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LAMPIRAN

Lampiran 1. Program ventilator

```
code_venus_rev1 | Arduino 1.8.13
File Edit Sketch Tools Help
code_venus_rev1
#include <ezButton.h>
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
#include <EEPROMex.h>
#include <EEPROMVar.h>
#include "Arduino.h"

void disp(int input,byte col,byte row);
void setup();
void loop();

LiquidCrystal_I2C lcd(0x27,20,4);

ezButton pbset(2);
ezButton pbleft(3);
ezButton pbup(4);
ezButton pbright(5);
ezButton pbdown(6);
ezButton pbok(7);

const byte highpress = 44;
bool highpresstate = LOW;
unsigned long sebelum1 = 0;
long highpresson;
long highpressoff;

const byte lowpress = 45;
bool lowpresstate = LOW;
unsigned long sebelum2 = 0;
long highpresson;
long highpressoff;

const byte lowpress = 45;
bool lowpresstate = LOW;
unsigned long sebelum2 = 0;
long lowpresson;
long lowpressoff;

unsigned long sebelum3 = 0;
const long sampling = 100;

char tv_buf[9];
char bpm_buf[9];
char ie_buf[9];
```

```

ezButton pbleft(3);
ezButton pbup(4);
ezButton pbright(5);
ezButton pbdown(6);
ezButton pbok(7);

const byte highpress = 44;
bool highpresstate = LOW;
unsigned long sebelum1 = 0;
long highpression;
long highpressoiff;

const byte lowpress = 45;
bool lowpresstate = LOW;
unsigned long sebelum2 = 0;

//const float ADC_mV = 4.8828125; // convesion multiplier from Arduino ADC value to voltage in mV
const float ADC_mV = 4.8828125; // convesion multiplier from Arduino ADC value to voltage in mV
const float SensorOffset = 200.0; // in mV taken from datasheet
const float sensitivity = 4.413; // in mV/mmH2O taken from datasheet
const float mmh20_cmH2O = 10; // divide by this figure to convert mmH2O to cmH2O
const float mmh20_kpa = 0.00981; // convesion multiplier from mmH2O to kPa
const float mmh20_pa = 9.81; // convesion multiplier from mmH2O to Pa

void disp(int input,byte col,byte row){
  char buff[9];
  if (input <10){
    lcd.setCursor(col+1,row);lcd.print(" ");
    lcd.setCursor(col,row);lcd.print(itoa(input,buff,10));
  }else if ((input>=10)&&(input<100)){
    lcd.setCursor(col+2,row);lcd.print(" ");
    lcd.setCursor(col,row);lcd.print(itoa(input,buff,10));
  }else if ((input>=100)&&(input<1000)){
    lcd.setCursor(col+3,row);lcd.print(" ");
    lcd.setCursor(col,row);lcd.print(itoa(input,buff,10));
  }else if (input>=1000){
    lcd.setCursor(col+4,row);lcd.print(" ");
    lcd.setCursor(col,row);lcd.print(itoa(input,buff,10));
  }else {
    lcd.setCursor(col,row);lcd.print(itoa(input,buff,10));
  }
}

void setup() {
  pinMode(highpress,OUTPUT);
  pinMode(lowpress,OUTPUT);
  digitalWrite(highpress,LOW);
  digitalWrite(lowpress,LOW);

  pbset.setDebounceTime(50);
  pbleft.setDebounceTime(50);
  pbup.setDebounceTime(50);
  pbright.setDebounceTime(50);
  pbdown.setDebounceTime(50);
  pbok.setDebounceTime(50);

  Serial.begin(115200);
}

