

DAFTAR PUSTAKA

- Ali, H., Ideris, N. S. M., Zaidi, A. F. A., Azalan, M. S. Z., Amran, T. S. T., Ahmad, M. R., Rahim, N. A., & Shukor, S. A. A. 2021. Ground Penetrating Radar for Buried Utilities Detection and Mapping: A Review. *Journal of Physics*.
- Angelopoulos, M., Redman, D., Pollard, W. H., Haltigin, T. W., & Dietrich, P. 2014. Lunar Ground Penetrating Radar: Minimizing Potential Data Artifacts Caused by Signal Interaction with a Rover Body. *Advances in Space Research*, 54.
- Arief, M., & Lena, S. 2021. Penggunaan Metode Ground Penetrating Radar untuk Identifikasi Utilitas Bawah Permukaan. *Prisma Fisika*, 9.
- Bachiri, T., Alsharahi, G., Khamlichi, A., Bezzazi, M., & Faize, A. 2020. GPR application in Civil Engineering to search and detect underground Networks. *International Journal of Emerging Trends in Engineering Research*, 8.
- Bahri, A.S. 2009. Penentuan Karakteristik Dinding Gua Seropan Gunungkidul dengan Metode Ground Penetrating Radar. Institut Teknologi Sepuluh Nopember. Diakses pada 23 September 2022 dari <http://digilib.its.ac.id/public/ITS-Undergraduate-12481-penentuan-karakteristik-dinding-gua-seropan-gunungkidul-dengan-metode-ground-penetrating-radar>.
- BPS Kota Bandung. 2021. Kota Bandung Dalam Angka 2021. Bandung: Badan Pusat Statistik Kota Bandung.
- Bemmelen, R. W. V. 1949. *The Geology of Indonesia Vol. 1A*. The Hague: Government Printing Office.
- Benson, A. K. 1995. Applications of Ground Penetrating Radar in Assessing Some Geological Hazards: Examples of Groundwater Contamination, Faults, Cavities. *Journal of Applied Geophysics*. 33.
- Gabrys, M., & Ortyl, L. 2020. Georeferencing of Multi-Channel GPR-Accuracy and Efficiency of Mapping of Underground Utility Networks. *Remote Sensing*, 12.
- Gergan, J. T., & Thayyen, R. J. 2006. Ice Thickness and Subglacial Topography Studies by Ground Penetrating Radar during the XX Indian Antarctic Expedition. Twentieth Indian Expedition to Antarctica, Scientific Report, 2006 Ministry of Earth Sciences, Technical Publication No. 18
- Hilman, M. 2004. Perkembangan Lokasi Perumahan di Wilayah Gedebage Kota Bandung Akibat Pemekaran Kota. *Dimensi Teknik Arsitektur*, 32.
- Hirose, A., & Lonngren, K. E. 1985. *Introduction to Wave Phenomena*. London: Willey-Blackwell.

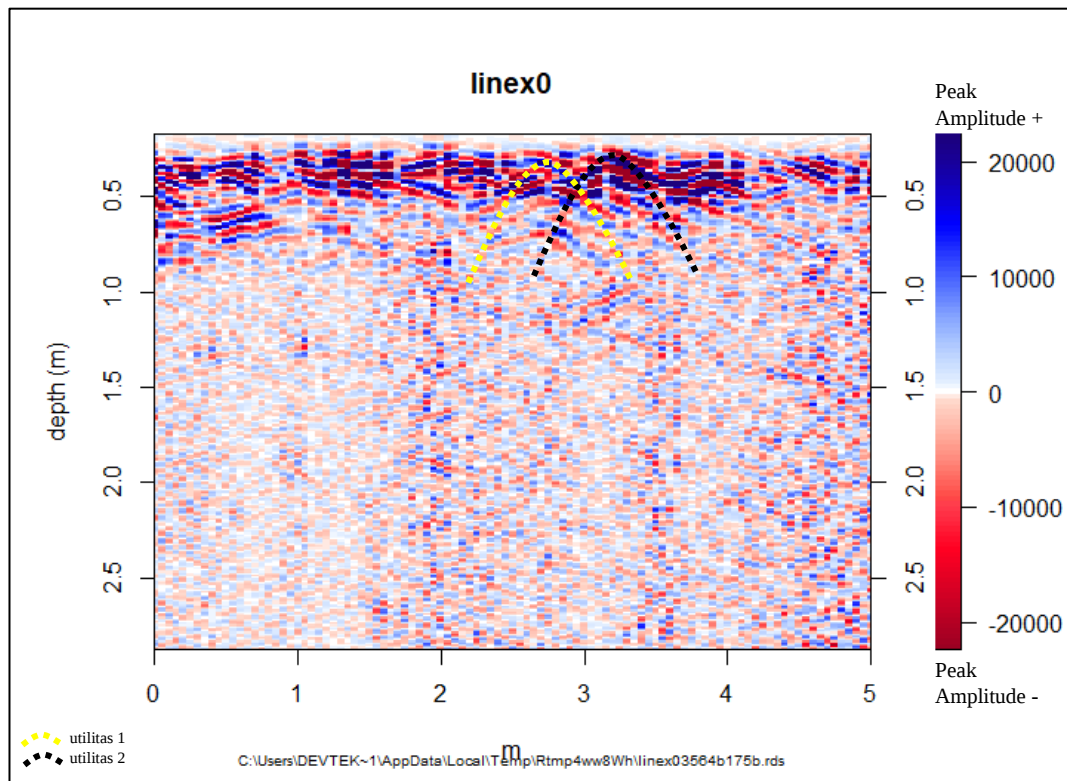
- Hubber, E., & Hans, G. 2018. RGPR – An open-source package to process and visualize GPR data. Submitted to the 17th International Conference on Ground Penetrating Radar. Switzerland: June 18-21.
- Hugenschmidt, J., & Mastrangelo, R. (2006). GPR inspection of concrete bridges. *Cement and Concrete Composites*, 28(4), 384-392.
- Jol, H. M. 2009. *Ground Penetrating Radar: Theory and Applications*. Oxford: Elsevier.
- Kemen PUPR. 2016. *Peningkatan Kualitas Lingkungan Perumahan dan Penyediaan PSU*. Bandung: Kementerian Pekerjaan Umum dan Perumahan Rakyat.
- Ko, K. H., Jang, G., Park, K., & Kim, K. 2012. GPR-Based Landmine Detection and Identification Using Multiple Features. *International Journal of Antennas and Propagation*. 2012.
- Komarudin. 1999. *Pembangunan Perkotaan Berwawasan Lingkungan*. Jakarta: Direktorat Jenderal Cipta Karya Departemen Pekerjaan Umum.
- Liu, X., Dong, X., & Leskovar, D. L. 2016. Ground Penetrating Radar for Underground Sensing in Agriculture: A Review. *International Agrophysics*, 30.
- Luga, A. L., Muliadi, M. M., & Ivansyah, O. (2019). Identifikasi Pipa Metal Bawah Permukaan Menggunakan Metode Ground Penetrating Radar (GPR). *PRISMA FISIKA*, 7(1), 20-29.
- Milsom, J. 2003. *Field Geophysics Third Edition*. London: Willey-Blackwell.
- Pemerintah Indonesia. 2011. *Undang-Undang Republik Indonesia Nomor 1 Tahun 2011 Tentang Perumahan dan Kawasan Permukiman*. Sekretariat Negara. Jakarta.
- Reitz, J. R., Milford, F. J. & Chrsty, R. W. 1979. *Foundation of Electromagnetic Theory Third Edition*. Boston: Addison-Wesley Publishing Company Inc.
- Reynolds, J. M. 2011. *An Introduction to Applied and Environmental Geophysics*. London: Willey-Blackwell.
- Ruwanto, B. 2007. *Asas-Asas Fisika*. Bogor: Yudhistira.
- Silitonga, P. H. 1973. *Peta Geologi Bersistem, Jawa*. Bandung: Pusat Penelitian dan Pengembangan Geologi.
- Sinharay, R. K. 2019. Applications and Future of Ground Penetrating Radar (GPR) as A Near-Surface Geophysical Technique : A Review. *Journal of Engineering Geology*, 44.

- Tamura, L. N., Almeida, R. P., Taioli, F., Marconato., & Janikian, L. 2016. Ground Penetrating Radar Investigation of Depositional Architecture: The Sao Sebastiao and Marizal Formations in The Cretaceous Tucano Basin (Northeastern Brazil). *Brazilian Journal of Geology*, 46.
- Venables, W. N., & Smith D. M. (2022, April 22). An Introduction to R Version 4.2.0. Retrived July 21, 2022, from <https://cran.r-project.com>.
- William, S. L., Banks., & Johnson C. D. 2011. Collecting, Processing, and Interpretation of Ground Penetrating Radar Data to Determine Sediment Thickness at Selected Locations in Deep Creek Lake, Garrett County, Maryland, 2007. Virginia: U.S. Geological Survey.
- Zhai, J., Wang, Q., Wang, H., Xie, X., Zhou, M., Yuan, D., & Zhang, W. 2022. Highway Tunnel Defect Detection Based on Mobile GPR Scanning. *Applied Science*. 12.

