi_1 \xi_{15} \xi_8 + \xi_1 \xi_6 \xi_8 - \xi_{11} \xi_{15} \xi_3 - \xi_{11} \xi_3 \xi_6 - \xi_{11} \xi_3 \xi_8 \\
& - \xi_{12} \xi_{15} \xi_9 - \xi_{12} \xi_6 \xi_9 + \xi_{13} \xi_{15} \xi_6 + \xi_{13} \xi_{15} \xi_8 - \xi_{13} \xi_2 \xi_5 + \xi_{13} \xi_6 \xi_8 - \xi_{15} \xi_2 \xi_5 \\
& + \xi_{15} \xi_6 \xi_8 - \xi_2 \xi_5 \xi_8) \lambda^2 - \frac{1}{32} (-3\xi_{15} \lambda^2 \xi_1 - 3\xi_{15} \lambda^2 \xi_{13} - 3\xi_{15} \lambda^2 \xi_6 \\
& - 3\xi_{15} \lambda^2 \xi_8 + 3\lambda^2 \xi_{11} \xi_3 + 3\lambda^2 \xi_{12} \xi_9 - 3\lambda^2 \xi_1 \xi_{13} - 3\lambda^2 \xi_1 \xi_6 - 3\lambda^2 \xi_1 \xi_8 \\
& - 3\lambda^2 \xi_{13} \xi_6 - 3\lambda^2 \xi_{13} \xi_8 + 3\lambda^2 \xi_2 \xi_5 - 3\lambda^2 \xi_6 \xi_8 + 4\xi_{15} \lambda^3 + 4\lambda^3 \xi_1 + 4\lambda^3 \xi_{13} \\
& + 4\lambda^3 \xi_6 + 4\lambda^3 \xi_8 - 2\lambda \xi_1 \xi_{12} \xi_9 - 2\lambda \xi_{11} \xi_3 \xi_6 - 2\lambda \xi_{11} \xi_3 \xi_8 - 2\lambda \xi_{12} \xi_6 \xi_9 \\
& + \xi_1 \xi_{12} \xi_6 \xi_9 + \xi_{11} \xi_3 \xi_6 \xi_8 - \xi_{12} \xi_2 \xi_5 \xi_9 + 2\lambda \xi_1 \xi_{13} \xi_6 + 2\lambda \xi_1 \xi_{13} \xi_8 \\
& + 2\lambda \xi_1 \xi_6 \xi_8 - 2\lambda \xi_{13} \xi_2 \xi_5 + 2\lambda \xi_{13} \xi_6 \xi_8 - 2\lambda \xi_2 \xi_5 \xi_8 - \xi_1 \xi_{13} \xi_6 \xi_8 \\
& + \xi_{13} \xi_2 \xi_5 \xi_8 + 2\xi_{15} \lambda \xi_1 \xi_{13} + 2\xi_{15} \lambda \xi_1 \xi_6 + 2\xi_{15} \lambda \xi_1 \xi_8 - 2\xi_{15} \xi_{11} \xi_3 \lambda \\
& - 2\xi_{15} \xi_{12} \xi_9 \lambda + 2\xi_{15} \lambda \xi_{13} \xi_6 + 2\xi_{15} \lambda \xi_{13} \xi_8 - 2\xi_{15} \lambda \xi_2 \xi_5 + 2\xi_{15} \lambda \xi_6 \xi_8 \\
& + \xi_{15} \xi_1 \xi_{12} \xi_9 - \xi_{15} \xi_1 \xi_{13} \xi_6 - \xi_{15} \xi_1 \xi_{13} \xi_8 - \xi_{15} \xi_1 \xi_6 \xi_8 + \xi_{15} \xi_{11} \xi_3 \xi_6 \\
& + \xi_{15} \xi_{11} \xi_3 \xi_8 + \xi_{15} \xi_{12} \xi_6 \xi_9 + \xi_{15} \xi_{13} \xi_2 \xi_5 - \xi_{15} \xi_{13} \xi_6 \xi_8 + \xi_{15} \xi_2 \xi_5 \xi_8 - 5\lambda^4) \lambda \\
& + \frac{1}{32} (\lambda - \xi_{15}) (-\lambda^2 \xi_{11} \xi_3 - \lambda^2 \xi_{12} \xi_9 + \lambda^2 \xi_1 \xi_{13} + \lambda^2 \xi_1 \xi_6 + \lambda^2 \xi_1 \xi_8 + \lambda^2 \xi_{13} \xi_6 \\
& + \lambda^2 \xi_{13} \xi_8 - \lambda^2 \xi_2 \xi_5 + \lambda^2 \xi_6 \xi_8 - \lambda^3 \xi_1 - \lambda^3 \xi_{13} - \lambda^3 \xi_6 - \lambda^3 \xi_8 + \lambda \xi_1 \xi_{12} \xi_9
\end{aligned}$$



$$\begin{aligned}
& + \lambda \xi_{11} \xi_3 \xi_6 + \lambda \xi_{11} \xi_3 \xi_8 + \lambda \xi_{12} \xi_6 \xi_9 - \xi_1 \xi_{12} \xi_6 \xi_9 - \xi_{11} \xi_3 \xi_6 \xi_8 + \xi_{12} \xi_2 \xi_5 \xi_9 \\
& - \lambda \xi_1 \xi_{13} \xi_6 - \lambda \xi_1 \xi_{13} \xi_8 - \lambda \xi_1 \xi_6 \xi_8 + \lambda \xi_{13} \xi_2 \xi_5 - \lambda \xi_{13} \xi_6 \xi_8 + \lambda \xi_2 \xi_5 \xi_8 \\
& + \xi_1 \xi_{13} \xi_6 \xi_8 - \xi_{13} \xi_2 \xi_5 \xi_8 + \lambda^4)
\end{aligned}$$

$$\begin{aligned}
> j0 := \text{coeff}(C11, \lambda, 5) & & j0 := 1 & \quad (4)
\end{aligned}$$

$$\begin{aligned}
> j1 := \text{coeff}(C11, \lambda, 4) & & j1 := -\frac{1}{2} \xi_{13} - \frac{1}{2} \xi_{15} - \frac{1}{2} \xi_6 - \frac{1}{2} \xi_8 - \frac{1}{2} \xi_1 & \quad (5)
\end{aligned}$$

$$\begin{aligned}
> j2 := \text{coeff}(C11, \lambda, 3) & & j2 := \frac{7}{32} \xi_{15} \xi_{13} + \frac{7}{32} \xi_{15} \xi_8 + \frac{7}{32} \xi_{15} \xi_6 + \frac{7}{32} \xi_{15} \xi_1 - \frac{1}{32} \xi_{15} (-\xi_1 - \xi_{13} - \xi_6 \\
& - \xi_8) + \frac{1}{4} \xi_{13} \xi_8 + \frac{1}{4} \xi_{13} \xi_6 + \frac{1}{4} \xi_{13} \xi_1 - \frac{1}{4} \xi_5 \xi_2 + \frac{1}{4} \xi_6 \xi_1 + \frac{1}{4} \xi_8 \xi_6 \\
& + \frac{1}{4} \xi_8 \xi_1 - \frac{1}{4} \xi_{11} \xi_3 - \frac{1}{4} \xi_{12} \xi_9 & \quad (6)
\end{aligned}$$