```

```

lcd.init();
lcd.init();
lcd.backlight();
lcd.setCursor(0,0);
lcd.print(" >>> VENUS-02 <<< ");
lcd.setCursor(0,1);
lcd.print(" VENTILATOR UNHAS ");
delay(1000);
lcd.clear();
tv = EEPROM.readInt(addr_tv);
bpm = EEPROM.readInt(addr_bpm);
ie = EEPROM.readInt(addr_ie);
}

void loop() {
  pbset.loop();pbleft.loop();pbup.loop();pbright.loop();pbdown.loop();pbok.loop();

  switch (state){
    case 0 :
      lcd.setCursor(0,0);lcd.print("HOME");
      lcd.setCursor(0,1);lcd.print("TV :");disp(tv,5,1);
      lcd.setCursor(0,2);lcd.print("BPM :");disp(bpm,5,2);
      lcd.setCursor(0,3);lcd.print("IE :1/");disp(ie,7,3);
      if(pbok.isPressed()){
        lcd.clear();
        state = 1;
      }else {
        state = 0;
      }
      break;

    case 1 :
      lcd.setCursor(0,0);lcd.print("Set Volume");
      lcd.setCursor(0,1);lcd.print("TV :");disp(tv,5,1);
      lcd.setCursor(0,2);lcd.print("BPM :");disp(bpm,5,2);
      lcd.setCursor(0,3);lcd.print("IE :1/");disp(ie,7,3);
      if (tv>800){
        tv = 800;
      }else if (tv<100){
        tv = 100;
      }else {
        tv = tv;
      }

      if(pbup.isReleased()){
        tv=tv+10;
      }else if(pbdown.isReleased()){
        tv=tv-10;
      }else if(pbleft.isReleased()){
        lcd.clear();
        state = 0;
      }else if(pbright.isReleased()){
        lcd.clear();
        state = 2;
      }
    }
  }
}

```

```

}else if(pbok.isPressed()){
    EEPROM.writeInt(addr_tv, tv);
    lcd.setCursor(15, 0); lcd.print("Saved");
    state = 1;
}else {
    state = 1;
}
break;

case 2 :
    lcd.setCursor(0, 0); lcd.print("Set BPM");
    lcd.setCursor(0, 1); lcd.print("TV  :"); disp(tv, 5, 1);
    lcd.setCursor(0, 2); lcd.print("BPM :"); disp(bpm, 5, 2);
    lcd.setCursor(0, 3); lcd.print("IE  :1/"); disp(ie, 7, 3);
    if (bpm > 40) {
        bpm = 40;
    } else if (bpm < 8) {
        bpm = 8;
    } else {
        bpm = bpm;
    }

    if (pbup.isReleased()) {
        bpm++;
    } else if (pbdown.isReleased()) {
        bpm--;
    } else if (pbleft.isReleased()) {
        lcd.clear();
        state = 1;
    } else if (pbright.isReleased()) {
        lcd.clear();
        state = 3;
    } else if (pbok.isPressed()) {
        EEPROM.writeInt(addr_bpm, bpm);
        lcd.setCursor(15, 0); lcd.print("Saved");
        state = 2;
    } else {
        state = 2;
    }
    break;

case 3 :
    lcd.setCursor(0, 0); lcd.print("Set I/E");
    lcd.setCursor(0, 1); lcd.print("TV  :"); disp(tv, 5, 1);
    lcd.setCursor(0, 2); lcd.print("BPM :"); disp(bpm, 5, 2);
    lcd.setCursor(0, 3); lcd.print("IE  :1/"); disp(ie, 7, 3);
    if (ie > 5) {
        ie = 5;
    }

```

```

}else if (ie<1){
    ie = 1;
}else {
    ie = ie;
}

if(pbup.isReleased()){
    ie++;
}else if(pbdwn.isReleased()){
    ie--;
}else if(pbleft.isReleased()){
    lcd.clear();
    state = 2;
}else if(pbright.isReleased()){
    lcd.clear();
    state = 4;
}else if(pbok.isPressed()){
    EEPROM.writeInt(addr_ie,ie);
    lcd.setCursor(15,0);lcd.print("Saved");
    state = 3;
}else {
    state = 3;
}
break;

```

case 4 :

```

tv = EEPROM.readInt(addr_tv);
bpm = EEPROM.readInt(addr_bpm);
ie = EEPROM.readInt(addr_ie);
ie = EEPROM.readInt(addr_ie);
perioda =(60.0/bpm)*1000.0; // dalam ms
ton = (1/(1.0+ie))*perioda;
toff = perioda - ton;
highpresson = tv;
highpressoff = perioda - tv;
lowpresson = ton;
lowpressoff = toff;
lcd.setCursor(0,0);lcd.print("TV:");lcd.print(tv);lcd.print(" ");lcd.print
lcd.setCursor(0,1);lcd.print("T  :");lcd.print(perioda);
lcd.setCursor(0,2);lcd.print("ton :");lcd.print(ton);
lcd.setCursor(0,3);lcd.print("toff:");lcd.print(toff);
if (pbok.isReleased()){
    lcd.clear();
    state = 0;
}else if (pbset.isReleased()){
    sebelum1=millis();
    sebelum2=millis();
    state = 5;
}
break;