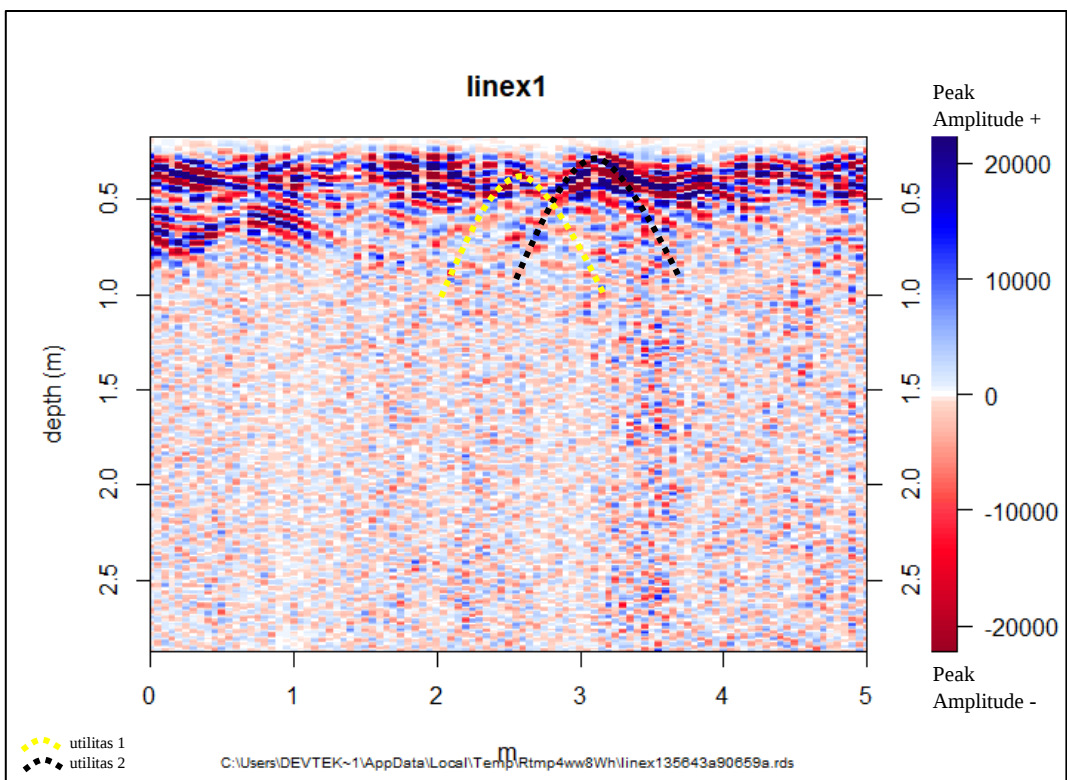
LAMPIRAN

Lampiran 1: Hasil Interpretasi Seluruh Lintasan

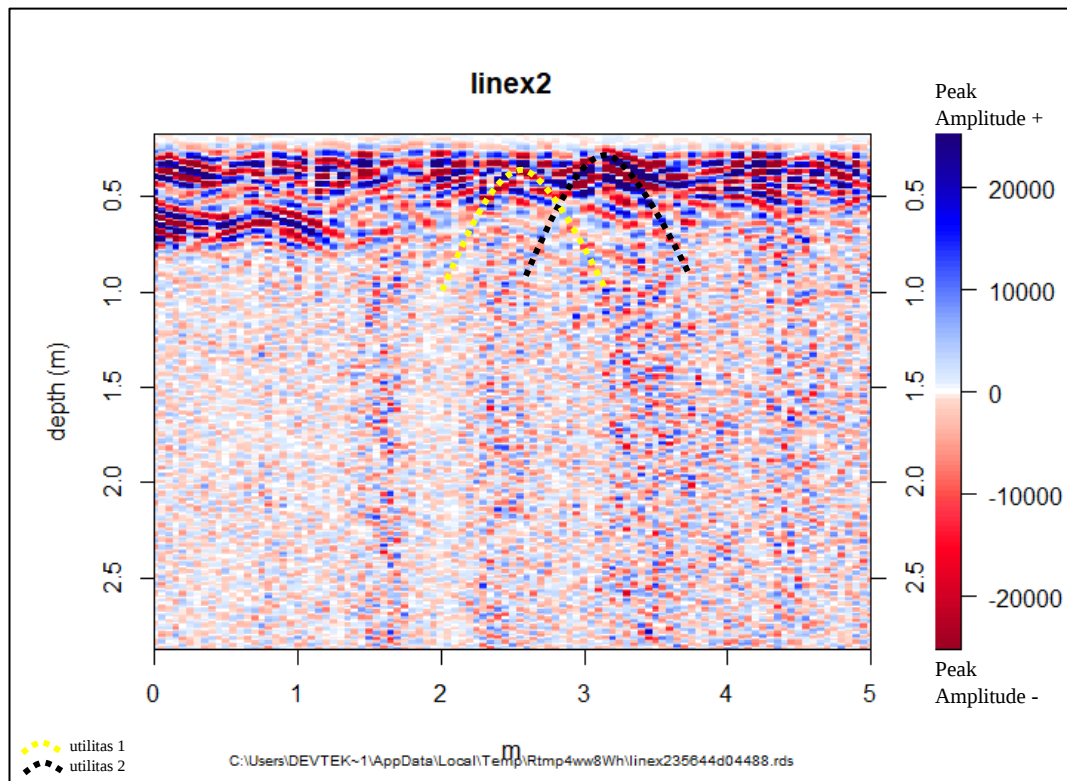
Lintasan 0 sumbu X



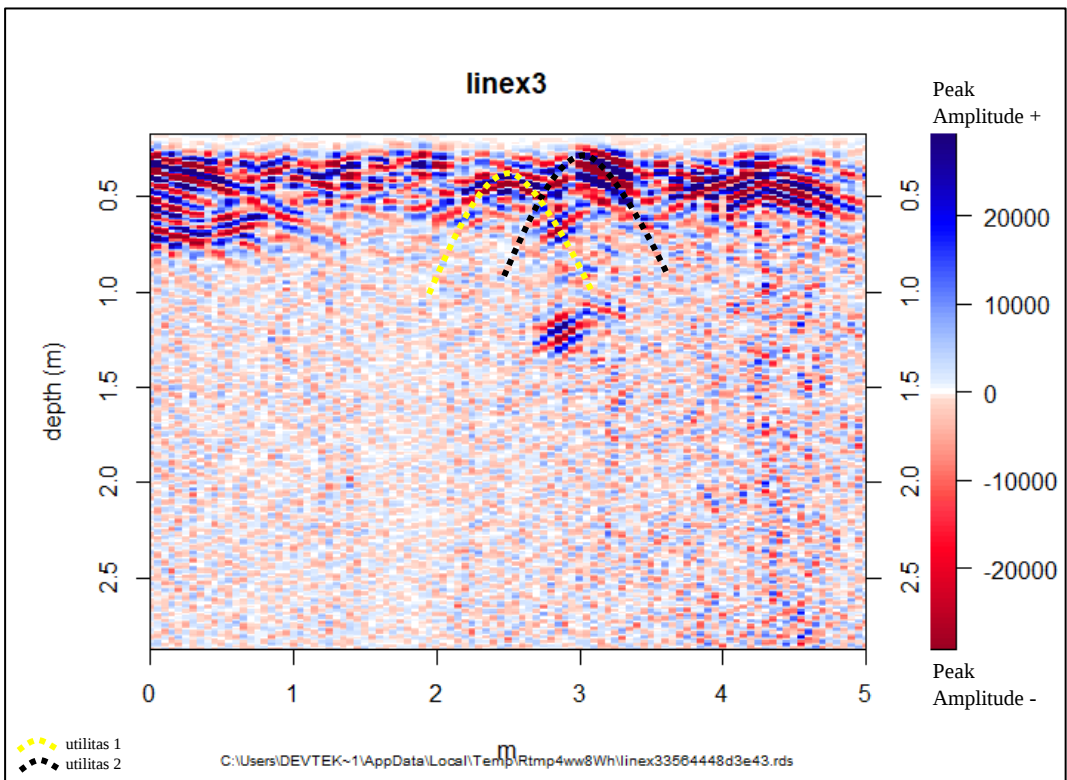
Lintasan 1 sumbu X