$$\begin{aligned}
> j3 := \text{coeff}(C11, \lambda, 2) & & j3 := -\frac{3}{32} \xi_{15} \xi_1 \xi_{13} - \frac{3}{32} \xi_{15} \xi_{13} \xi_8 + \frac{3}{32} \xi_{15} \xi_{11} \xi_3 - \frac{3}{32} \xi_{15} \xi_{13} \xi_6 - \frac{3}{32} \xi_{15} \xi_6 \xi_8 & \quad (7) \\
& + \frac{3}{32} \xi_{15} \xi_2 \xi_5 + \frac{3}{32} \xi_{15} \xi_{12} \xi_9 - \frac{3}{32} \xi_{15} \xi_1 \xi_6 - \frac{3}{32} \xi_{15} \xi_1 \xi_8 + \frac{1}{8} \xi_1 \xi_{12} \xi_9 \\
& - \frac{1}{8} \xi_1 \xi_{13} \xi_6 - \frac{1}{8} \xi_1 \xi_{13} \xi_8 - \frac{1}{8} \xi_1 \xi_6 \xi_8 + \frac{1}{8} \xi_{11} \xi_3 \xi_6 + \frac{1}{8} \xi_{11} \xi_3 \xi_8 \\
& + \frac{1}{8} \xi_{12} \xi_6 \xi_9 + \frac{1}{8} \xi_{13} \xi_2 \xi_5 - \frac{1}{8} \xi_{13} \xi_6 \xi_8 + \frac{1}{8} \xi_2 \xi_5 \xi_8 - \frac{1}{32} \xi_{15} (\xi_1 \xi_{13} + \xi_1 \xi_6 \\
& + \xi_1 \xi_8 - \xi_{11} \xi_3 - \xi_{12} \xi_9 + \xi_{13} \xi_6 + \xi_{13} \xi_8 - \xi_2 \xi_5 + \xi_6 \xi_8)
\end{aligned}$$

$$\begin{aligned}
> j4 := \text{coeff}(C11, \lambda, 1) & & j4 := -\frac{1}{32} \xi_{15} \xi_1 \xi_{12} \xi_9 - \frac{1}{16} \xi_1 \xi_{12} \xi_6 \xi_9 + \frac{1}{32} \xi_{15} \xi_1 \xi_{13} \xi_6 + \frac{1}{32} \xi_{15} \xi_1 \xi_{13} \xi_8 & \quad (8) \\
& + \frac{1}{16} \xi_1 \xi_{13} \xi_6 \xi_8 + \frac{1}{32} \xi_{15} \xi_1 \xi_6 \xi_8 - \frac{1}{32} \xi_{15} \xi_{11} \xi_3 \xi_6 - \frac{1}{32} \xi_{15} \xi_{11} \xi_3 \xi_8 \\
& - \frac{1}{16} \xi_{11} \xi_3 \xi_6 \xi_8 - \frac{1}{32} \xi_{15} \xi_{12} \xi_6 \xi_9 + \frac{1}{16} \xi_{12} \xi_2 \xi_5 \xi_9 - \frac{1}{32} \xi_{15} \xi_{13} \xi_2 \xi_5 \\
& + \frac{1}{32} \xi_{15} \xi_{13} \xi_6 \xi_8 - \frac{1}{16} \xi_{13} \xi_2 \xi_5 \xi_8 - \frac{1}{32} \xi_{15} \xi_2 \xi_5 \xi_8 - \frac{1}{32} \xi_{15} (\xi_1 \xi_{12} \xi_9 \\
& - \xi_1 \xi_{13} \xi_6 - \xi_1 \xi_{13} \xi_8 - \xi_1 \xi_6 \xi_8 + \xi_{11} \xi_3 \xi_6 + \xi_{11} \xi_3 \xi_8 + \xi_{12} \xi_6 \xi_9 + \xi_{13} \xi_2 \xi_5 \\
& - \xi_{13} \xi_6 \xi_8 + \xi_2 \xi_5 \xi_8)
\end{aligned}$$

$$\begin{aligned}
> j5 := \text{coeff}(C11, \lambda, 0) & & j5 := -\frac{1}{32} \xi_{15} (-\xi_1 \xi_{12} \xi_6 \xi_9 + \xi_1 \xi_{13} \xi_6 \xi_8 - \xi_{11} \xi_3 \xi_6 \xi_8 + \xi_{12} \xi_2 \xi_5 \xi_9 - \xi_{13} \xi_2 \xi_5 \xi_8) & \quad (9)
\end{aligned}$$



Lampiran 6. Penjabaran k_1, k_2, \dots, k_5 pada Analisis Kestabilan Lokal E_I

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> restart
> with(LinearAlgebra) :
> J2 := 
$$\begin{bmatrix} \zeta_1 & \zeta_2 & 0 & \zeta_3 & 0 \\ \zeta_4 & \zeta_5 & 0 & 0 & 0 \\ 0 & 0 & \zeta_6 & \zeta_7 & \zeta_8 \\ \zeta_9 & 0 & \zeta_{10} & \zeta_{11} & \zeta_{12} \\ 0 & 0 & 0 & 0 & \zeta_{13} \end{bmatrix};$$

> M2 := IdentityMatrix(5)
> P2 := J2 - M2*\lambda

```

$$P2 := \begin{bmatrix} -\lambda + \zeta_1 & \zeta_2 & 0 & \zeta_3 & 0 \\ \zeta_4 & -\lambda + \zeta_5 & 0 & 0 & 0 \\ 0 & 0 & -\lambda + \zeta_6 & \zeta_7 & \zeta_8 \\ \zeta_9 & 0 & \zeta_{10} & -\lambda + \zeta_{11} & \zeta_{12} \\ 0 & 0 & 0 & 0 & -\lambda + \zeta_{13} \end{bmatrix} \quad (1)$$

