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Lampiran 1 Dokumentasi alat



Tampak samping kanan (dalam)



Tampak atas (dalam)

Tampak mifi, baterai dan modul *step-up*

Tampak kanan (luar)



Lampiran 2 Listing program

```
#define BLYNK_TEMPLATE_ID "TMPL6N4TzDJx7"
#define BLYNK_TEMPLATE_NAME "Tugas Akhir"
#define BLYNK_AUTH_TOKEN "xsnvFRqa7WYCiGHbHM_Vasi9CueaRAI2"
#define BLYNK_PRINT Serial
#include <SoftwareSerial.h>
#include <ESP8266WiFi.h>
#include <BlynkSimpleEsp8266.h>
#include <ESP8266HTTPClient.h>
#include <WiFiClient.h>
#include <TinyGPS++.h>
```

```
static const int RXPin = 4, TXPin = 5;
static const uint32_t GPSBaud = 9600;
const int vibrationSensor = 2;
int vibrationSensorState = 0;
const int relaysensor = 12;
const int relaybuzzer = 13;
const int relaymifi = 14;
const int buzzer = 16;
```

```
TinyGPSPlus gps;
WidgetMap myMap(V0);
```

```
int VibrateCount = 0;
const int maxVibrateCount = 18;
```

```
SoftwareSerial mym(RXPin, TXPin);
```



```
ude, longitude;
Latitude = 0.0;
Longitude = 0.0;
```

```

bool alertSent = false;

char auth[] = "xsnvFRqa7WYCiGHbHM_Vasi9CueaRAI2";
char ssid[] = "Redmi";
char pass[] = "rtyuiop1234";

BlynkTimer timer;

String url;

WiFiClient client;

unsigned int move_index = 1;
unsigned long lastMoveTime = 0;
const unsigned long moveTimeout = 60000;
unsigned long lastVibrateTime = 0;
const unsigned long vibrateInterval = 600000;
unsigned long beforeRelay = 0;
const unsigned long intervalRelay = 3600000;
unsigned long beforeGps = 0;
const unsigned long intervalGps = 1000;

bool RelayStatus = true;

void setup()
{
  Serial.begin(115200);
  pinMode(vibrationSensor, INPUT);
  pinMode(buzzer, OUTPUT);
  digitalWrite(relaysensor, LOW);
  digitalWrite(relaybuzzer, HIGH);
  Serial.begin(GPSBaud);

```



```

    Blynk.begin(auth, ssid, pass);
    timer.setInterval(5000L, checkGPS);
}

void checkGPS()
{
    if (gps.charsProcessed() < 10)
    {
        Serial.println(F("No GPS detected: check wiring."));
    }
}

void postData()
{
    int httpCode;
    HTTPClient http;
    http.begin(client, url);
    int httpResponCode = http.GET();
    httpCode = http.POST(url);
    Serial.println(httpResponCode);
    http.end();
}

void kirim_wa(String pesan)
{
    url = "http://api.callmebot.com/whatsapp.php?phone=6282189126424&text=" +
    urlencode(pesan) + "&apikey=5249381";
    postData();
}

```



```

String urlencode(String str)
{
    String encodedString = "";
    char c;
    for (int i = 0; i < str.length(); i++)
    {
        c = str.charAt(i);
        if (c == ' ')
        {
            encodedString += "+";
        }
        else if (isalnum(c))
        {
            encodedString += c;
        }
    }
    Serial.println(encodedString);
    return encodedString;
}

void mifi_charge()
{
    unsigned long nowRelay = millis();
    if (nowRelay - beforeRelay > intervalRelay)
    {
        RelayStatus = !RelayStatus;
        if (RelayStatus)
        {
            digitalWrite(relaymifi, HIGH);
            Serial.println("Mi-Fi Charging...");
        }
    }
}

```



```

else
{
    digitalWrite(relaymifi, LOW);
    Serial.println("Mi-Fi Uncharge.");
}
beforeRelay = nowRelay;
}
}

void gpsInfo(){
    unsigned long nowGps = millis();
    if (nowGps - beforeGps > intervalGps)
    {
        if (gps.location.isValid())
        {
            latitude = gps.location.lat();
            longitude = gps.location.lng();

            Serial.print("LAT: ");
            Serial.println(latitude, 6);
            Serial.print("LONG: ");
            Serial.println(longitude, 6);

            Blynk.virtualWrite(V1, String(latitude, 6));
            Blynk.virtualWrite(V2, String(longitude, 6));
            myMap.location(move_index, latitude, longitude, "GPS_Location");

            float distance = calculateDistance(prevLatitude, prevLongitude, latitude,
            longitude);

