

DAFTAR PUSTAKA

- Ahuja, M.K., Singh, A., 2015. Static vision based Hand Gesture recognition using principal component analysis, in: 2015 IEEE 3rd International Conference on MOOCs, Innovation and Technology in Education (MITE). Presented at the 2015 IEEE 3rd International Conference on MOOCs, Innovation and Technology in Education (MITE), pp. 402–406. <https://doi.org/10.1109/MITE.2015.7375353>
- Chuan, C., Regina, E., Guardino, C., 2014. American Sign Language Recognition Using Leap Motion Sensor, in: 2014 13th International Conference on Machine Learning and Applications. Presented at the 2014 13th International Conference on Machine Learning and Applications, pp. 541–544. <https://doi.org/10.1109/ICMLA.2014.110>
- Dzulkarnain, I., Sumpeno, S., Christyowidiasmoro, C., 2016. Pengenalan Isyarat Tangan Menggunakan Leap Motion Controller untuk Pertunjukan Boneka Tangan Virtual. *Jurnal Teknik ITS* 5. <https://doi.org/10.12962/j23373539.v5i2.16462>
- Hartanto, R., Kartikasari, A., 2016. Android based real-time static Indonesian sign language recognition system prototype, in: 2016 8th International Conference on Information Technology and Electrical Engineering (ICITEE). Presented at the 2016 8th International Conference on Information Technology and Electrical Engineering (ICITEE), pp. 1–6. <https://doi.org/10.1109/ICITEED.2016.7863311>
- Hasan, M.A., Tolle, H., Brata, A.H., 2018. Implementasi Aplikasi Papan Komunikasi (Communication Board) Berbasis Tablet Android Bagi Tunarungu 7.
- Khamid, Wibawa, A.D., Sumpeno, S., 2017. Gesture Recognition for Indonesian Sign Language Systems (ISLS) Using Multimodal Sensor Leap Motion and Myo Armband Controllers Based-on Naïve Bayes Classifier, in: 2017 International Conference on Soft Computing, Intelligent System and Information Technology (ICSIIT). Presented

- at the 2017 International Conference on Soft Computing, Intelligent System and Information Technology (ICSIIT), pp. 1–6. <https://doi.org/10.1109/ICSIIT.2017.42>
- Kuroki, K., Zhou, Y., Cheng, Z., Lu, Z., Zhou, Y., Jing, L., 2015. A remote conversation support system for deaf-mute persons based on bimanual gestures recognition using finger-worn devices, in: 2015 IEEE International Conference on Pervasive Computing and Communication Workshops (PerCom Workshops). Presented at the 2015 IEEE International Conference on Pervasive Computing and Communication Workshops (PerCom Workshops), pp. 574–578. <https://doi.org/10.1109/PERCOMW.2015.7134101>
- Maulia, N., 2017. PENGARUH PENGGUNAAN SISTEM ISYARAT BAHASA INDONESIA (SIBI) TERHADAP PEMAHAMAN INFORMASI SISWA PENYANDANG TUNARUNGU DI SLB-PKK PROVINSI LAMPUNG 15.
- Mohandes, M., Aliyu, S., Deriche, M., 2015. Prototype Arabic Sign language recognition using multi-sensor data fusion of two leap motion controllers, in: 2015 IEEE 12th International Multi-Conference on Systems, Signals Devices (SSD15). Presented at the 2015 IEEE 12th International Multi-Conference on Systems, Signals Devices (SSD15), pp. 1–6. <https://doi.org/10.1109/SSD.2015.7348113>
- Nugroho, A.S., Witarto, A.B., Handoko, D., 2003. –Teori dan Aplikasinya dalam Bioinformatika1– 11.
- Nuriyanti, Y., Tresnawati, D., 2015. PENGEMBANGAN APLIKASI PENGENALAN DASAR BAHASA ISYARAT SEBAGAI MEDIA PEMBELAJARAN BERBASIS ANDROID 12, 9.
- Pramunanto, E., Sumpeno, S., Legowo, R.S., 2017. Classification of hand gesture in Indonesian sign language system using Naive Bayes, in: 2017 International Seminar on Sensors, Instrumentation, Measurement and Metrology (ISSIMM). Presented at the 2017 International Seminar on Sensors, Instrumentation, Measurement