```

> C2 := CharacteristicPolynomial(P2, \lambda)
C2 := \lambda^5 - (-5\lambda + \zeta_{13} + \zeta_{11} + \zeta_6 + \zeta_5 + \zeta_1) \lambda^4 - (-\zeta_1 \zeta_{11} - \zeta_1 \zeta_{13} - \zeta_1 \zeta_5 - \zeta_1 \zeta_6
+ 4 \zeta_1 \lambda + \zeta_{10} \zeta_7 - \zeta_{11} \zeta_{13} - \zeta_{11} \zeta_5 - \zeta_{11} \zeta_6 + 4 \zeta_{11} \lambda - \zeta_{13} \zeta_5 - \zeta_{13} \zeta_6 + 4 \zeta_{13} \lambda
+ \zeta_2 \zeta_4 + \zeta_3 \zeta_9 - \zeta_5 \zeta_6 + 4 \zeta_5 \lambda + 4 \zeta_6 \lambda - 10 \lambda^2) \lambda^3 - (-\zeta_1 \zeta_{10} \zeta_7 + \zeta_1 \zeta_{11} \zeta_{13}
+ \zeta_1 \zeta_{11} \zeta_5 + \zeta_1 \zeta_{11} \zeta_6 - 3 \zeta_1 \zeta_{11} \lambda + \zeta_1 \zeta_{13} \zeta_5 + \zeta_1 \zeta_{13} \zeta_6 - 3 \zeta_1 \zeta_{13} \lambda + \zeta_1 \zeta_5 \zeta_6
- 3 \zeta_1 \zeta_5 \lambda - 3 \zeta_1 \zeta_6 \lambda + 6 \zeta_1 \lambda^2 - \zeta_{10} \zeta_{13} \zeta_7 - \zeta_{10} \zeta_5 \zeta_7 + 3 \zeta_{10} \zeta_7 \lambda + \zeta_{11} \zeta_{13} \zeta_5
+ \zeta_{11} \zeta_{13} \zeta_6 - 3 \zeta_{11} \zeta_{13} \lambda - \zeta_{11} \zeta_2 \zeta_4 + \zeta_{11} \zeta_5 \zeta_6 - 3 \zeta_{11} \zeta_5 \lambda - 3 \zeta_{11} \zeta_6 \lambda + 6 \zeta_{11} \lambda^2
- \zeta_{13} \zeta_2 \zeta_4 - \zeta_{13} \zeta_5 \zeta_6 + \zeta_{13} \zeta_5 \zeta_6 - 3 \zeta_{13} \zeta_5 \lambda - 3 \zeta_{13} \zeta_6 \lambda + 6 \zeta_{13} \lambda^2 - \zeta_2 \zeta_4 \zeta_6
+ 3 \zeta_2 \zeta_4 \lambda - \zeta_3 \zeta_5 \zeta_9 - \zeta_3 \zeta_6 \zeta_9 + 3 \zeta_3 \zeta_9 \lambda - 3 \zeta_5 \zeta_6 \lambda + 6 \zeta_5 \lambda^2 + 6 \zeta_6 \lambda^2 - 10 \lambda^3) \lambda^2
- (\zeta_1 \zeta_{10} \zeta_5 \zeta_7 - 2 \zeta_1 \zeta_{10} \zeta_7 \lambda - \zeta_{10} \zeta_2 \zeta_4 \zeta_7 - 2 \zeta_{10} \zeta_5 \zeta_7 \lambda + \zeta_3 \zeta_5 \zeta_6 \zeta_9
- 2 \zeta_3 \zeta_5 \zeta_9 \lambda - 2 \zeta_3 \zeta_6 \zeta_9 \lambda - \zeta_1 \zeta_{11} \zeta_5 \zeta_6 + 2 \zeta_1 \zeta_{11} \zeta_5 \lambda + 2 \zeta_1 \zeta_{11} \zeta_6 \lambda + 2 \zeta_1 \zeta_5 \zeta_6 \lambda
+ \zeta_{11} \zeta_2 \zeta_4 \zeta_6 - 2 \zeta_{11} \zeta_2 \zeta_4 \lambda + 2 \zeta_{11} \zeta_5 \zeta_6 \lambda - 2 \zeta_2 \zeta_4 \zeta_6 \lambda + \zeta_{13} \zeta_1 \zeta_{10} \zeta_7
- \zeta_{13} \zeta_1 \zeta_{11} \zeta_5 - \zeta_{13} \zeta_1 \zeta_{11} \zeta_6 + 2 \zeta_{13} \zeta_1 \zeta_{11} \lambda - \zeta_{13} \zeta_1 \zeta_5 \zeta_6 + 2 \zeta_{13} \zeta_1 \zeta_5 \lambda
+ 2 \zeta_{13} \zeta_1 \zeta_6 \lambda + \zeta_{13} \zeta_{10} \zeta_5 \zeta_7 - 2 \zeta_{13} \zeta_{10} \zeta_7 \lambda + \zeta_{13} \zeta_{11} \zeta_2 \zeta_4 - \zeta_{13} \zeta_{11} \zeta_5 \zeta_6
+ 2 \zeta_{13} \zeta_{11} \zeta_5 \lambda + 2 \zeta_{13} \zeta_{11} \zeta_6 \lambda + \zeta_{13} \zeta_2 \zeta_4 \zeta_6 - 2 \zeta_{13} \zeta_2 \zeta_4 \lambda + \zeta_{13} \zeta_3 \zeta_5 \zeta_9
+ \zeta_{13} \zeta_3 \zeta_6 \zeta_9 - 2 \zeta_{13} \zeta_3 \zeta_9 \lambda + 2 \zeta_{13} \zeta_5 \zeta_6 \lambda + 4 \zeta_{13} \lambda^3 + 4 \zeta_1 \lambda^3 + 4 \zeta_{11} \lambda^3 + 4 \zeta_5 \lambda^3
+ 4 \zeta_6 \lambda^3 - 5 \lambda^4 + 3 \zeta_{10} \zeta_7 \lambda^2 + 3 \zeta_3 \zeta_9 \lambda^2 - 3 \zeta_1 \zeta_{11} \lambda^2 - 3 \zeta_1 \zeta_5 \lambda^2 - 3 \zeta_1 \zeta_6 \lambda^2

```



$$\begin{aligned}
& -3 \zeta_{11} \zeta \lambda^2 - 3 \zeta_{11} \zeta_6 \lambda^2 + 3 \varphi \zeta_1 \lambda^2 - 3 \zeta \zeta_6 \lambda^2 - 3 \zeta_{13} \zeta_1 \lambda^2 - 3 \zeta_{13} \zeta_{11} \lambda^2 \\
& - 3 \zeta_{13} \zeta \lambda^2 - 3 \zeta_{13} \zeta_6 \lambda^2) \lambda + (-\lambda + \zeta_{13}) (\zeta_1 \zeta_{10} \zeta \zeta - \zeta_1 \zeta_{10} \zeta_7 \lambda - \zeta_{10} \varphi \zeta_4 \zeta \\
& - \zeta_{10} \zeta \zeta_7 \lambda + \zeta \zeta \zeta_6 \varphi - \zeta \zeta \zeta_7 \lambda - \zeta \zeta_6 \zeta_7 \lambda - \zeta_1 \zeta_{11} \zeta \zeta_6 + \zeta_1 \zeta_{11} \zeta \lambda \\
& + \zeta_1 \zeta_{11} \zeta_6 \lambda + \zeta_1 \zeta \zeta_6 \lambda + \zeta_{11} \varphi \zeta_4 \zeta_6 - \zeta_{11} \varphi \zeta_4 \lambda + \zeta_{11} \zeta \zeta_6 \lambda - \varphi \zeta_4 \zeta_6 \lambda + \zeta_1 \lambda^3 \\
& + \zeta_{11} \lambda^3 + \zeta \lambda^3 + \zeta_6 \lambda^3 - \lambda^4 + \zeta_{10} \zeta_7 \lambda^2 + \zeta \zeta_7 \lambda^2 - \zeta_1 \zeta_{11} \lambda^2 - \zeta_1 \zeta \lambda^2 - \zeta_1 \zeta_6 \lambda^2 \\
& - \zeta_{11} \zeta \lambda^2 - \zeta_{11} \zeta_6 \lambda^2 + \varphi \zeta_4 \lambda^2 - \zeta \zeta_6 \lambda^2)
\end{aligned}$$

$$\begin{aligned}
> C22 &:= \frac{C2}{\text{coeff}(C2, \lambda^5)} \\
C22 &:= \frac{1}{32} \lambda^5 - \frac{1}{32} (-5\lambda + \zeta_{13} + \zeta_{11} + \zeta_6 + \zeta + \zeta_1) \lambda^4 - \frac{1}{32} (-\zeta_1 \zeta_{11} - \zeta_1 \zeta_{13} \\
& - \zeta_1 \zeta - \zeta_1 \zeta_6 + 4 \zeta_1 \lambda + \zeta_{10} \zeta - \zeta_{11} \zeta_{13} - \zeta_{11} \zeta - \zeta_{11} \zeta_6 + 4 \zeta_{11} \lambda - \zeta_{13} \zeta \\
& - \zeta_{13} \zeta_6 + 4 \zeta_{13} \lambda + \varphi \zeta_4 + \zeta \zeta_7 - \zeta \zeta_6 + 4 \zeta \lambda + 4 \zeta_6 \lambda - 10 \lambda^2) \lambda^3 - \frac{1}{32} (\\
& - \zeta_1 \zeta_{10} \zeta + \zeta_1 \zeta_{11} \zeta_{13} + \zeta_1 \zeta_{11} \zeta + \zeta_1 \zeta_{11} \zeta_6 - 3 \zeta_1 \zeta_{11} \lambda + \zeta_1 \zeta_{13} \zeta + \zeta_1 \zeta_{13} \zeta_6 \\
& - 3 \zeta_1 \zeta_{13} \lambda + \zeta_1 \zeta \zeta_6 - 3 \zeta_1 \zeta \lambda - 3 \zeta_1 \zeta_6 \lambda + 6 \zeta_1 \lambda^2 - \zeta_{10} \zeta_{13} \zeta - \zeta_{10} \zeta \zeta_7 \\
& + 3 \zeta_{10} \zeta_7 \lambda + \zeta_{11} \zeta_{13} \zeta + \zeta_{11} \zeta_{13} \zeta_6 - 3 \zeta_{11} \zeta_{13} \lambda - \zeta_{11} \varphi \zeta_4 + \zeta_{11} \zeta \zeta_6 \\
& - 3 \zeta_{11} \zeta \lambda - 3 \zeta_{11} \zeta_6 \lambda + 6 \zeta_{11} \lambda^2 - \zeta_{13} \varphi \zeta_4 - \zeta_{13} \zeta \zeta_7 + \zeta_{13} \zeta \zeta_6 - 3 \zeta_{13} \zeta \lambda \\
& - 3 \zeta_{13} \zeta_6 \lambda + 6 \zeta_{13} \lambda^2 - \varphi \zeta_4 \zeta_6 + 3 \varphi \zeta_4 \lambda - \zeta \zeta \zeta_7 - \zeta \zeta_6 \zeta_7 + 3 \zeta \zeta_7 \lambda \\
& - 3 \zeta \zeta_6 \lambda + 6 \zeta \lambda^2 + 6 \zeta_6 \lambda^2 - 10 \lambda^3) \lambda^2 - \frac{1}{32} (\zeta_1 \zeta_{10} \zeta \zeta - 2 \zeta_1 \zeta_{10} \zeta_7 \lambda \\