```

```

case 5 :
    sekarang = millis();
    if((lowpresstate == HIGH) && (sekarang - sebelum2 >= lowpresson)){
        lowpresstate = LOW;
        sebelum2 = sekarang;
        digitalWrite(lowpress, lowpresstate);
    }else if ((lowpresstate == LOW) && (sekarang - sebelum2 >= lowpressoff)){
        lowpresstate = HIGH;
        sebelum2 = sekarang;
        digitalWrite(lowpress, lowpresstate);
    }
    if((lowpresstate == LOW) && (highpresstate == HIGH) && (sekarang - sebelum1 >= highpresson)){
        highpresstate = LOW;
        sebelum1 = sekarang;
        digitalWrite(highpress, highpresstate);
    }else if ((lowpresstate == LOW) && (highpresstate == LOW) && (sekarang - sebelum1 >= highpressoff)){
        highpresstate = HIGH;
        sebelum1 = sekarang;
        digitalWrite(highpress, highpresstate);
    }
    }

    if(sekarang-sebelum3>=sampling){
        sebelum3 = sekarang;
        float deltaP = ((analogRead(A1) * ADC_mV - SensorOffset) / sensitivity * mmh20_pa); // result in Pa
        float Q = 5.42*sqrt(deltaP)/100;
        float cmh2o = (analogRead(A0) * ADC_mV - SensorOffset) / sensitivity / mmh20_cmH2O; // result in cmH2O
        lcd.setCursor(13,1);lcd.print("P:");lcd.print(" ");
        lcd.setCursor(15,1);lcd.print(cmh2o);
        lcd.setCursor(13,2);lcd.print("Q:");lcd.print(" ");
        lcd.setCursor(15,2);lcd.print(Q,3);
        lcd.setCursor(13,3);lcd.print(Q,3);
        Serial.println(cmh2o);
    }
    }

    if (pbok.isPressed()){
        digitalWrite(highpress,LOW);
        digitalWrite(lowpress,HIGH);delay(5000);
        digitalWrite(lowpress,LOW);
        lcd.clear();
        state = 0;
    }
    break;
}
}
}