- and Metrology (ISSIMM), pp. 187–191.
<https://doi.org/10.1109/ISSIMM.2017.8124288>
- Saxena, A., Jain, D.K., Singhal, A., 2014. Hand Gesture Recognition Using an Android Device, in: 2014 Fourth International Conference on Communication Systems and Network Technologies. Presented at the 2014 Fourth International Conference on Communication Systems and Network Technologies, pp. 819–822.
<https://doi.org/10.1109/CSNT.2014.170>
- Sidabutar, R.P., Andhini, M., Daulika, C.A., Hidayati, H., Kom, S., 2015. Jurnal Aplikasi CallMe : Aplikasi Alat Bantu Komunikasi Jarak Jauh Untuk Penyandang Tuna Rungu Dan Penyandang Tuna netra 5.
- Supria, Muhamad Nasir, R.F., 2017. Aplikasi Marawis Digital Menggunakan Sensor Leap Motion.
- Suyanto, 2017. DATA MINING, Mei 2017. ed, Untuk Klasifikasi dan Klasterisasi Data. Informatika Bandung.
- Syafiq, M., Al Kadafi, A.J., Zakiiyah, R.H., Jauhari, D., Luqyana, W.A., Cholissodin, I., Muflikhah, L., 2016. Aplikasi Mobile (Lide) Untuk Diagnosis Tingkat Resiko Penyakit Stroke Menggunakan PTVPSO-SVM. Jurnal Teknologi Informasi dan Ilmu Komputer 3, 147.
<https://doi.org/10.25126/jtiik.201632190>
- Wibowo, M.D., Nurtanio, I., Ilham, A.A., 2017. Indonesian sign language recognition using leap motion controller, in: 2017 11th International Conference on Information Communication Technology and System (ICTS). Presented at the 2017 11th International Conference on Information Communication Technology and System (ICTS), pp. 67–72. <https://doi.org/10.1109/ICTS.2017.8265648>
- Wibowo, M.D., Nurtanio, I., Ilham, A.A., n.d. Indonesian sign language recognition using leap motion controller - IEEE Conference Publication.
- Wijayanto, C.P., 2009. MEMBANGUN APLIKASI PELATIHAN BAHASA ISYARAT BERBASIS KOMPUTER PADA ORANG TUNARUNGU.

LAMPIRAN 1

Biodata Guru Ahli Isyarat SIBI SLB Katolik Rajawali

Nama : Dominika Roa,S.Pd
Tempat/Tgl Lahir : Bokeka, 30 September 1994
No. Hp : 0821919791446
NIP : -
Alamat : Jl. Lamadukelleng
Status Guru : Guru Slb Kelas X
Lama Mengajar : 1 Tahun 10 Bulan