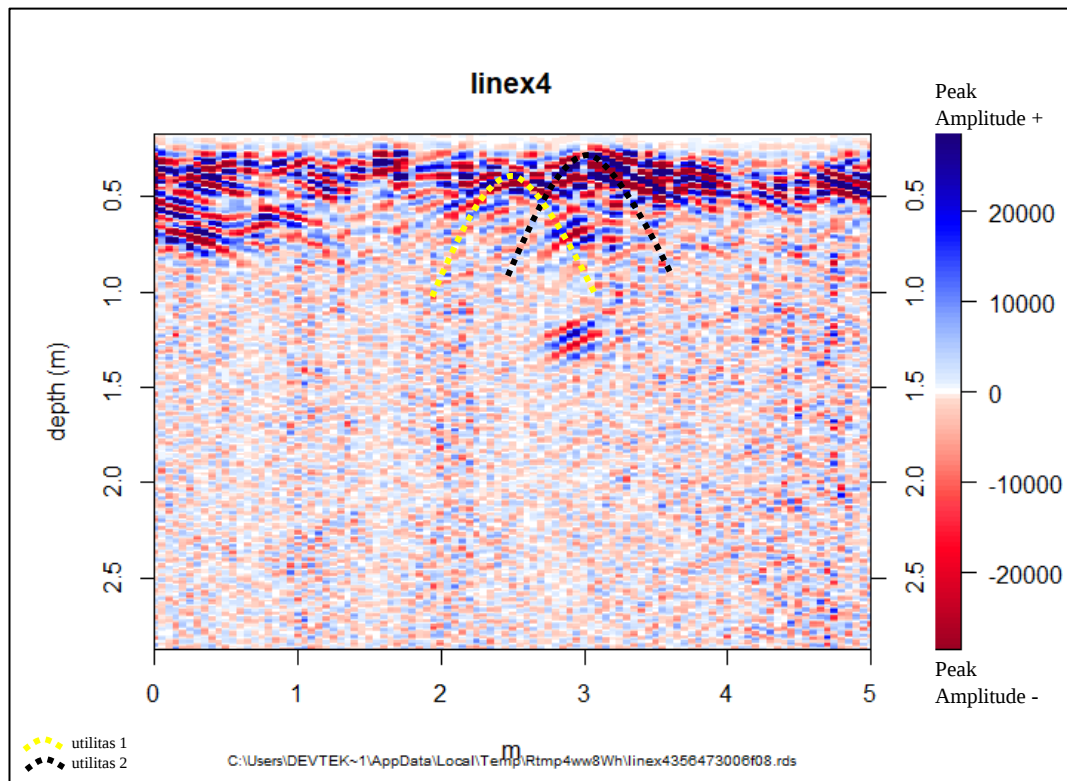
Lintasan 2 sumbu X



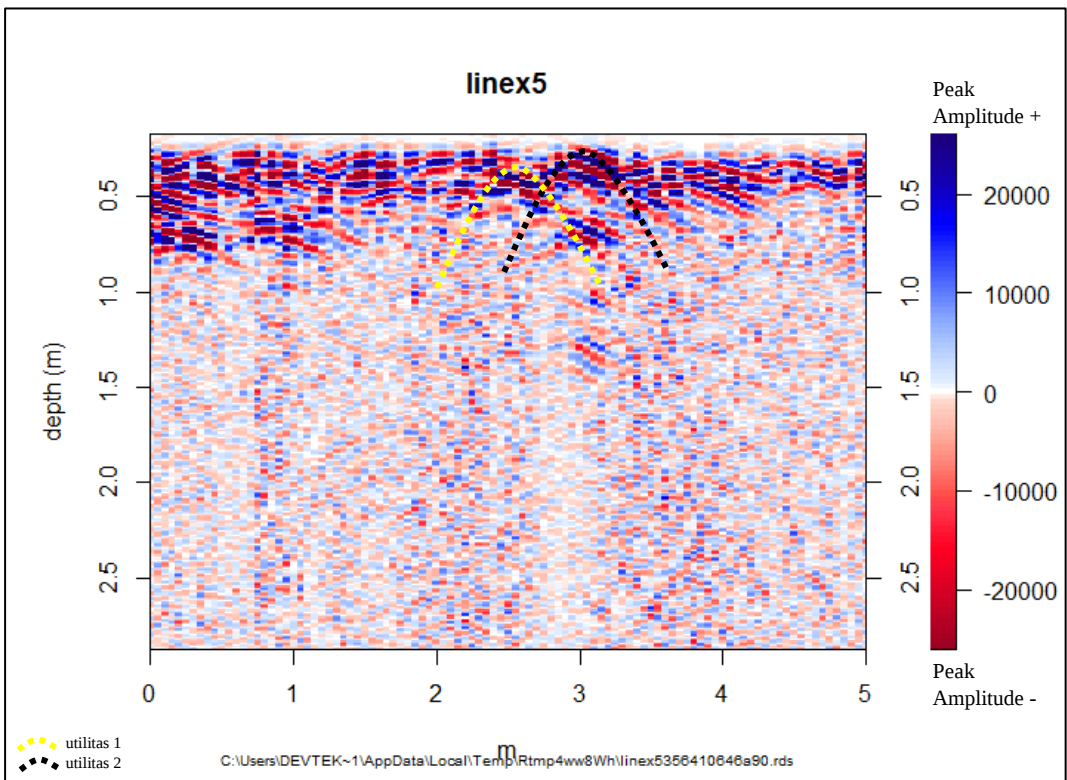
Lintasan 3 sumbu X



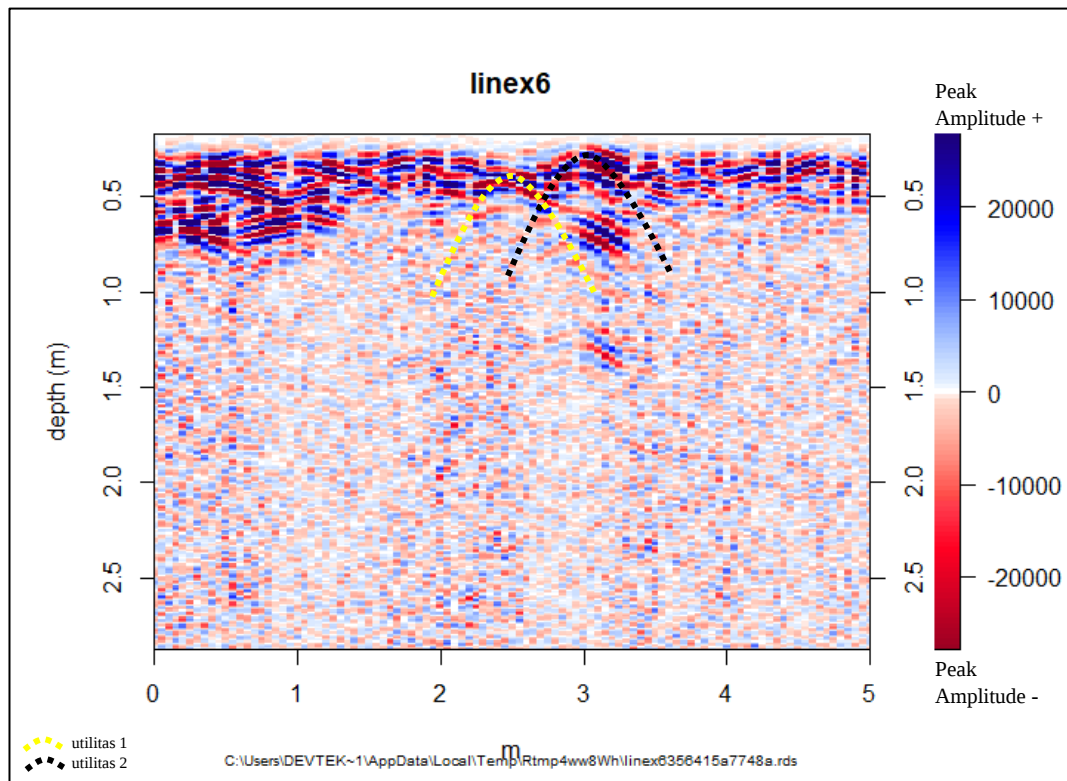
Lintasan 4 sumbu X



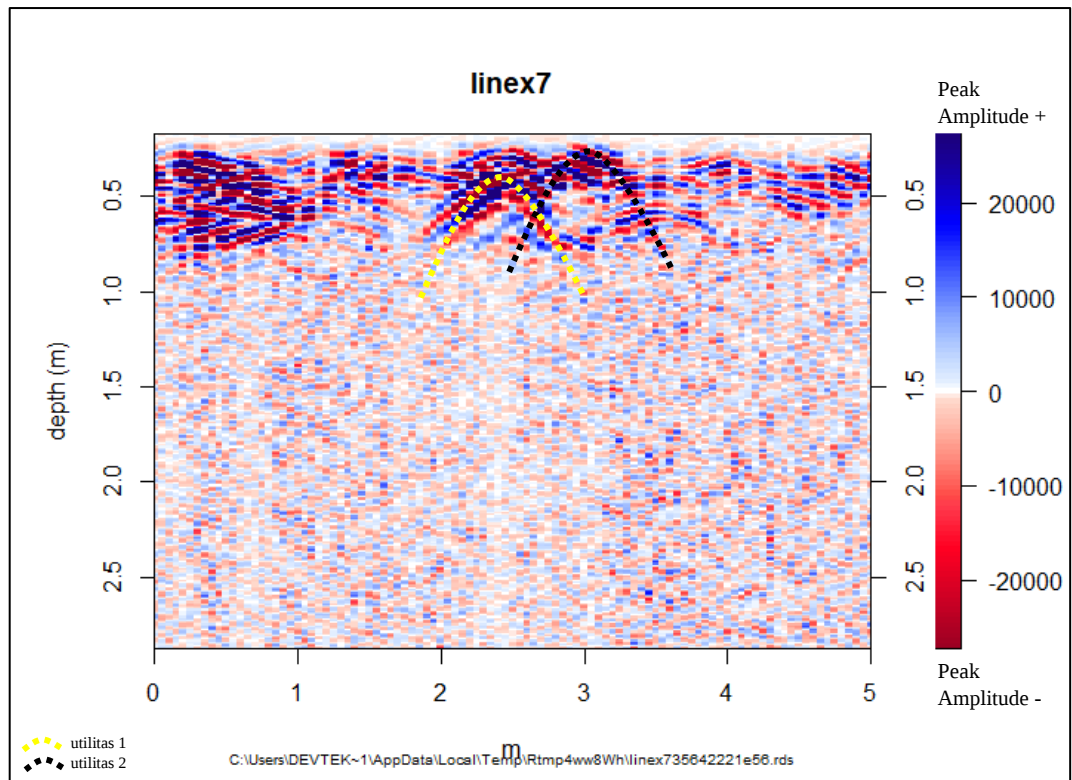