```


Lampiran 2. Pengujian ventilator di RS. Dr. Wahidin Sudirohusodo



Lampiran 3. Pengukuran PIP dengan Sensor MPX 5010 DP

```
code_venus_rev1 | Arduino 1.8.13
File Edit Sketch Tools Help

code_venus_rev1
#include <ezButton.h>
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
#include <EEPROMex.h>
#include <EEPROMVar.h>
#include "Arduino.h"

void disp(int input,byte col,byte row);
void setup();
void loop();

LiquidCrystal_I2C lcd(0x27,20,4);

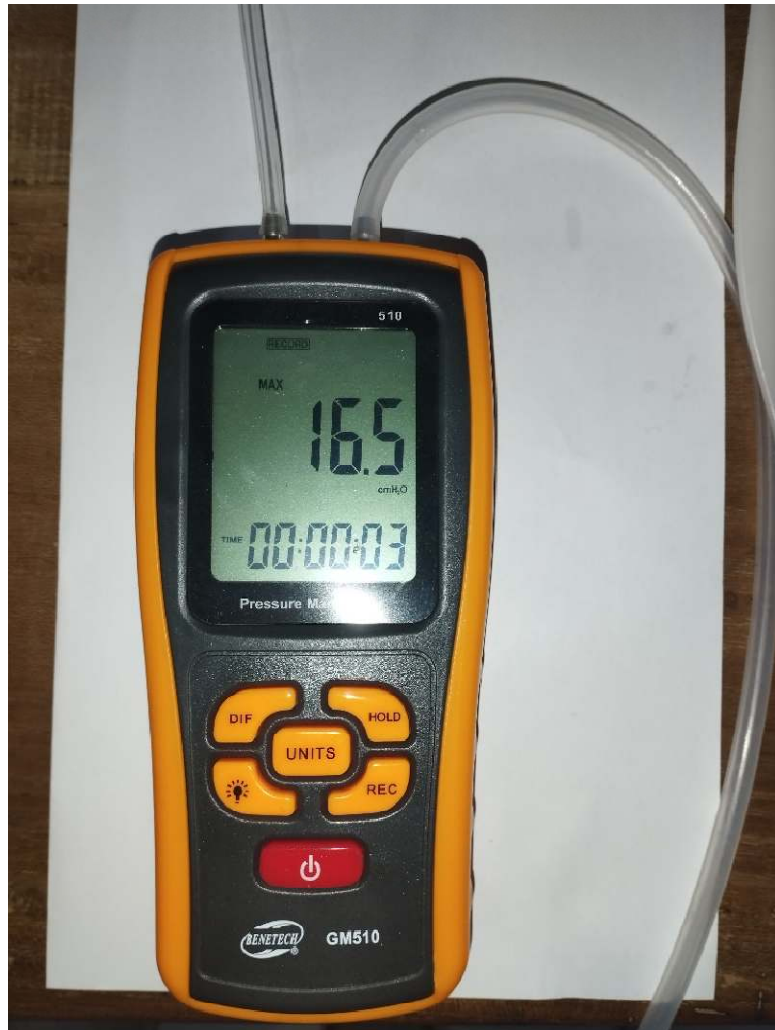
ezButton pbset(2);
ezButton pbleft(3);
ezButton pbup(4);
ezButton pbright(5);
ezButton pbdown(6);
ezButton pbok(7);

const byte highpress = 44;
bool highpresstate = LOW;
unsigned long sebelum1 = 0;
long highpresson;
long highpressoff;

const byte lowpress = 45;
bool lowpresstate = LOW;
unsigned long sebelum2 = 0;
```

```
COM3
14.28
15.05
15.83
16.16
16.49
16.60
16.38
15.72
15.38
14.72
14.50
13.50
13.06
12.95
12.51
12.29
12.06
11.73
11.29
12.62
14.17
15.05
15.61
16.16
16.49
Autoscroll Show timestamp Newline 115200 baud Clear output
```

Lampiran 4. Pengukuran PIP dengan Manometer



Lampiran 5. Tabel hasil pengukuran tidal volume dan PIP

<i>Solenoid Valve 1 On (s)</i>	Volume Udara Terukur (ml)		<i>Peak Inspiratory Pressure (cmH₂O)</i>			
	Inspirasi	Ekspirasi	PEEP valve 5 cmH ₂ O	PEEP valve 10 cmH ₂ O	PEEP valve 15 cmH ₂ O	PEEP valve 20 cmH ₂ O
0.10	50	50	2.7	5.4	9.1	11.6
0.11	60	60	2.8	5.5	9.3	11.9
0.12	70	70	2.9	5.6	9.6	12.3
0.13	85	85	3.0	5.7	9.8	12.5
0.14	90	90	3.1	5.8	10.0	12.8
0.15	100	100	3.2	5.9	10.1	13.1
0.16	115	115	3.4	6.0	10.1	13.1
0.17	130	130	3.6	6.0	10.1	13.1
0.18	140	140	3.8	6.1	10.2	13.2
0.19	145	145	3.8	6.1	10.2	13.2
0.20	160	160	3.9	6.2	10.2	13.3
0.21	170	170	3.9	6.2	10.4	13.3
0.22	180	180	4.0	6.3	10.6	13.3
0.23	195	195	4.0	6.3	10.8	13.4
0.24	205	205	4.1	6.4	11.0	13.5
0.25	215	215	4.1	6.5	11.1	13.5
0.26	225	225	4.1	6.6	11.2	13.6
0.27	235	235	4.1	6.7	11.2	13.7
0.28	245	245	4.1	6.8	11.2	13.8
0.29	255	255	4.2	6.9	11.3	13.9
0.30	265	265	4.2	7.0	11.3	14.0
0.31	275	275	4.2	7.1	11.4	14.1
0.32	285	285	4.2	7.1	11.5	14.1
0.33	295	295	4.2	7.2	11.7	14.2
0.34	310	310	4.3	7.4	11.9	14.3
0.35	315	315	4.4	7.6	12.3	14.4
0.36	325	325	4.5	7.8	12.3	14.5
0.37	330	330	4.6	8.0	12.3	14.6
0.38	335	335	4.7	8.2	12.3	14.8
0.39	345	345	4.7	8.2	12.3	14.8
0.40	355	355	4.7	8.2	12.3	14.8
0.41	365	365	4.7	8.2	12.3	14.8
0.42	380	380	4.7	8.2	12.3	14.8
0.43	400	400	4.7	8.2	12.3	14.8
0.44	420	420	4.7	8.2	12.3	14.8