LAMPIRAN 2

Dataset dari API *Leap Motion*

F51.1313374042511		
aF15.881324768066406	aF23.646447075737846	aa(lp23
aF-12.56293123960495	aF-98.40548027886285	F50.776134729385376
aF31.521901726722717	aF-9.055412451426188	aF18.297447204589844
aF15.243303298950195	aF28.051076253255207	aF-12.370995223522186
aF-86.32466745376587	aF-88.82417085435655	aF31.58326506614685
aF11.343953967094421	aF-29.445795483059353	aF18.664703369140625
aF16.304914474487305	aF22.36202833387587	aF-86.30322408676147
aF-99.54169416427612	aF-68.45867029825847	aF11.083371877670288
aF-6.881304860115051	aF17.967585751187087	aF19.816783905029297
aF18.875247955322266	aF153.2526798963134	aF-99.37541055679321
aF-91.84874629974365	aa(lp23	aF-6.3777996301651
aF-28.42245662212372	F50.776134729385376	aF18.398956298828125
aF13.700569152832031	aF18.297447204589844	aF-92.52093887329102
aF-70.94187641143799	aF-12.370995223522186	aF-29.20080268383026
aF20.37058435165299	aF31.58326506614685	aF15.143062591552734
aF156.44460184473914	aF18.664703369140625	aF-71.31683111190796
aa(lp22	aF-86.30322408676147	aF17.774632005928712
F50.22144444783529	aF11.083371877670288	aF152.72340720943677
aF22.800189548068577	aF19.816783905029297	etc
aF-10.649721569485134	aF-99.37541055679321	
aF30.59514586130778	aF-6.3777996301651	
aF22.468241373697918	aF18.398956298828125	
aF-85.41178597344293	aF-92.52093887329102	
aF10.428424305386013	aF-29.20080268383026	

LAMPIRAN 3

Source Code pada proses penerjemah

```

import math
class SVM:
    def __init__(self):
        self.classes = {}
    def train(self, kernel):
        """Given the training features X with labels y, returns a SVM
        predictor representing the trained SVM.
        """
        # Sort kernel by class
        classesData = {}
        for labels in kernel:
            # If class is new
            if labels[0] not in classesData:
                classesData[labels[0]] = [labels[1]]
                self.classes[labels[0]] = []

            # Append to existing class
            else:
                classesData[labels[0]].append(labels[1])

        # Compute formula components per class
        for _class, linear in classesData.iteritems():
            prior = math.log(len(linear)/float(len(kernel)))
            mu = []
            variance = []

            # Fill lists of mu and variance for each feature
            for feature in zip(*linear): # * selects columns instead of rows
                avg = sum(feature)/float(len(feature))
                mu.append(avg)
                variance.append(sum(map(lambda x : (x - avg) ** 2, feature))
                / len(feature)) #

            # Precompute first part of formula
            base = sum(map(lambda x : math.log(2 * math.pi * x), variance)) * (-
            0.5)

            maxDistance = 0
            totalDistance = 0
            for sample in linear:
                euclid = self.euclidian(sample, mu)
                totalDistance += euclid
                if euclid > maxDistance:
                    maxDistance = euclid

```

```

# Store results
        self.classes[_class] = (mu, variance, prior + base, maxDistance)
def euclidian(self, pVector, qVector):
    """
    Get euclidian distance between vector p and q
    """
    return math.sqrt(sum([(p - q) ** 2 for p, q in zip(pVector, qVector)]))
def support_vectors(self, vector):
    """
    Get the support vectors for all classes
    along with euclidian distances
    """
    support_vectors = []
    distances = [] #euclidian distances for novelty detection

    for _class in self.classes:
        _vars = zip(vector, self.classes[_class][0], self.classes[_class][1])

        # Calculate rest of formula; the exponent
        exp = (-0.5) * sum(map(lambda x : (x[0] - x[1])**2 / x[2], _vars))
        support_vectors.append(self.classes[_class][2]+exp)

        # Calculate how many max distances vector is from average in n-
dimensions
        distances.append(self.euclidian(vector, self.classes[_class][0]) /
self.classes[_class][3])
        # Normalize; convert log between 0 and 1
        _sum = sum(support_vectors)
        output = []
        for _class, support_vector_labels, dist in zip(self.classes, support_vectors,
distances):
            output.append((_class, (1 - (support_vector_labels / _sum)) / 2.0,
dist))

    return sorted(output, key=lambda x: x[1], reverse=True)

def classify(self, vector):
    """
    Get name only of the best candidate of class match
    """
    return self.support_vectors(vector)[0][0]
def accuracy(self, kernel):
    """
    Test accuracy of trained classifier
    """
    return sum([d[0] == self.classify(d[1]) for d in kernel]) / float(len(kernel))

```