Lintasan 5 sumbu X



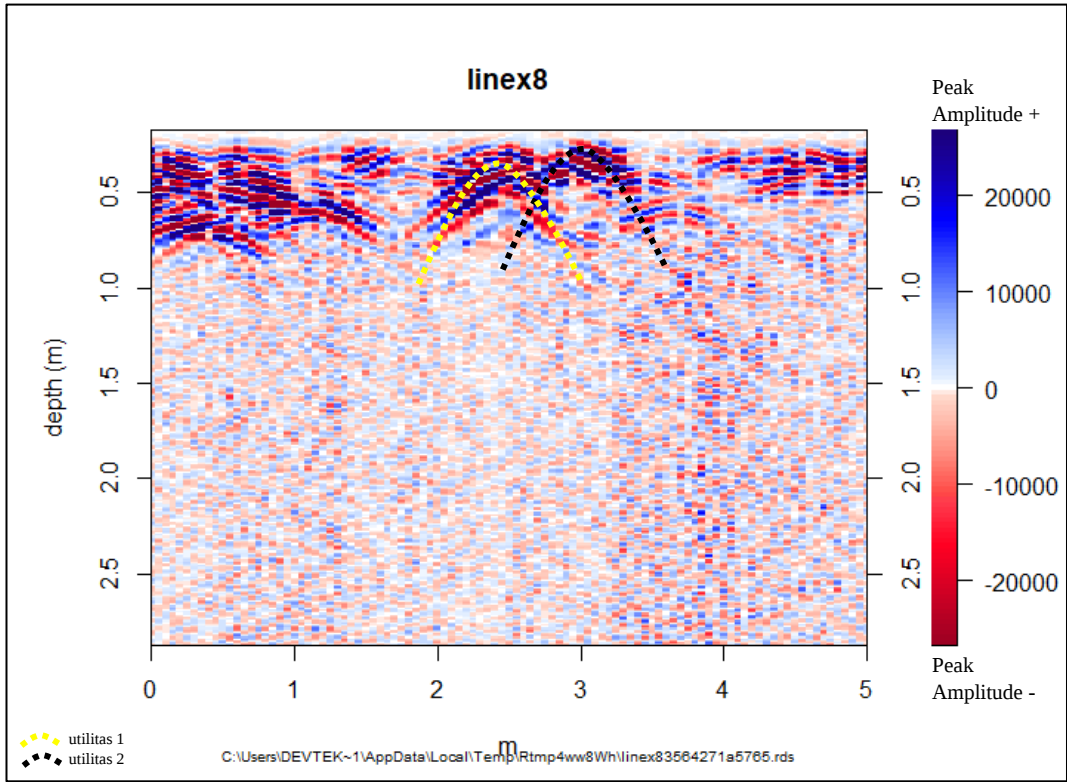
Lintasan 6 sumbu X



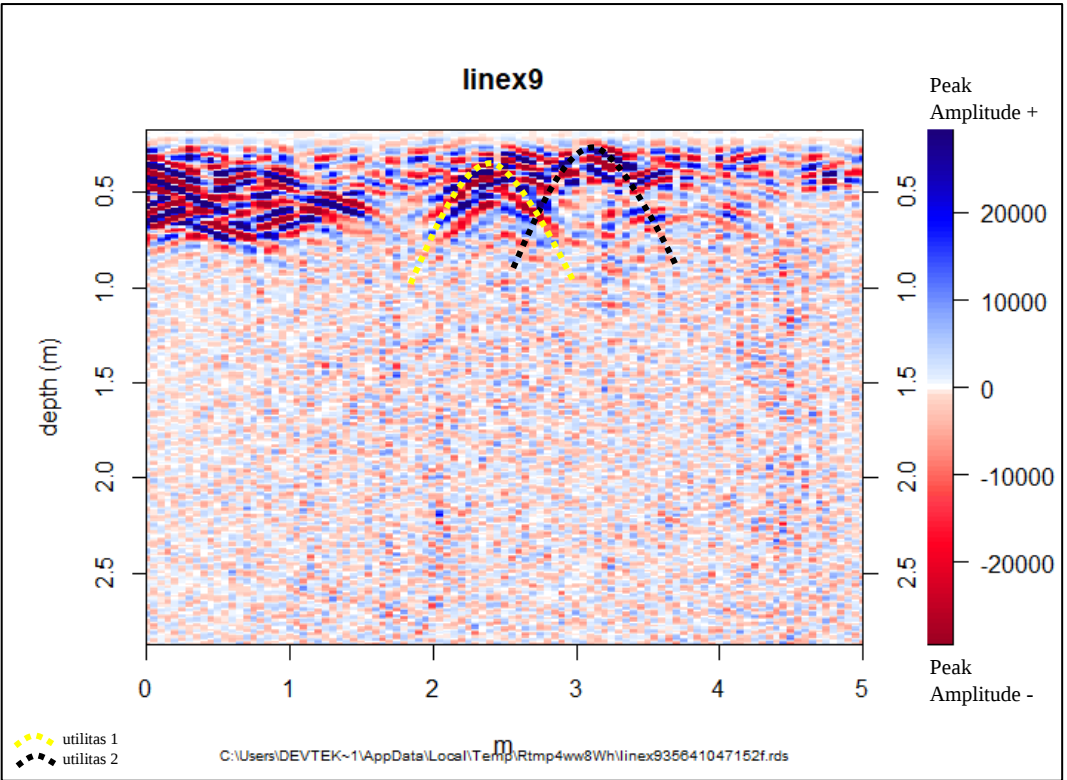
Lintasan 7 sumbu X



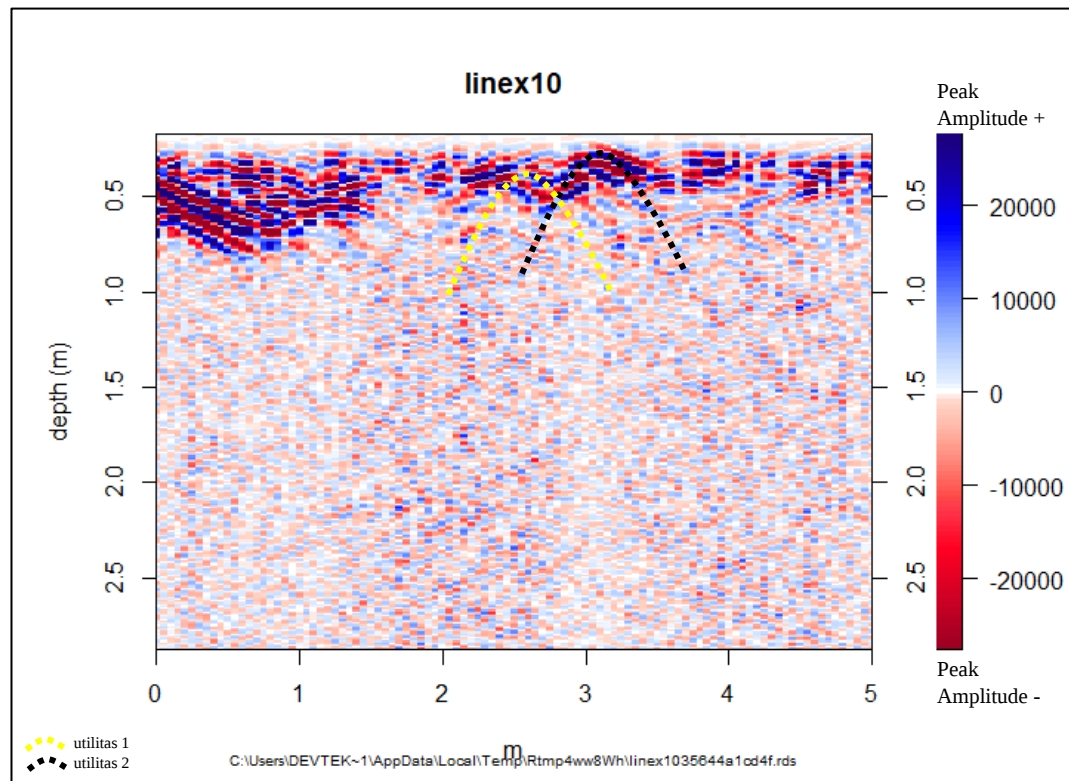
Lintasan 8 sumbu X



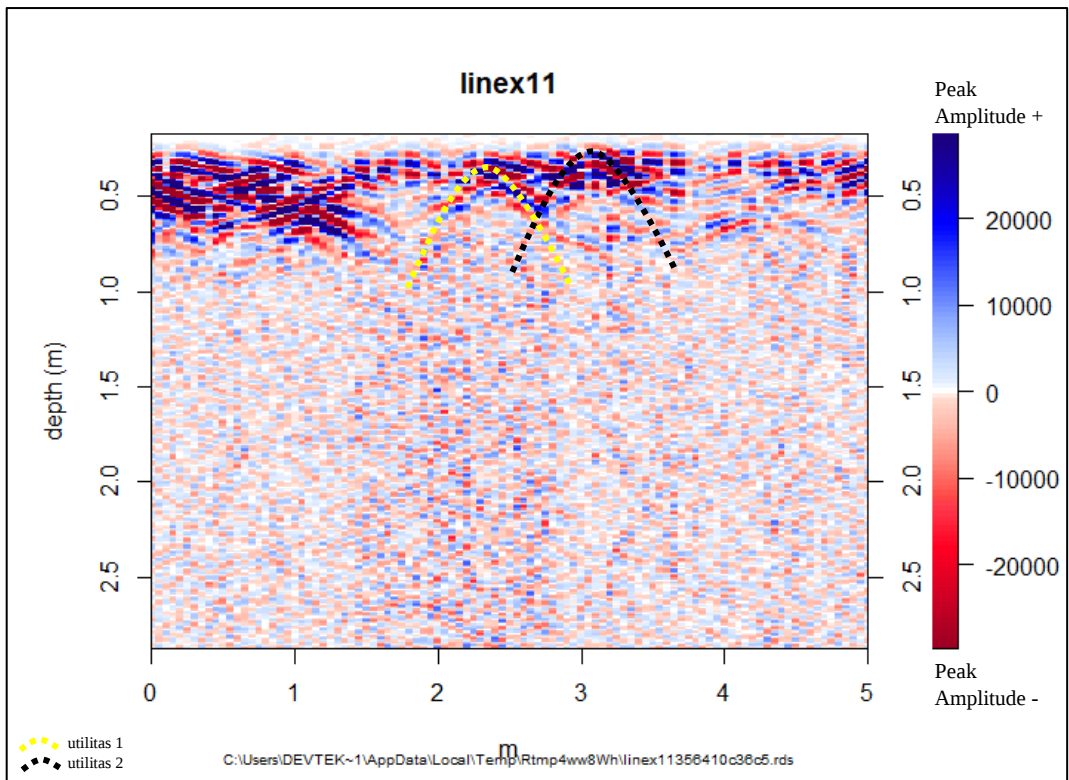