& - \zeta_{10} \varphi \zeta_4 \zeta - 2 \zeta_{10} \zeta \zeta_7 \lambda + \zeta \zeta \zeta_6 \varphi - 2 \zeta \zeta \zeta_7 \lambda - 2 \zeta \zeta_6 \zeta_7 \lambda - \zeta_1 \zeta_{11} \zeta \zeta_6 \\
& + 2 \zeta_1 \zeta_{11} \zeta \lambda + 2 \zeta_1 \zeta_{11} \zeta_6 \lambda + 2 \zeta_1 \zeta \zeta_6 \lambda + \zeta_{11} \varphi \zeta_4 \zeta_6 - 2 \zeta_{11} \varphi \zeta_4 \lambda \\
& + 2 \zeta_{11} \zeta \zeta_6 \lambda - 2 \varphi \zeta_4 \zeta_6 \lambda + \zeta_{13} \zeta_1 \zeta_{10} \zeta - \zeta_{13} \zeta_1 \zeta_{11} \zeta - \zeta_{13} \zeta_1 \zeta_{11} \zeta_6 \\
& + 2 \zeta_{13} \zeta_1 \zeta_{11} \lambda - \zeta_{13} \zeta_1 \zeta \zeta_6 + 2 \zeta_{13} \zeta_1 \zeta \lambda + 2 \zeta_{13} \zeta_1 \zeta_6 \lambda + \zeta_{13} \zeta_{10} \zeta \zeta_7 \\
& - 2 \zeta_{13} \zeta_{10} \zeta_7 \lambda + \zeta_{13} \zeta_{11} \varphi \zeta_4 - \zeta_{13} \zeta_{11} \zeta \zeta_6 + 2 \zeta_{13} \zeta_{11} \zeta \lambda + 2 \zeta_{13} \zeta_{11} \zeta_6 \lambda \\
& + \zeta_{13} \varphi \zeta_4 \zeta_6 - 2 \zeta_{13} \varphi \zeta_4 \lambda + \zeta_{13} \zeta \zeta \zeta_7 + \zeta_{13} \zeta \zeta_6 \varphi - 2 \zeta_{13} \zeta_7 \zeta \lambda \\
& + 2 \zeta_{13} \zeta \zeta_6 \lambda + 4 \zeta_{13} \lambda^3 + 4 \zeta_1 \lambda^3 + 4 \zeta_{11} \lambda^3 + 4 \zeta \lambda^3 + 4 \zeta_6 \lambda^3 - 5 \lambda^4 + 3 \zeta_{10} \zeta_7 \lambda^2 \\
& + 3 \zeta \zeta_7 \lambda^2 - 3 \zeta_1 \zeta_{11} \lambda^2 - 3 \zeta_1 \zeta \lambda^2 - 3 \zeta_1 \zeta_6 \lambda^2 - 3 \zeta_{11} \zeta \lambda^2 - 3 \zeta_{11} \zeta_6 \lambda^2 \\
& + 3 \varphi \zeta_4 \lambda^2 - 3 \zeta \zeta_6 \lambda^2 - 3 \zeta_{13} \zeta_1 \lambda^2 - 3 \zeta_{13} \zeta_{11} \lambda^2 - 3 \zeta_{13} \zeta \lambda^2 - 3 \zeta_{13} \zeta_6 \lambda^2) \lambda \\
& + \frac{1}{32} (-\lambda + \zeta_{13}) (\zeta_1 \zeta_{10} \zeta \zeta - \zeta_1 \zeta_{10} \zeta_7 \lambda - \zeta_{10} \varphi \zeta_4 \zeta - \zeta_{10} \zeta \zeta_7 \lambda \\
& + \zeta \zeta \zeta_6 \varphi - \zeta \zeta \zeta_7 \lambda - \zeta \zeta_6 \zeta_7 \lambda - \zeta_1 \zeta_{11} \zeta \zeta_6 + \zeta_1 \zeta_{11} \zeta \lambda + \zeta_1 \zeta_{11} \zeta_6 \lambda \\
& + \zeta_1 \zeta \zeta_6 \lambda + \zeta_{11} \varphi \zeta_4 \zeta_6 - \zeta_{11} \varphi \zeta_4 \lambda + \zeta_{11} \zeta \zeta_6 \lambda - \varphi \zeta_4 \zeta_6 \lambda + \zeta_1 \lambda^3 + \zeta_{11} \lambda^3
\end{aligned}$$



$$+ \zeta \lambda^3 + \zeta_6 \lambda^3 - \lambda^4 + \zeta_{10} \vartheta \lambda^2 + \zeta_3 \vartheta \lambda^2 - \zeta_1 \zeta_{11} \lambda^2 - \zeta_1 \zeta \lambda^2 - \zeta_1 \zeta_6 \lambda^2 - \zeta_{11} \zeta \lambda^2 - \zeta_{11} \zeta_6 \lambda^2 + \vartheta \zeta_4 \lambda^2 - \zeta \zeta_6 \lambda^2)$$

$$\begin{aligned} > k0 := \text{coeff}(C22, \lambda, 5) & & k0 := 1 & (4) \end{aligned}$$

$$\begin{aligned} > k1 := \text{coeff}(C22, \lambda, 4) & & k1 := -\frac{1}{2} \zeta_1 - \frac{1}{2} \zeta - \frac{1}{2} \zeta_6 - \frac{1}{2} \zeta_{11} - \frac{1}{2} \zeta_{13} & (5) \end{aligned}$$

$$\begin{aligned} > k2 := \text{coeff}(C22, \lambda, 3) & & k2 := -\frac{1}{4} \zeta_{10} \vartheta - \frac{1}{4} \zeta_3 \vartheta + \frac{1}{4} \zeta_1 \zeta_{11} + \frac{1}{4} \zeta_1 \zeta + \frac{1}{4} \zeta_1 \zeta_6 + \frac{1}{4} \zeta_{11} \zeta + \frac{1}{4} \zeta_{11} \zeta_6 & (6) \\ & & -\frac{1}{4} \vartheta \zeta_4 + \frac{1}{4} \zeta_5 \zeta_6 + \frac{7}{32} \zeta_{13} \zeta_1 + \frac{7}{32} \zeta_{13} \zeta_{11} + \frac{7}{32} \zeta_{13} \zeta + \frac{7}{32} \zeta_{13} \zeta_6 & \\ & & + \frac{1}{32} \zeta_{13} (\zeta_1 + \zeta_{11} + \zeta + \zeta_6) & \end{aligned}$$

$$\begin{aligned} > k3 := \text{coeff}(C22, \lambda, 2) & & k3 := -\frac{1}{8} \zeta_1 \zeta_{11} \zeta - \frac{3}{32} \zeta_{13} \zeta_5 \zeta_6 - \frac{1}{8} \zeta_1 \zeta_5 \zeta_6 + \frac{3}{32} \zeta_{13} \zeta_{10} \vartheta + \frac{1}{8} \zeta_3 \zeta_6 \vartheta & (7) \\ & & -\frac{3}{32} \zeta_{13} \zeta_{11} \zeta_6 + \frac{3}{32} \zeta_{13} \vartheta \zeta_3 + \frac{1}{8} \zeta_3 \zeta_5 \vartheta + \frac{1}{8} \zeta_{11} \vartheta \zeta_4 - \frac{1}{8} \zeta_{11} \zeta_5 \zeta_6 & \\ & & -\frac{3}{32} \zeta_{13} \zeta_1 \zeta_6 - \frac{3}{32} \zeta_{13} \zeta_{11} \zeta + \frac{1}{8} \zeta_1 \zeta_{10} \vartheta + \frac{1}{8} \zeta_{10} \zeta_5 \vartheta + \frac{1}{8} \vartheta \zeta_4 \zeta_6 & \\ & & -\frac{3}{32} \zeta_{13} \zeta_1 \zeta_5 + \frac{3}{32} \zeta_{13} \vartheta \zeta_4 - \frac{1}{8} \zeta_1 \zeta_{11} \zeta_6 - \frac{3}{32} \zeta_{13} \zeta_1 \zeta_{11} + \frac{1}{32} \zeta_{13} (-\zeta_1 \zeta_{11} & \\ & & -\zeta_1 \zeta_5 - \zeta_1 \zeta_6 + \zeta_{10} \vartheta - \zeta_{11} \zeta_5 - \zeta_{11} \zeta_6 + \vartheta \zeta_4 + \zeta_3 \vartheta - \zeta_5 \zeta_6) & \end{aligned}$$

$$\begin{aligned} > k4 := \text{coeff}(C22, \lambda, 1) & & k4 := -\frac{1}{32} \zeta_{13} \zeta_1 \zeta_{10} \vartheta - \frac{1}{16} \zeta_1 \zeta_{10} \zeta_5 \vartheta + \frac{1}{32} \zeta_{13} \zeta_1 \zeta_{11} \zeta + \frac{1}{32} \zeta_{13} \zeta_1 \zeta_{11} \zeta_6 & (8) \\ & & + \frac{1}{16} \zeta_1 \zeta_{11} \zeta_5 \zeta_6 + \frac{1}{32} \zeta_{13} \zeta_1 \zeta_5 \zeta_6 - \frac{1}{32} \zeta_{13} \zeta_{10} \zeta_5 \vartheta + \frac{1}{16} \zeta_{10} \vartheta \zeta_4 \vartheta & \\ & & -\frac{1}{32} \zeta_{13} \zeta_{11} \vartheta \zeta_4 + \frac{1}{32} \zeta_{13} \zeta_{11} \zeta_5 \zeta_6 - \frac{1}{16} \zeta_{11} \vartheta \zeta_4 \zeta_6 - \frac{1}{32} \zeta_{13} \vartheta \zeta_4 \zeta_6 & \\ & & -\frac{1}{32} \zeta_{13} \zeta_3 \zeta_5 \vartheta - \frac{1}{32} \zeta_{13} \zeta_3 \zeta_6 \vartheta - \frac{1}{16} \zeta_3 \zeta_5 \zeta_6 \vartheta + \frac{1}{32} \zeta_{13} (-\zeta_1 \zeta_{10} \vartheta & \\ & & + \zeta_1 \zeta_{11} \zeta_5 + \zeta_1 \zeta_{11} \zeta_6 + \zeta_1 \zeta_5 \zeta_6 - \zeta_{10} \zeta_5 \vartheta - \zeta_{11} \vartheta \zeta_4 + \zeta_{11} \zeta_5 \zeta_6 - \vartheta \zeta_4 \zeta_6 & \\ & & -\zeta_3 \zeta_5 \vartheta - \zeta_3 \zeta_6 \vartheta) & \end{aligned}$$

$$\begin{aligned} > k5 := \text{coeff}(C22, \lambda, 0) & & k5 := \frac{1}{32} \zeta_{13} (\zeta_1 \zeta_{10} \zeta_5 \vartheta - \zeta_1 \zeta_{11} \zeta_5 \zeta_6 - \zeta_{10} \vartheta \zeta_4 \vartheta + \zeta_{11} \vartheta \zeta_4 \zeta_6 + \zeta_3 \zeta_5 \zeta_6 \vartheta) & (9) \end{aligned}$$



Lampiran 7. Simulasi Numerik untuk Sistem Tanpa Terapi