```



```

            distance >= 60.0 && !alertSent)

```

```

            n_wa("CPU Komputer Anda dalam Bahaya Pencurian");

```

```

        alertSent = true;
    }

    if (distance < 60.0 && alertSent)
    {
        alertSent = false;
    }

    prevLatitude = latitude;
    prevLongitude = longitude;

    lastMoveTime = nowGps;
}

}

if (nowGps - lastMoveTime > moveTimeout && !alertSent)
{
    Serial.println("Perangkat berhenti bergerak.");
}

beforeGps = nowGps;
Serial.println();
}

float calculateDistance(float lat1, float lon1, float lat2, float lon2)
{
    float R = 6371000.0;
    float dLat = radians(lat2 - lat1);
    float dLon = radians(lon2 - lon1);
    float a = sin(dLat / 2.0) * sin(dLat / 2.0) + cos(radians(lat1)) * cos(radians(lat2))
    * sin(dLon / 2.0) * sin(dLon / 2.0);
    float c = 2.0 * atan2(sqrt(a), sqrt(1.0 - a));
    return R * c;
}

```



```

float distance = R * c;

return distance;
}

void vibrate_cond(){
    unsigned long nowVibrate = millis();
    if (vibrationSensorState == HIGH) {
        delay(100);
        if (vibrationSensorState == HIGH) {
            VibrateCount++;
            Serial.print("Getaran: ");
            Serial.println(VibrateCount);
            lastVibrateTime = nowVibrate;
        }
    }

    if (nowVibrate - lastVibrateTime > vibrateInterval) {
        if (VibrateCount >= maxVibrateCount) {
            kirim_wa("CPU Komputer Anda dalam Bahaya Pencurian");
        }
        VibrateCount = 0;
        lastVibrateTime = nowVibrate;
    }

    if (nowVibrate - lastVibrateTime > 60000) {
        VibrateCount = 0;
        lastVibrateTime = nowVibrate;
    }
}

```



```
void loop()
{
  while (mym.available() > 0)
  {
    if (gps.encode(mym.read()))
      gpsInfo();
  }

  Blynk.run();
  timer.run();

  vibrate_cond();

  tone(buzzer, 6000, 250);

  mifi_charge();
}
```



Lampiran 3 Biaya

No	Nama Barang	Jumlah	Satuan	Harga	Total
1	NodeMCU ESP8266	1	Pcs	Rp31.300,-	Rp31.300,-
2	GPS Ublox Neo-6MV2	1	Pcs	Rp44.900,-	Rp44.900,-
3	Sensor Getar SW-420	1	Pcs	Rp6.000,-	Rp6.000,-
4	Relay 4-Channel	1	Pcs	Rp19.900,-	Rp19.900,-
5	Buzzer SFM-27	1	Pcs	Rp5.700,-	Rp5.700,-
6	Mifi Orion Bolt 4G	1	Pcs	Rp175.000,-	Rp175.000,-
7	Baterai Li-Ion 18650	2	Pcs	Rp15.000,-	Rp30.000,-
8	Holder 2 Baterai	1	Pcs	Rp20.000,-	Rp20.000,-
9	Modul TP4056	1	Pcs	Rp3.000,-	Rp3.000,-
10	Step-up MT3608	1	Pcs	Rp5.900,-	Rp5.900,-
11	PCB 5x7 cm	1	Pcs	Rp1.300,-	Rp1.300,-
12	Solder Listrik	1	Pcs	Rp18.950,-	Rp18.950,-
13	Timah Solder 1 m	2	Pcs	Rp7.500,-	Rp15.000,-
14	Breadboard	2	Pcs	Rp9.700,-	Rp19.400,-
15	Kabel Jumper Male to Female	20	Pcs	Rp50,-	Rp10.000,-
16	Kabel Jumper Male to Male	10	Pcs	Rp50,-	Rp5.000,-
17	Langganan Blynk	1	Bulan	Rp109.890,-	Rp109.890,-
18	Kartu SIM Pascabayar	1	Bulan	Rp80.000,-	Rp80.000,-
Total Biaya Keseluruhan					Rp601.240,-