Lintasan 9 sumbu X



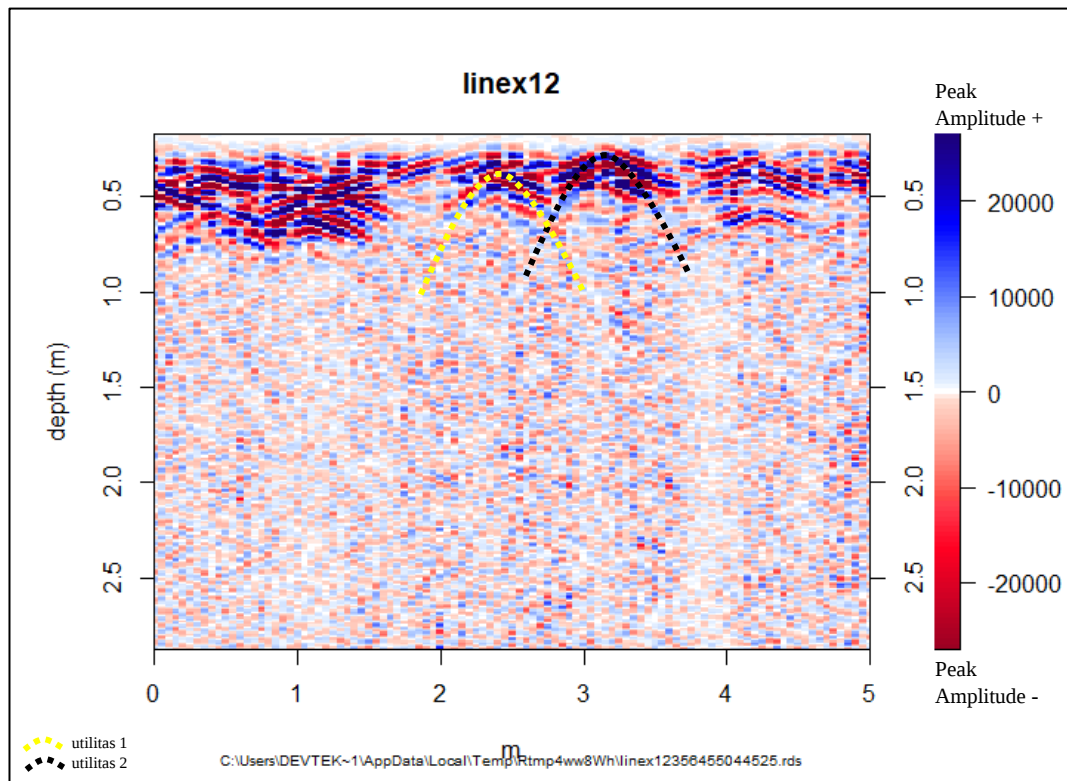
Lintasan 10 sumbu X



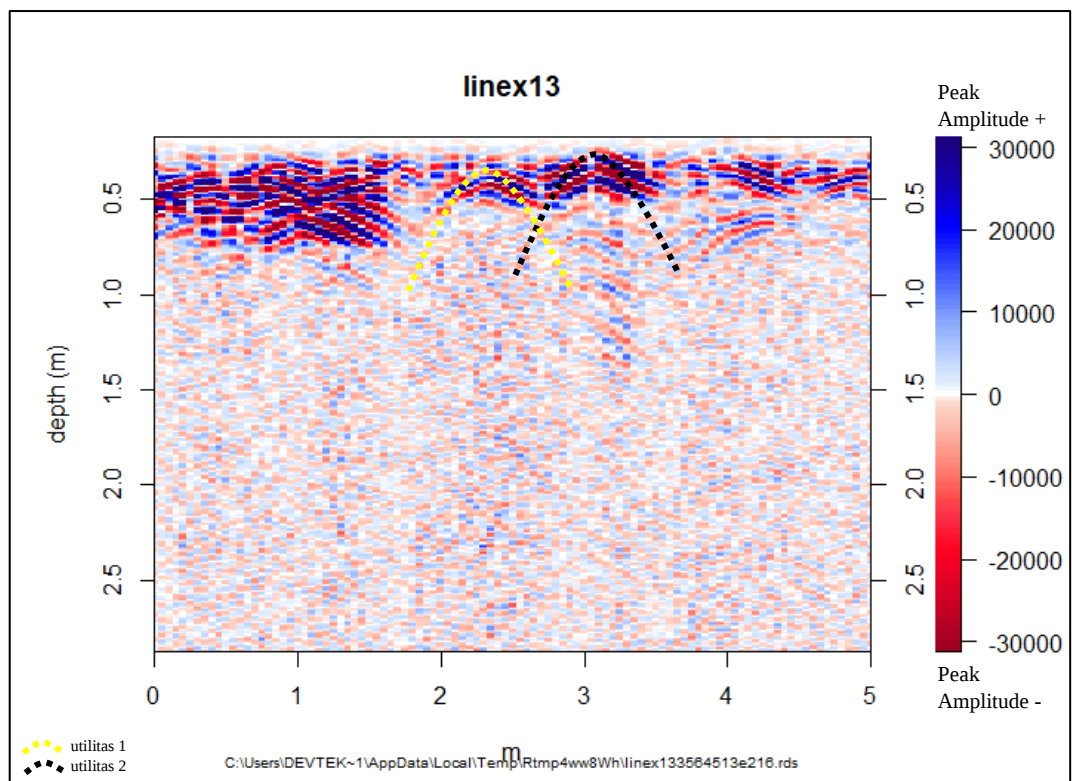
Lintasan 11 sumbu X



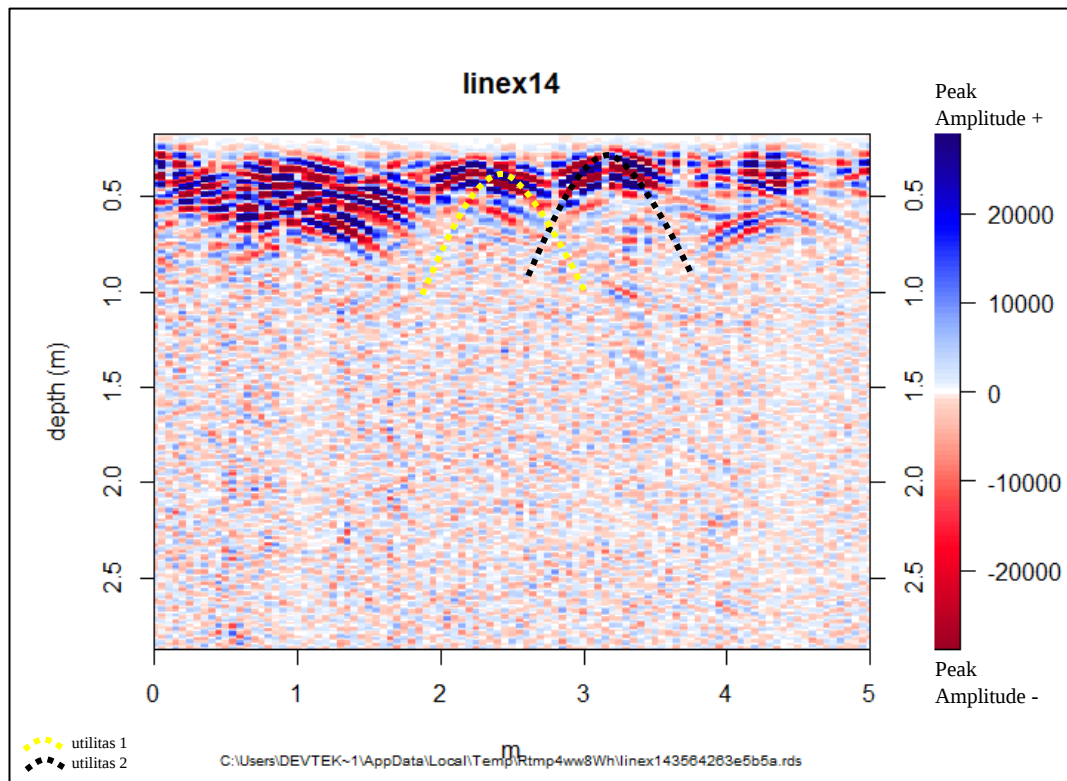
Lintasan 12 sumbu X