```

function dy = F_TanpaTerapi (t,y)
clc; close all;

%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);

%Sistem Tanpa Terapi
dy = zeros(4,1);

dy(1)= r1*y(1)-r1*b1*y(1)*y(1)-rho1*y(2)*y(1)-alpha1*y(4)*y(1);
dy(2)= r2*y(2)-r2*b2*y(2)*y(2)-mu1*y(2)-rho2*y(1)*y(2);
dy(3)= r3*y(3)-r3*b3*y(3)*y(3)-beta*y(4)*y(3);
dy(4)= beta*y(3)*y(4)-mu2*y(4)-alpha2*y(1)*y(4);
end

%SIMULASI NUMERIK:
%Tanpa Pengaruh Terapi
clc; clear all;
timel = linspace(0,350);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History1 = [ na1; na2; na3; na4 ];

%-----TANPA TERAPI-----
sol0 = ode23s(@F_TanpaTerapi, timel, History1);
S1 = sol0.x'; X1 = sol0.y';
S2 = sol0.x'; X2 = sol0.y';
S3 = sol0.x'; X3 = sol0.y';
S4 = sol0.x'; X4 = sol0.y';
P1 = spline (S1, X1(:,1),timel);
P2 = spline (S2, X2(:,2),timel);
P3 = spline (S3, X3(:,3),timel);
P4 = spline (S4, X4(:,4),timel);

```

```

(321)
timel, P1, 'black', 'LineWidth', 1.5)
'Waktu (Hari)', 'FontSize', 12)

```



```
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, P2, 'black', 'LineWidth', 1.5)
hold on
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, P3, 'black', 'LineWidth', 1.5)
hold on
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, P4, 'black', 'LineWidth', 1.5)
hold on
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');
```



Lampiran 8. Simulasi Numerik untuk Sistem Kemoterapi Konstan

```

function dy = F_Kemo_Konstan (t,y)
clc; close all;

%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);
gamma1 = 0.01;
q1 = 0.9;
q2 = 1*10^(-12);
q3 = 1*10^(-5);
q4 = 2*10^(-11);
delta1 = 0.0357;
u0 = 0.5;

%Sistem Kemoterapi Konstan
dy = zeros(5,1);

dy(1)= r1*y(1)-r1*b1*y(1)*y(1)-rho1*y(2)*y(1)-alpha1*y(4)*y(1)-
q1*y(5)*y(1);
dy(2)= r2*y(2)-r2*b2*y(2)*y(2)-mu1*y(2)-rho2*y(1)*y(2)-
q2*y(5)*y(2);
dy(3)= r3*y(3)-r3*b3*y(3)*y(3)-beta*y(4)*y(3)-q3*y(5)*y(3);
dy(4)= beta*y(3)*y(4)-mu2*y(4)-alpha2*y(1)*y(4)-q4*y(5)*y(4);
dy(5)= delta1*u0-gamma1*y(5);
end

%SIMULASI NUMERIK:
%Pengaruh Pemberian Kemoterapi secara Konstan
clc; clear all;
time1 = linspace(0,350);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History2 = [ na1; na2; na3; na4; na5 ];

%-----KEMOTERAPI KONSTAN-----
ode23s(@F_Kemo_Konstan, time1, History2);
l1.x'; Y1 = sol1.y';
l1.x'; Y2 = sol1.y';
l1.x'; Y3 = sol1.y';
l1.x'; Y4 = sol1.y';

```



```

T5 = sol1.x'; Y5 = sol1.y';
Q1 = spline (T1, Y1(:,1),time1);
Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%Plot
subplot (321)
plot (time1, Q1, 'red', 'LineWidth', 1.5);
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2, 'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3, 'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4, 'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');

subplot (325)
plot (time1, Q5, 'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('DK (mg/L)', 'FontSize', 12)
title ('(e)');

```



Lampiran 9. Simulasi Numerik untuk Sistem Kemoterapi Periodik