Lanjutan lampiran 5

Solenoid Valve 1 On (s)	Volume Udara Terukur (ml)		<i>Peak Inspiratory Pressure (cmH₂O)</i>			
	Inspirasi	Ekspirasi	PEEP valve 5 cmH ₂ O	PEEP valve 10 cmH ₂ O	PEEP valve 15 cmH ₂ O	PEEP valve 20 cmH ₂ O
0.45	440	435	4.8	8.2	12.4	15.0
0.46	455	450	4.8	8.2	12.5	15.1
0.47	465	460	4.8	8.2	12.5	15.1
0.48	475	475	4.8	8.2	12.6	15.1
0.49	480	480	4.8	8.2	12.6	15.1
0.50	490	485	4.8	8.3	12.6	15.1
0.51	505	500	4.9	8.3	12.6	15.1
0.52	515	515	5.0	8.4	12.6	15.1
0.53	530	525	5.1	8.4	12.6	15.1
0.54	545	545	5.2	8.5	12.6	15.1
0.55	565	465	5.3	8.6	12.6	15.1
0.56	575	475	5.3	8.7	12.6	15.1
0.57	585	480	5.3	8.8	12.6	15.1
0.58	590	490	5.3	8.9	12.6	15.1
0.59	610	605	5.3	9.0	12.8	15.2
0.60	620	620	5.4	9.0	13.0	15.3
0.61	630	625	5.4	9.0	13.2	15.4
0.62	650	645	5.5	9.0	13.2	15.4
0.63	665	665	5.5	9.0	13.2	15.4
0.64	675	670	5.6	9.0	13.2	15.4
0.65	685	685	5.6	9.0	13.3	15.5
0.66	700	690	5.6	9.0	13.4	15.6
0.67	715	710	5.6	9.0	13.5	15.7
0.68	725	720	5.7	9.0	13.6	15.7
0.69	740	740	5.7	9.0	13.6	15.7
0.70	750	745	5.7	9.1	13.6	15.8
0.71	765	760	5.9	9.1	13.6	15.9
0.72	775	770	5.9	9.1	13.7	16.1
0.73	785	780	5.9	9.2	13.7	16.2
0.74	805	805	5.9	9.2	13.7	16.3

Lampiran 6. Tabel hasil pengukuran PEEP

Volume Udara Terukur (ml)	<i>Positif end Expiratory Pressure (cmH₂O)</i>			
	PEEP Valve 5 cmH ₂ O	PEEP Valve 10 cmH ₂ O	PEEP Valve 15 cmH ₂ O	PEEP Valve 20 cmH ₂ O
50	0.9	2.9	6.3	7.6
60	0.9	2.9	6.4	7.9
70	0.9	3.0	6.5	8.3
85	1.0	3.1	6.7	8.6
90	1.0	3.1	6.9	8.8
100	1.0	3.1	7.0	9.2
115	1.1	3.2	7.0	9.2
130	1.1	3.2	7.0	9.2
140	1.1	3.3	7.1	9.3
145	1.1	3.3	7.1	9.3
160	1.1	3.3	7.1	9.3
170	1.1	3.3	7.1	9.3
180	1.1	3.3	7.2	9.3
195	1.1	3.3	7.2	9.3
205	1.1	3.3	7.2	9.3
215	1.1	3.3	7.2	9.3
225	1.1	3.3	7.2	9.3
235	1.1	3.3	7.2	9.3
245	1.1	3.3	7.3	9.3
255	1.1	3.3	7.3	9.4
265	1.1	3.3	7.3	9.4
275	1.1	3.3	7.3	9.4
285	1.1	3.3	7.3	9.4
295	1.1	3.4	7.5	9.5
310	1.1	3.5	7.7	9.5
315	1.1	3.6	7.7	9.5
325	1.1	3.7	7.7	9.5
330	1.1	3.8	7.7	9.5
335	1.1	3.8	7.7	9.5
345	1.1	3.8	7.7	9.5
355	1.1	3.8	7.7	9.5
365	1.1	3.8	7.7	9.5
380	1.1	3.8	7.7	9.5
400	1.1	3.8	7.7	9.5
420	1.1	3.8	7.7	9.5