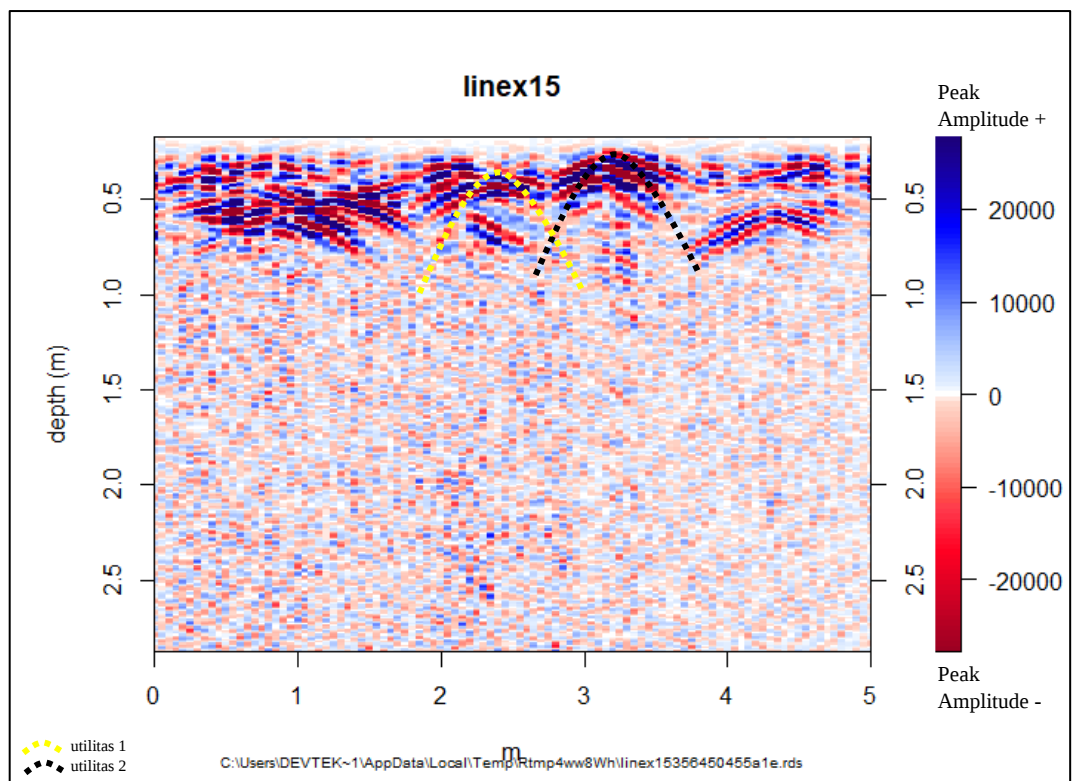
Lintasan 13 sumbu X



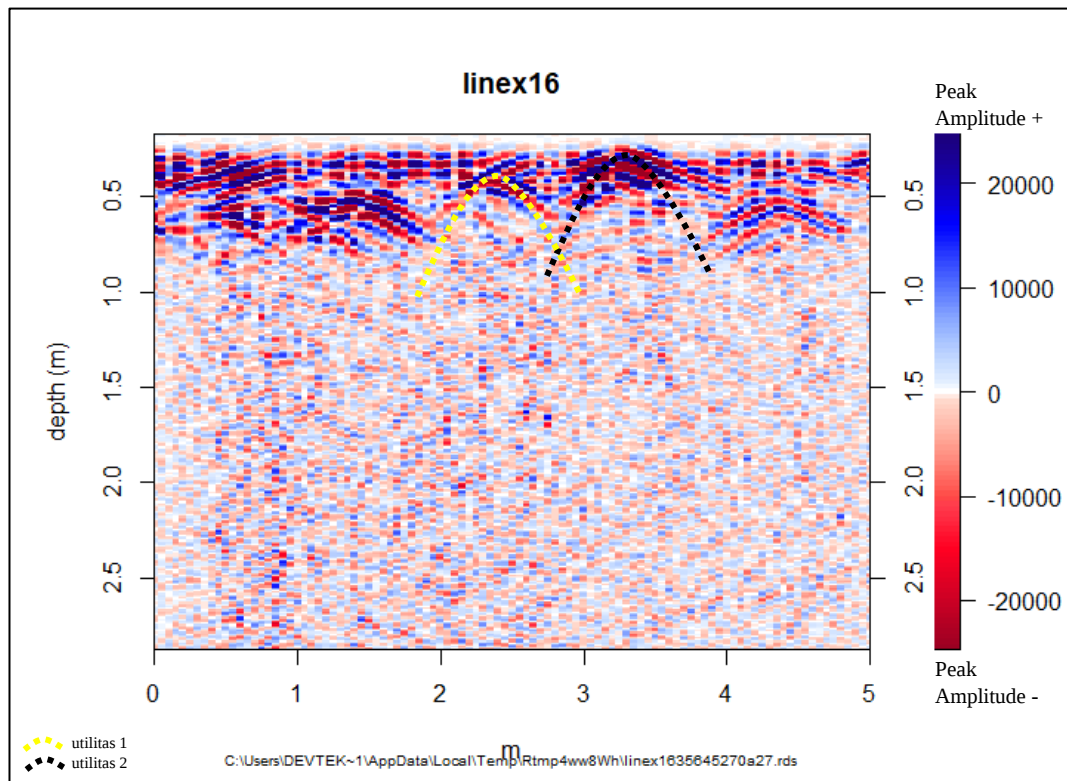
Lintasan 14 sumbu X



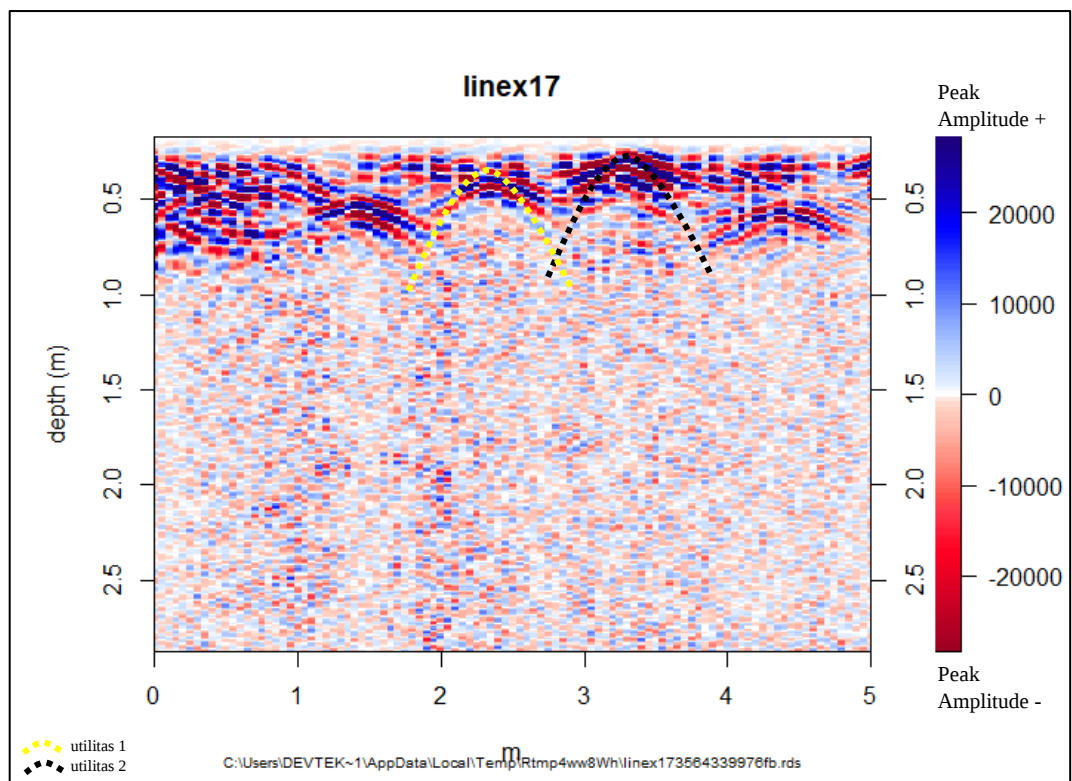
Lintasan 15 sumbu X



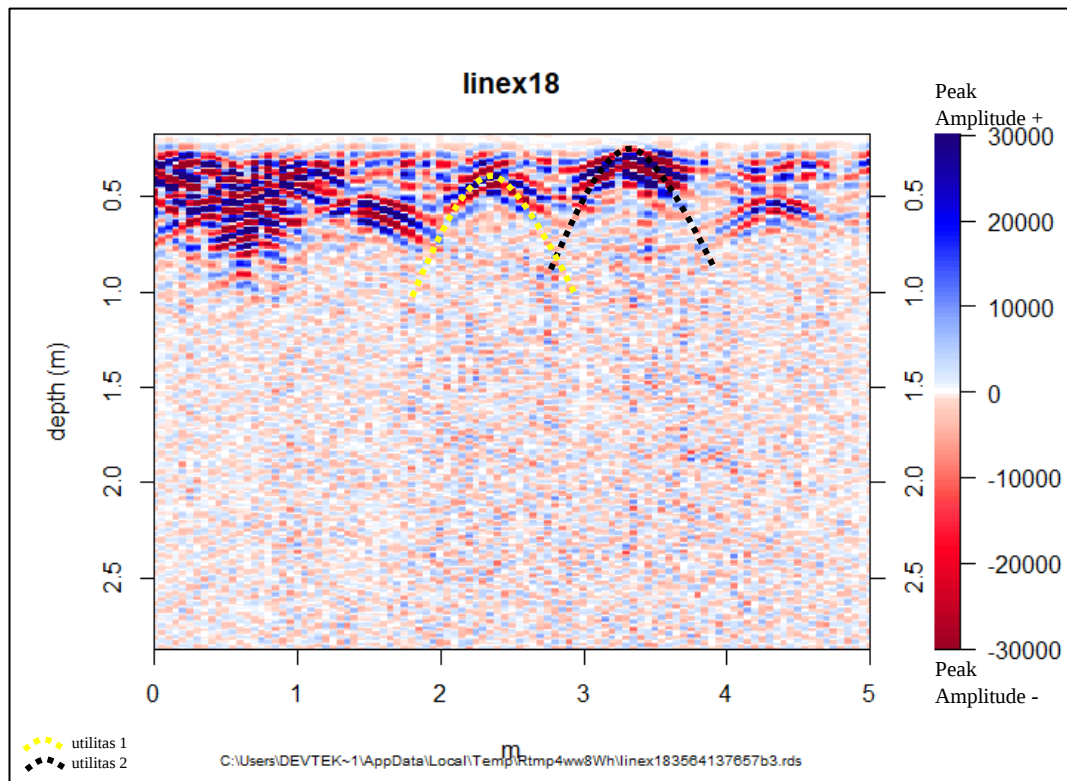