```

function dy = F_Kemo_Periodik (t,y)
clc; close all;

%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);
gamma1 = 0.01;
q1 = 0.9;
q2 = 1*10^(-12);
q3 = 1*10^(-5);
q4 = 2*10^(-11);
delta1 = 0.0357;
psi1 = 2;
omega = 0.2;
u0 = 0.5;

%Sistem Kemoterapi Periodik
dy = zeros(5,1);

dy(1)= r1*y(1)-r1*b1*y(1)*y(1)-rho1*y(2)*y(1)-alpha1*y(4)*y(1)-
q1*y(5)*y(1);
dy(2)= r2*y(2)-r2*b2*y(2)*y(2)-mu1*y(2)-rho2*y(1)*y(2)-
q2*y(5)*y(2);
dy(3)= r3*y(3)-r3*b3*y(3)*y(3)-beta*y(4)*y(3)-q3*y(5)*y(3);
dy(4)= beta*y(3)*y(4)-mu2*y(4)-alpha2*y(1)*y(4)-q4*y(5)*y(4);
dy(5)= delta1*(u0+psi1*sin(omega*t))-gamma1*y(5);
end

%SIMULASI NUMERIK:
%Pengaruh Pemberian Kemoterapi secara Periodik
clc; clear all;
time1 = linspace(0,350);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History2 = [ na1; na2; na3; na4; na5 ];

```

```

-----KEMOTERAPI PERIODIK-----
ode23s(@F_Kemo_Periodik, time1, History2);
l1.x'; Y1 = sol1.y';
l1.x'; Y2 = sol1.y';

```



```

T3 = soll.x'; Y3 = soll.y';
T4 = soll.x'; Y4 = soll.y';
T5 = soll.x'; Y5 = soll.y';
Q1 = spline (T1, Y1(:,1),time1);
Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%Plot
subplot (321)
plot (time1, Q1,'red', 'LineWidth', 1.5);
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2,'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3,'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4,'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');

subplot (325)
plot (time1, Q5,'red', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('DK (mg/L)', 'FontSize', 12)
title ('(e)');

```



Lampiran 10. Simulasi Numerik untuk Sistem Imunoterapi Konstan

```

function dy = F_Imuno_Konstan (t,y)
clc; close all;

%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);
gamma2 = 0.02;
s1 = 1*10^(-2);
s2 = 1*10^(-5);
delta2 = 0.0179;
v0 = 0.4;

%Sistem Imunoterapi Konstan
dy = zeros(5,1);

dy(1)= r1*y(1)-r1*b1*y(1)*y(1)-rho1*y(2)*y(1)-alpha1*y(4)*y(1);
dy(2)= r2*y(2)-r2*b2*y(2)*y(2)-mu1*y(2)-rho2*y(1)*y(2);
dy(3)= r3*y(3)-r3*b3*y(3)*y(3)-beta*y(4)*y(3)+s1*y(5)*y(3);
dy(4)= beta*y(3)*y(4)-mu2*y(4)-alpha2*y(1)*y(4)+s2*y(5)*y(4);
dy(5)= delta2*v0-gamma2*y(5);
end

%SIMULASI NUMERIK:
%Pengaruh Pemberian Imunoterapi secara Konstan
clc; clear all;
time1 = linspace(0,350);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History2 = [ na1; na2; na3; na4; na5 ];

%-----IMUNOTERAPI KONSTAN-----
sol1 = ode23s(@F_Imuno_Konstan, time1, History2);
T1 = sol1.x'; Y1 = sol1.y';
T2 = sol1.x'; Y2 = sol1.y';
T3 = sol1.x'; Y3 = sol1.y';
T4 = sol1.x'; Y4 = sol1.y';
T5 = sol1.x'; Y5 = sol1.y';
line (T1, Y1(:,1),time1);
line (T2, Y2(:,2),time1);
line (T3, Y3(:,3),time1);

```



```

Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%Plot
subplot (321)
plot (time1, Q1,'blue', 'LineWidth', 1.5);
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2,'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3,'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4,'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');

subplot (325)
plot (time1, Q5,'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('DI (mg/L)', 'FontSize', 12)
title ('(e)');

```



Lampiran 11. Simulasi Numerik untuk Sistem Imunoterapi Periodik

```
function dy = F_Imuno_Periodik (t,y)
clc; close all;

%Nilai Parameter
r1 = 0.44;
r2 = 0.18;
r3 = 0.0245;
b1 = 9.8*10^(-8);
b2 = 1*10^(-9);
b3 = 1*10^(-10);
rho1 = 1.1*10^(-10);
rho2 = 4.8*10^(-10);
mu1 = 0.01;
mu2 = 0.0412;
alpha1 = 1.101*10^(-7);
alpha2 = 3.422*10^(-10);
beta = 6.2*10^(-9);
gamma2 = 0.02;
s1 = 1*10^(-2);
s2 = 1*10^(-5);
delta2 = 0.0179;
psi2 = 2;
omega = 0.2;
v0 = 0.4;

%Sistem Imunoterapi Periodik
dy = zeros(5,1);

dy(1)= r1*y(1)-r1*b1*y(1)*y(1)-rho1*y(2)*y(1)-alpha1*y(4)*y(1);
dy(2)= r2*y(2)-r2*b2*y(2)*y(2)-mu1*y(2)-rho2*y(1)*y(2);
dy(3)= r3*y(3)-r3*b3*y(3)*y(3)-beta*y(4)*y(3)+s1*y(5)*y(3);
dy(4)= beta*y(3)*y(4)-mu2*y(4)-alpha2*y(1)*y(4)+s2*y(5)*y(4);
dy(5)= delta2*(v0+psi2*sin(omega*t))-gamma2*y(5);
end

%SIMULASI NUMERIK:
%Pengaruh Pemberian Imunoterapi secara Periodik
clc; clear all;
time1 = linspace(0,350);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History2 = [ na1; na2; na3; na4; na5 ];

%-----IMUNOTERAPI PERIODIK-----
sol1 = ode23s(@F_Imuno_Periodik, time1, History2);
T1 = sol1.x'; Y1 = sol1.y';
T1 = sol1.x'; Y2 = sol1.y';
T1 = sol1.x'; Y3 = sol1.y';
T1 = sol1.x'; Y4 = sol1.y';
T1 = sol1.x'; Y5 = sol1.y';
line (T1, Y1(:,1),time1);
```



```

Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%Plot
subplot (321)
plot (time1, Q1, 'blue', 'LineWidth', 1.5);
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2, 'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3, 'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4, 'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');

subplot (325)
plot (time1, Q5, 'blue', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize', 12)
ylabel('DI (mg/L)', 'FontSize', 12)
title ('(e)');

```



Lampiran 12. Simulasi Numerik untuk Sistem Kombinasi Imunoterapi Konstan- Kemoterapi Konstan

```

%SIMULASI NUMERIK KOMBINASI:
%Pengaruh Pemberian Imunoterapi Konstan-Kemoterapi Konstan
clc; clear all;

%-----TERAPI PERTAMA-----
time1 = linspace(0,60);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History1 = [ na1; na2; na3; na4; na5 ];

%Imunoterapi Konstan
sol1 = ode23s(@F_Imuno_Konstan, time1, History1);
T1 = sol1.x'; Y1 = sol1.y';
T2 = sol1.x'; Y2 = sol1.y';
T3 = sol1.x'; Y3 = sol1.y';
T4 = sol1.x'; Y4 = sol1.y';
T5 = sol1.x'; Y5 = sol1.y';
Q1 = spline (T1, Y1(:,1),time1);
Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%-----TERAPI KEDUA-----
time2 = linspace(60,350);
%Kondisi Awal
na11 = 7.774e+06;
na22 = 9.238e+08;
na33 = 1.484e+06;
na44 = 2.56e+04;
na55 = 0;
History2 = [ na11; na22; na33; na44; na55 ];