Lanjutan lampiran 6

Volume Udara Terukur (ml)	<i>Positif end Expiratory Pressure (cmH₂O)</i>			
	PEEP Valve 5 cmH ₂ O	PEEP Valve 10 cmH ₂ O	PEEP Valve 15 cmH ₂ O	PEEP Valve 20 cmH ₂ O
440	1.1	3.8	7.8	9.5
455	1.1	3.8	7.8	9.5
465	1.1	3.8	7.8	9.5
475	1.1	3.8	7.8	9.5
480	1.1	3.8	7.8	9.5
490	1.1	3.8	7.8	9.5
505	1.1	3.8	7.8	9.5
515	1.1	3.8	7.8	9.5
530	1.1	3.8	7.8	9.5
545	1.1	3.8	7.8	9.5
565	1.1	3.9	7.8	9.5
575	1.1	3.9	7.8	9.5
585	1.1	3.9	7.8	9.6
590	1.1	3.9	7.8	9.7
610	1.1	3.9	7.8	9.8
620	1.1	3.9	7.8	9.9
630	1.1	3.9	7.8	9.9
650	1.1	3.9	7.9	10.0
665	1.1	3.9	7.9	10.0
675	1.1	3.9	7.9	10.0
685	1.1	3.9	7.9	10.0
700	1.1	3.9	7.9	10.0
715	1.1	3.9	7.9	10.0
725	1.1	3.9	7.9	10.0
740	1.1	3.9	7.9	10.2
750	1.1	3.9	7.9	10.4
765	1.1	3.9	7.9	10.6
775	1.1	3.9	7.9	10.8
785	1.1	3.9	7.9	10.9
805	1.1	3.9	7.9	10.9

Lampiran 7. Pengukuran PIP dan PEEP (RR dan I/E berbeda)

RR & I/E	V _T	PEEP Valve 5 cmH ₂ O		PEEP Valve 10 cmH ₂ O		PEEP Valve 15 cmH ₂ O		PEEP Valve 20 cmH ₂ O	
		PIP	PEEP	PIP	PEEP	PIP	PEEP	PIP	PEEP
10-1/1	805	6	0.4	9.5	2.2	14	6.1	16.3	8.6
10-1/2	805	5.8	0.4	9.5	1.8	13.2	5.9	16.3	8.3
10-1/3	805	5.8	0.4	9.6	2.0	13.5	5.9	16.5	7.3
10-1/4	805	6.0	0.6	9.8	2.6	13.9	6.5	16.4	7.5
10-1/5	805	5.8	0.4	9.4	2.0	13.8	6.0	16.4	7.5
20-1/1	805	5.9	1.1	9.2	3.9	13.7	7.9	16.3	10.9
20-1/2	805	6.4	1.6	9.5	3.9	13.9	8.0	16.6	10.8
20-1/3	805	6.0	1.3	9.4	3.8	13.7	8.3	16.5	10.8
20-1/4	805	6.2	1.6	9.8	4.3	14.2	8.9	16.2	10.2
20-1/5	805	6.5	1.7	9.7	4.0	14.3	8.4	16.4	10.5
30-1/1	805	5.5	1.2	9	4.6	13.4	9.7	15.9	11.7
30-1/2	805	5.7	1.8	9.1	4.9	13.5	9.8	15.8	12.3
30-1/3	805	5.9	2.4	9.6	5.4	13.7	9.7	16.2	12.4
30-1/4	805	6.1	2.6	10.0	5.8	13.8	9.9	16.1	12.5
30-1/5	805	5.9	2.6	9.6	5.6	13.3	9.1	16.1	12.2

Lampiran 8. Pengujian ventilator di BPFK



Lampiran 9. Data hasil pengujian tahap terakhir di BPFK Makassar

<i>Solenoid Valve</i> 1 On (detik)	V_T Terukur (ml)	<i>Peak Inspiratory</i> <i>Pressure</i> (cmH ₂ O)
0.10	81	5.8
0.20	235	13.3
0.30	357	17.8
0.40	409	19.1
0.50	432	20.8
0.60	599	26.6
0.70	621	34.1
0.80	638	42