Lintasan 16 sumbu X



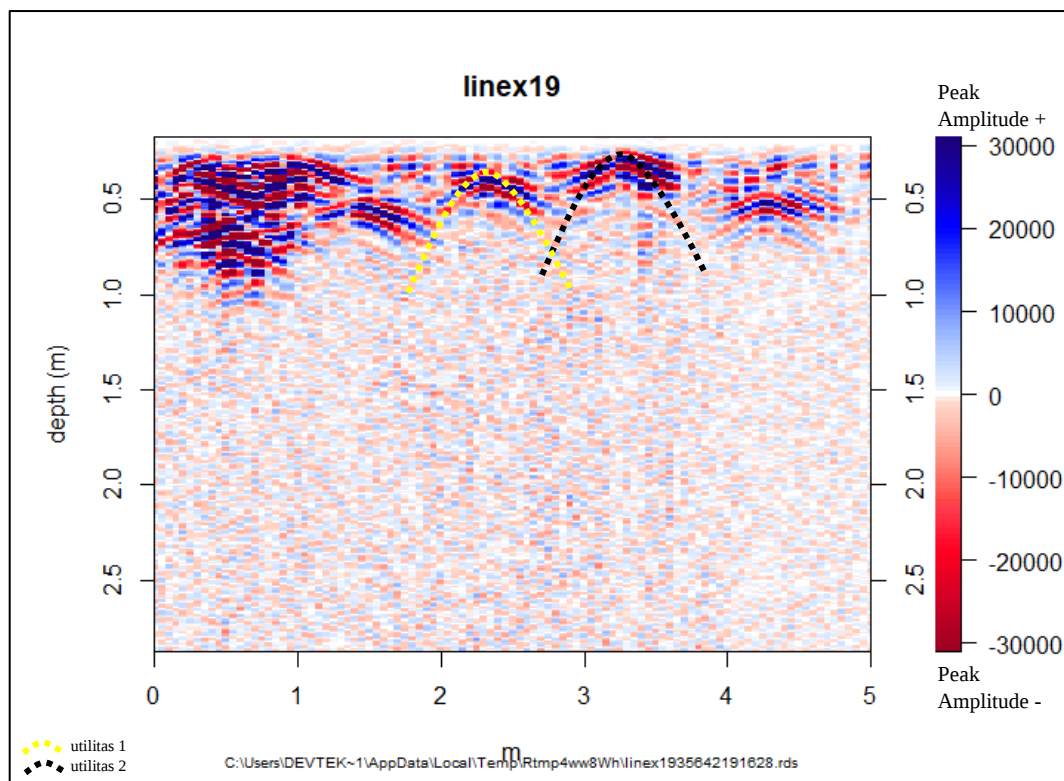
Lintasan 17 sumbu X



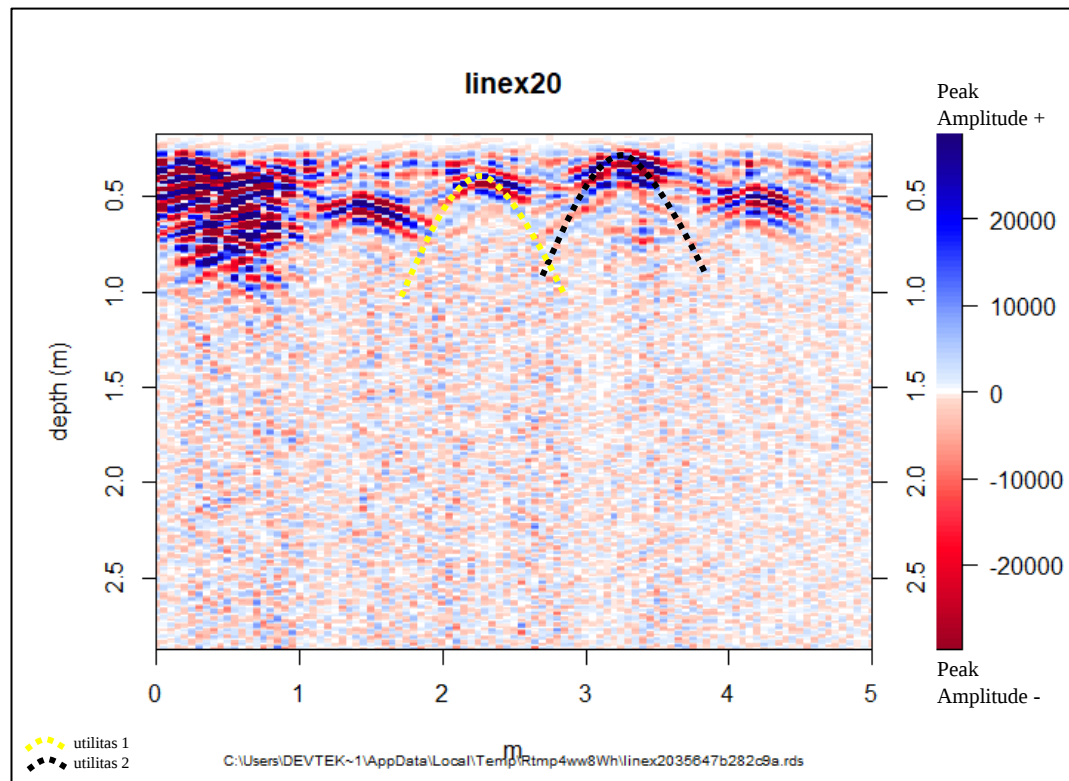
Lintasan 18 sumbu X



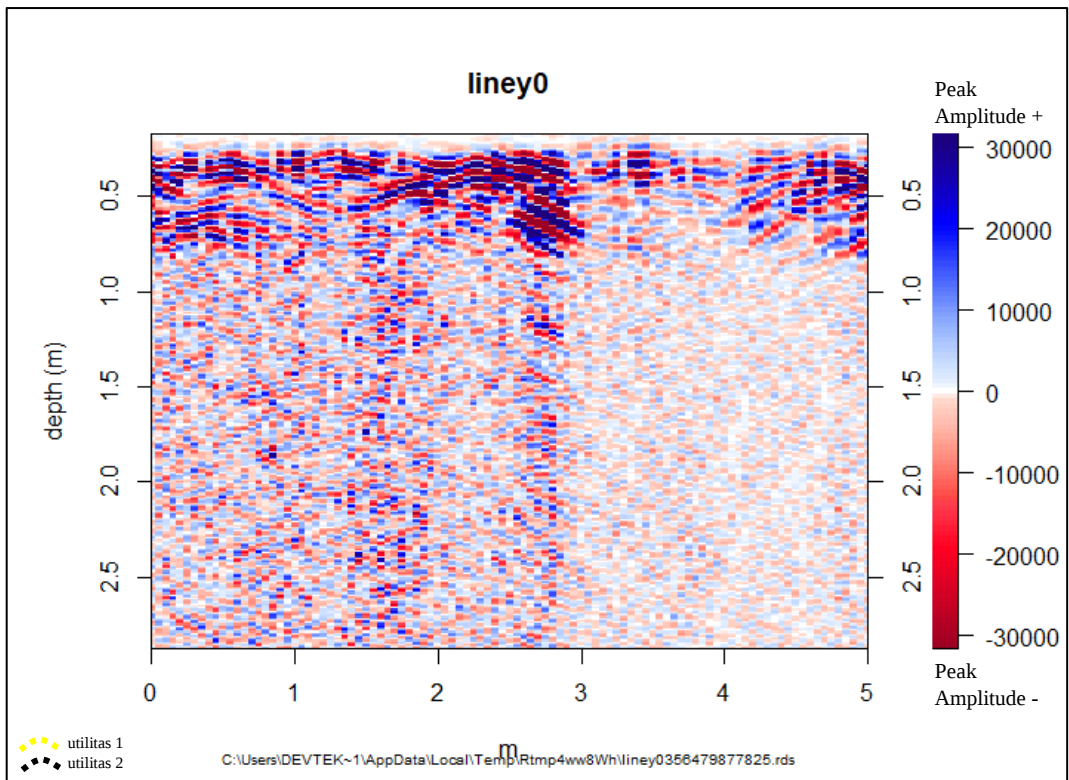
Lintasan 19 sumbu X



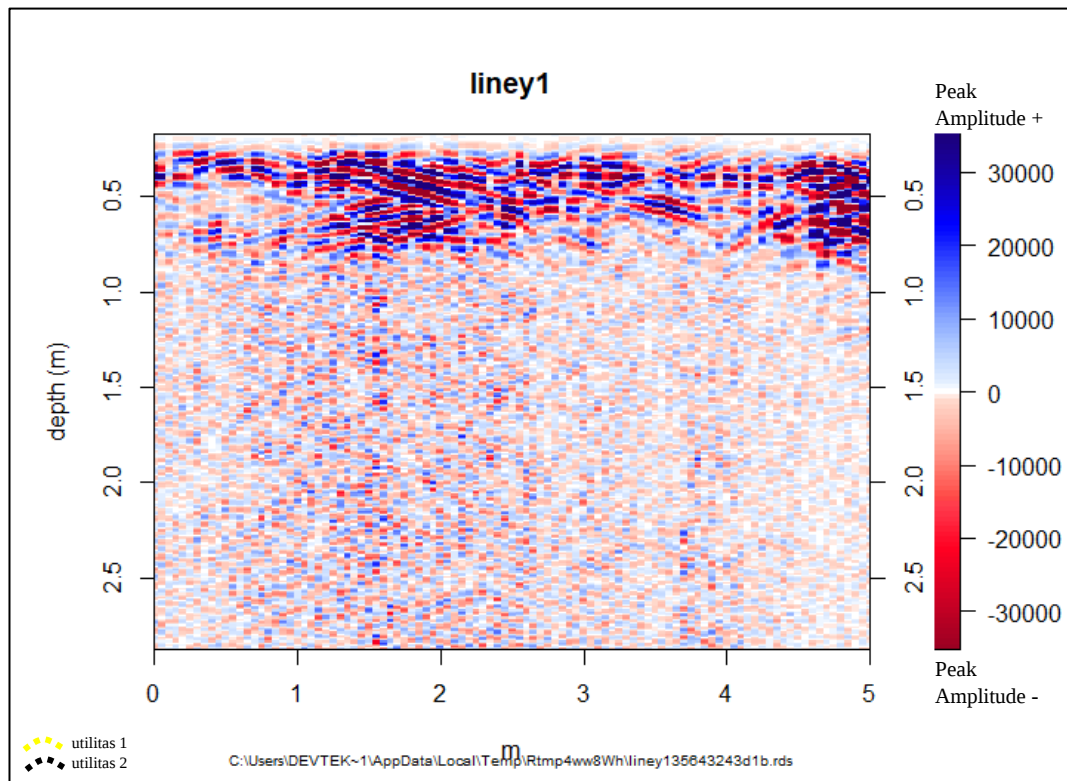