%Kemoterapi Konstan
sol01 = ode23s(@F_Kemo_Konstan, time2, History2);
T01 = sol01.x'; Y01 = sol01.y';
T02 = sol01.x'; Y02 = sol01.y';
T03 = sol01.x'; Y03 = sol01.y';
T04 = sol01.x'; Y04 = sol01.y';
T05 = sol01.x'; Y05 = sol01.y';
Q01 = spline (T01, Y01(:,1),time2);
Q02 = spline (T02, Y02(:,2),time2);
Q03 = spline (T03, Y03(:,3),time2);
Q04 = spline (T04, Y04(:,4),time2);
Q05 = spline (T05, Y05(:,5),time2);

(321)
time1, Q1, 'g',time2, Q01, 'g', 'LineWidth', 1.5);
'Waktu (Hari)', 'FontSize',12)

```



```
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2, 'g',time2, Q02, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3, 'g',time2, Q03, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4, 'g',time2, Q04, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');
```



Lampiran 13. Simulasi Numerik untuk Sistem Kombinasi Imunoterapi Konstan-Kemoterapi Periodik

```

%SIMULASI NUMERIK KOMBINASI:
%Pengaruh Pemberian Imunoterapi Konstan-Kemoterapi Periodik
clc; clear all;

%-----TERAPI PERTAMA-----
time1 = linspace(0,60);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History1 = [ na1; na2; na3; na4; na5 ];

%Imunoterapi Konstan
sol1 = ode23s(@F_Imuno_Konstan, time1, History1);
T1 = sol1.x'; Y1 = sol1.y';
T2 = sol1.x'; Y2 = sol1.y';
T3 = sol1.x'; Y3 = sol1.y';
T4 = sol1.x'; Y4 = sol1.y';
T5 = sol1.x'; Y5 = sol1.y';
Q1 = spline (T1, Y1(:,1),time1);
Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%-----TERAPI KEDUA-----
time2 = linspace(60,350);
%Kondisi Awal
na11 = 7.774e+06;
na22 = 9.238e+08;
na33 = 1.484e+06;
na44 = 2.56e+04;
na55 = 0;
History2 = [ na11; na22; na33; na44; na55 ];

%Kemoterapi Periodik
sol01 = ode23s(@F_Kemo_Periodik, time2, History2);
T01 = sol01.x'; Y01 = sol01.y';
T02 = sol01.x'; Y02 = sol01.y';
T03 = sol01.x'; Y03 = sol01.y';
T04 = sol01.x'; Y04 = sol01.y';
T05 = sol01.x'; Y05 = sol01.y';
Q01 = spline (T01, Y01(:,1),time2);
Q02 = spline (T02, Y02(:,2),time2);
Q03 = spline (T03, Y03(:,3),time2);
Q04 = spline (T04, Y04(:,4),time2);
Q05 = spline (T05, Y05(:,5),time2);

(321)
time1, Q1, 'g',time2, Q01, 'g', 'LineWidth', 1.5);
'Waktu (Hari)', 'FontSize',12)

```



```
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2, 'g',time2, Q02, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3, 'g',time2, Q03, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4, 'g',time2, Q04, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');
```



Lampiran 14. Simulasi Numerik untuk Sistem Kombinasi Imunoterapi Periodik-Kemoterapi Konstan

```

%SIMULASI NUMERIK KOMBINASI:
%Pengaruh Pemberian Imunoterapi Periodik-Kemoterapi Konstan
clc; clear all;

%-----TERAPI PERTAMA-----
time1 = linspace(0,60);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History1 = [ na1; na2; na3; na4; na5 ];

%Imunoterapi Periodik
sol1 = ode23s(@F_Imuno_Periodik, time1, History1);
T1 = sol1.x'; Y1 = sol1.y';
T2 = sol1.x'; Y2 = sol1.y';
T3 = sol1.x'; Y3 = sol1.y';
T4 = sol1.x'; Y4 = sol1.y';
T5 = sol1.x'; Y5 = sol1.y';
Q1 = spline (T1, Y1(:,1),time1);
Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%-----TERAPI KEDUA-----
time2 = linspace(60,350);
%Kondisi Awal
na11 = 7.773e+06;
na22 = 9.238e+08;
na33 = 1.58e+06;
na44 = 2.603e+04;
na55 = 0;
History2 = [ na11; na22; na33; na44; na55 ];

%Kemoterapi Konstan
sol01 = ode23s(@F_Kemo_Konstan, time2, History2);
T01 = sol01.x'; Y01 = sol01.y';
T02 = sol01.x'; Y02 = sol01.y';
T03 = sol01.x'; Y03 = sol01.y';
T04 = sol01.x'; Y04 = sol01.y';
T05 = sol01.x'; Y05 = sol01.y';
Q01 = spline (T01, Y01(:,1),time2);
Q02 = spline (T02, Y02(:,2),time2);
Q03 = spline (T03, Y03(:,3),time2);
Q04 = spline (T04, Y04(:,4),time2);
Q05 = spline (T05, Y05(:,5),time2);

(321)
time1, Q1, 'g',time2, Q01, 'g', 'LineWidth', 1.5);
'Waktu (Hari)', 'FontSize',12)

```



```
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2, 'g',time2, Q02, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3, 'g',time2, Q03, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4, 'g',time2, Q04, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');
```



Lampiran 15. Simulasi Numerik untuk Sistem Kombinasi Imunoterapi Periodik- Kemoterapi Periodik

```

%SIMULASI NUMERIK KOMBINASI
%Pengaruh Pemberian Imunoterapi Periodik-Kemoterapi Periodik
clc; clear all;

%-----TERAPI PERTAMA-----
time1 = linspace(0,60);
%Kondisi Awal
na1 = 10^6;
na2 = 10^9;
na3 = 3*10^5;
na4 = 3*10^5;
na5 = 0;
History1 = [ na1; na2; na3; na4; na5 ];

%Imunoterapi Periodik
sol1 = ode23s(@F_Imuno_Periodik, time1, History1);
T1 = sol1.x'; Y1 = sol1.y';
T2 = sol1.x'; Y2 = sol1.y';
T3 = sol1.x'; Y3 = sol1.y';
T4 = sol1.x'; Y4 = sol1.y';
T5 = sol1.x'; Y5 = sol1.y';
Q1 = spline (T1, Y1(:,1),time1);
Q2 = spline (T2, Y2(:,2),time1);
Q3 = spline (T3, Y3(:,3),time1);
Q4 = spline (T4, Y4(:,4),time1);
Q5 = spline (T5, Y5(:,5),time1);

%-----TERAPI KEDUA-----
time2 = linspace(60,350);
%Kondisi Awal
na11 = 7.773e+06;
na22 = 9.238e+08;
na33 = 1.58e+06;
na44 = 2.603e+04;
na55 = 0;
History2 = [ na11; na22; na33; na44; na55 ];

%Kemoterapi Periodik
sol01 = ode23s(@F_Kemo_Periodik, time2, History2);
T01 = sol01.x'; Y01 = sol01.y';
T02 = sol01.x'; Y02 = sol01.y';
T03 = sol01.x'; Y03 = sol01.y';
T04 = sol01.x'; Y04 = sol01.y';
T05 = sol01.x'; Y05 = sol01.y';
Q01 = spline (T01, Y01(:,1),time2);
Q02 = spline (T02, Y02(:,2),time2);
Q03 = spline (T03, Y03(:,3),time2);
Q04 = spline (T04, Y04(:,4),time2);
Q05 = spline (T05, Y05(:,5),time2);

(321)
time1, Q1, 'g',time2, Q01, 'g', 'LineWidth', 1.5);
'Waktu (Hari)', 'FontSize',12)

```



```
ylabel('C (sel)', 'FontSize', 12)
title ('(a)');

subplot (322)
plot (time1, Q2, 'g',time2, Q02, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
title ('(b)');

subplot (323)
plot (time1, Q3, 'g',time2, Q03, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Ip (sel)', 'FontSize', 12)
title ('(c)');

subplot (324)
plot (time1, Q4, 'g',time2, Q04, 'g', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('Is (sel)', 'FontSize', 12)
title ('(d)');
```



Lampiran 16. Perhitungan Efek Toksisitas terhadap Sel Normal yang Dihasilkan oleh Kemoterapi Tunggal dan Kombinasi Terapi

```

function dy = F_Toksik_KemoK (t,y)
clc; close all;
%Nilai Parameter
gamma1 = 0.01;
q2 = 1*10^(-12);
delta1 = 0.0357;
u0 = 0.5;
%Efek Toksisitas Kemoterapi Konstan terhadap Sel Normal
dy = zeros(2,1);
dy(1)= -q2*y(2)*y(1);
dy(2)= delta1*u0-gamma1*y(2);
end

function dy = F_Toksik_KemoP (t,y)
clc; close all;
%Nilai Parameter
gamma1 = 0.01;
q2 = 1*10^(-12);
delta1 = 0.0357;
psil = 2;
omega = 0.2;
u0 = 0.5;
%Efek Toksisitas Kemoterapi Periodik terhadap Sel Normal
dy = zeros(2,1);
dy(1)= -q2*y(2)*y(1);
dy(2)= delta1*(u0+psil*sin(omega*t))-gamma1*y(2);
end

%Perhitungan Efek Sitotoksik dari KEMOTERAPI TUNGGAL
clc; clear all;
time1 = linspace(0,350);
%Kondisi Awal
na2 = 10^9;
na5 = 0;
History2 = [ na2; na5 ];
%-----KEMOTERAPI KONSTAN-----
sol1 = ode23s(@F_Toksik_KemoK, time1, History2);
T2 = sol1.x'; Y2 = sol1.y';
Q2 = spline (T2, Y2(:,1),time1);
%Plot
plot (time1, Q2,'black', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
%Besar Efek Toksisitas dari Kemoterapi Konstan terhadap Sel Normal
ET_H_KK = trapz(T2, Y2(:,1))
%-----KEMOTERAPI PERIODIK-----
sol11 = ode23s(@F_Toksik_KemoP, time1, History2);
T22 = sol11.x'; Y22 = sol11.y';
Q22 = spline (T22, Y22(:,1),time1);
plot (time1, Q22,'black', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)

```



```

%Besar Efek Toksisitas dari Kemoterapi Periodik terhadap Sel
Normal
ET_H_KP = trapz(T22, Y2(:,1))

%Perhitungan Efek Sitotoksik dari KOMBINASI TERAPI
%IMUNOTERAPI KONSTAN-KEMOTERAPI KONSTAN:
clc; clear all;
%-----TERAPI PERTAMA-----
%Besar Efek Toksisitas Imunoterapi Konstan terhadap Sel Normal = 0
ET_H_IK = 0;
%-----TERAPI KEDUA-----
time1 = linspace(60,350);
%Kondisi Awal
na22 = 9.238e+08;
na55 = 0;
History1 = [ na22; na55 ];
%Kemoterapi Konstan
soll1 = ode23s(@F_Toksik_KemoK, time1, History1);
T2 = soll1.x'; Y2 = soll1.y';
Q2 = spline (T2, Y2(:,1),time1);
%Plot
plot (time1, Q2,'black', 'LineWidth', 1.5)
xlabel('Waktu (Hari)','FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
%Besar Efek Toksisitas dari Kemoterapi Konstan terhadap Sel Normal
ET_H_KK = trapz(T2, Y2(:,1));
%Total Efek Toksisitas dari Imunoterapi Konstan-Kemoterapi Konstan
terhadap Sel Normal
ET_H = ET_H_IK + ET_H_KK

%IMUNOTERAPI KONSTAN-KEMOTERAPI PERIODIK:
clc; clear all;
%-----TERAPI PERTAMA-----
%Besar Efek Toksisitas Imunoterapi Konstan terhadap Sel Normal = 0
ET_H_IK = 0;
%-----TERAPI KEDUA-----
time1 = linspace(60,350);
%Kondisi Awal
na22 = 9.238e+08;
na55 = 0;
History1 = [ na22; na55 ];
%Kemoterapi Periodik
soll1 = ode23s(@F_Toksik_KemoP, time1, History1);
T2 = soll1.x'; Y2 = soll1.y';
Q2 = spline (T2, Y2(:,1),time1);
%Plot
plot (time1, Q2,'black', 'LineWidth', 1.5)
xlabel('Waktu (Hari)','FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
%Besar Efek Toksisitas dari Kemoterapi Periodik terhadap Sel
Normal
ET_H_KP = trapz(T2, Y2(:,1));
%Total Efek Toksisitas dari Imunoterapi Konstan-Kemoterapi
Periodik terhadap Sel Normal
ET_H = ET_H_IK + ET_H_KP

```



```

%IMUNOTERAPI PERIODIK-KEMOTERAPI KONSTAN:
clc; clear all;
%-----TERAPI PERTAMA-----
%Besar Efek Toksisitas Imunoterapi Periodik terhadap Sel Normal= 0
ET_H_IP = 0;
%-----TERAPI KEDUA-----
time1 = linspace(60,350);
%Kondisi Awal
na22 = 9.238e+08;
na55 = 0;
History1 = [ na22; na55 ];
%Kemoterapi Konstan
soll1 = ode23s(@F_Toksik_KemoK, time1, History1);
T2 = soll1.x'; Y2 = soll1.y';
Q2 = spline (T2, Y2(:,1),time1);
%Plot
plot (time1, Q2, 'black', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
%Besar Efek Toksisitas dari Kemoterapi Konstan terhadap Sel Normal
ET_H_KK = trapz(T2, Y2(:,1));
%Total Efek Toksisitas dari Imunoterapi Periodik-Kemoterapi
Konstan terhadap Sel Normal
ET_H = ET_H_IP + ET_H_KK

%IMUNOTERAPI PERIODIK-KEMOTERAPI PERIODIK:
clc; clear all;
%-----TERAPI PERTAMA-----
%Besar Efek Toksisitas Imunoterapi Periodik terhadap Sel Normal= 0
ET_H_IP = 0;
%-----TERAPI KEDUA-----
time1 = linspace(60,350);
%Kondisi Awal
na22 = 9.238e+08;
na55 = 0;
History1 = [ na22; na55 ];
%Kemoterapi Periodik
soll1 = ode23s(@F_Toksik_KemoP, time1, History1);
T2 = soll1.x'; Y2 = soll1.y';
Q2 = spline (T2, Y2(:,1),time1);
%Plot
plot (time1, Q2, 'black', 'LineWidth', 1.5)
xlabel('Waktu (Hari)', 'FontSize',12)
ylabel('H (sel)', 'FontSize', 12)
%Besar Efek Toksisitas dari Kemoterapi Periodik terhadap Sel
Normal
ET_H_KP = trapz(T2, Y2(:,1));
%Total Efek Toksisitas dari Imunoterapi Periodik-Kemoterapi
Periodik terhadap Sel Normal
ET_H = ET_H_IP + ET_H_KP

```



Berdasarkan hasil simulasi tersebut, diperoleh bahwa besar efek toksisitas dari kemoterapi tunggal baik kemoterapi konstan dan kemoterapi periodik, yaitu sebesar $3,50 \times 10^{11}$ sedangkan dari kombinasi terapi baik imunoterapi konstan-kemoterapi konstan, imunoterapi konstan-kemoterapi periodik, imunoterapi periodik-kemoterapi konstan, dan imunoterapi periodik-kemoterapi periodik, yaitu sebesar $2,65 \times 10^{11}$. Jika dilakukan perhitungan sebagai berikut:

$$\frac{3,50 \times 10^{11} - 2,65 \times 10^{11}}{3,50 \times 10^{11}} \times 100\% = 24,29\%,$$

maka diperoleh bahwa efek toksisitas terhadap sel normal yang dihasilkan oleh kombinasi terapi yaitu 24,29% lebih rendah dibandingkan dengan yang dihasilkan oleh kemoterapi tunggal.