Lintasan 20 sumbu X



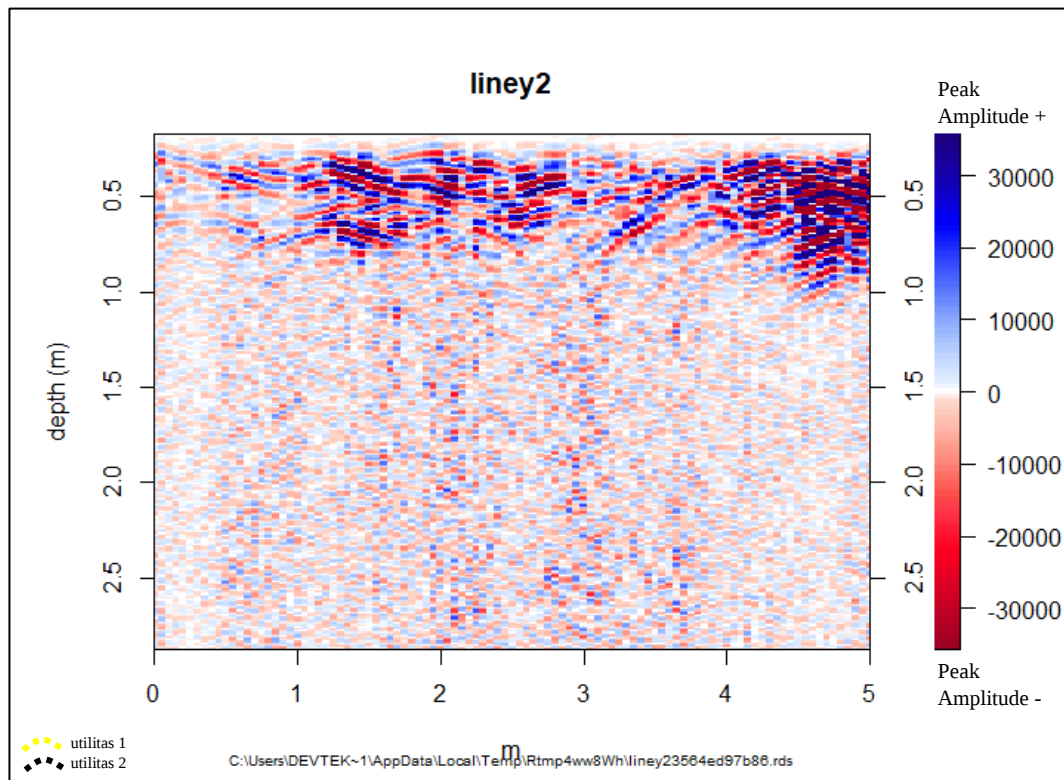
Lintasan 0 sumbu Y



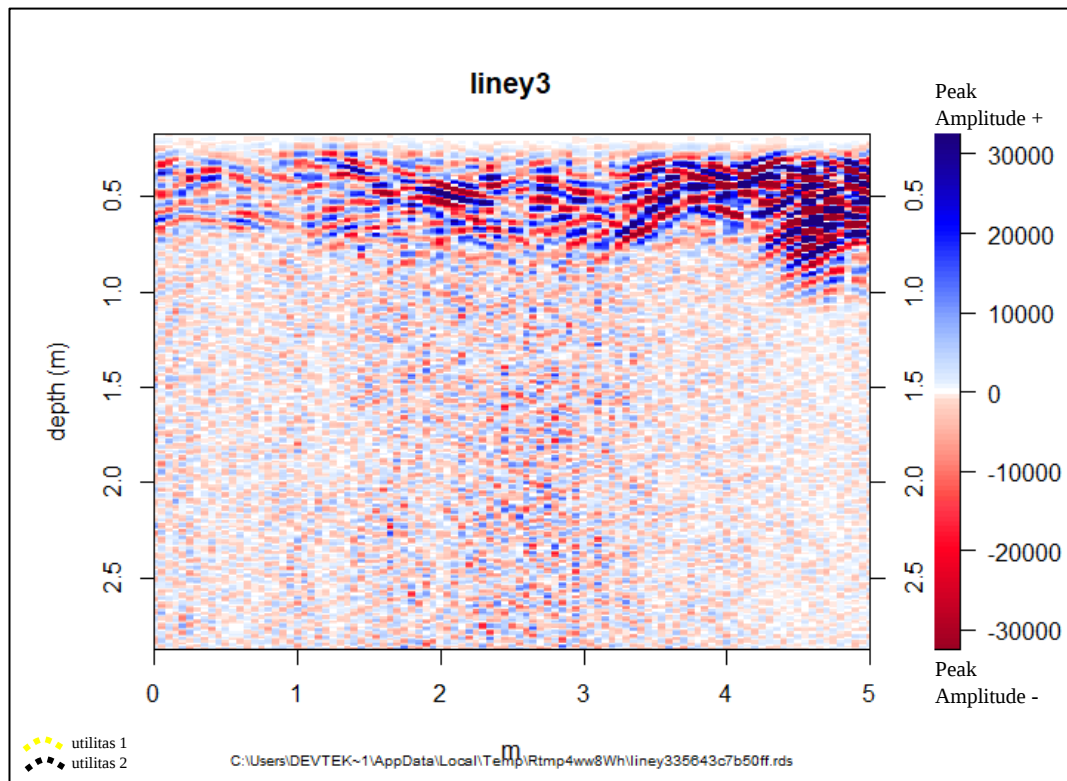
Lintasan 1 sumbu Y



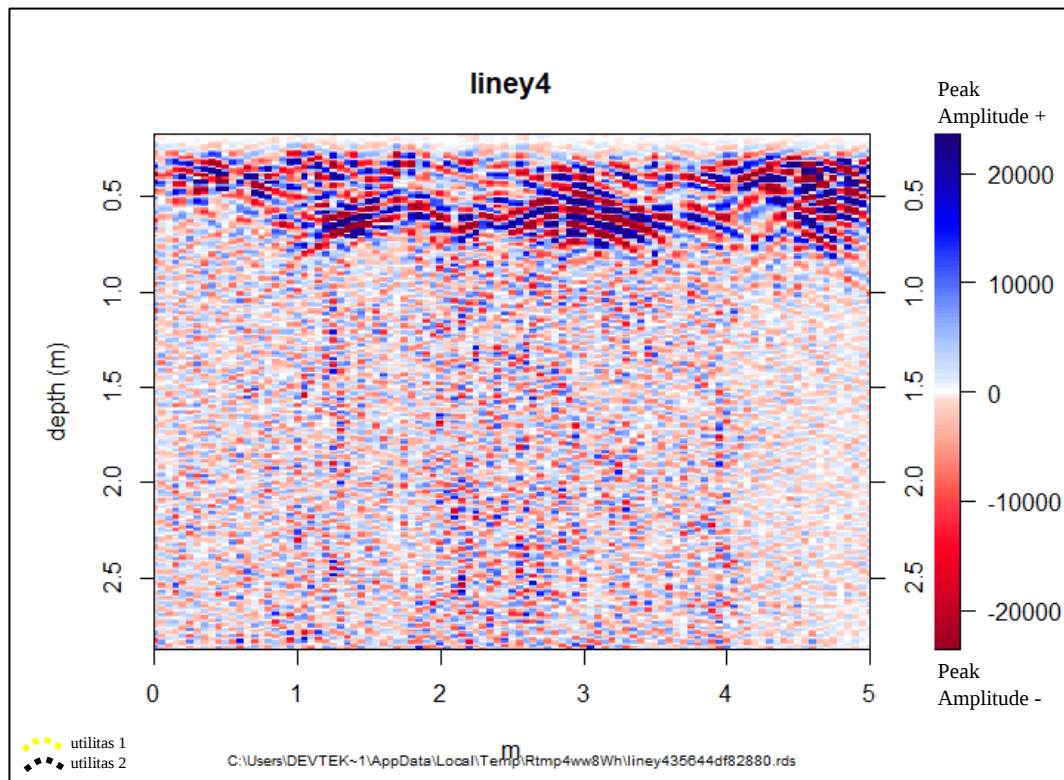
Lintasan 2 sumbu Y



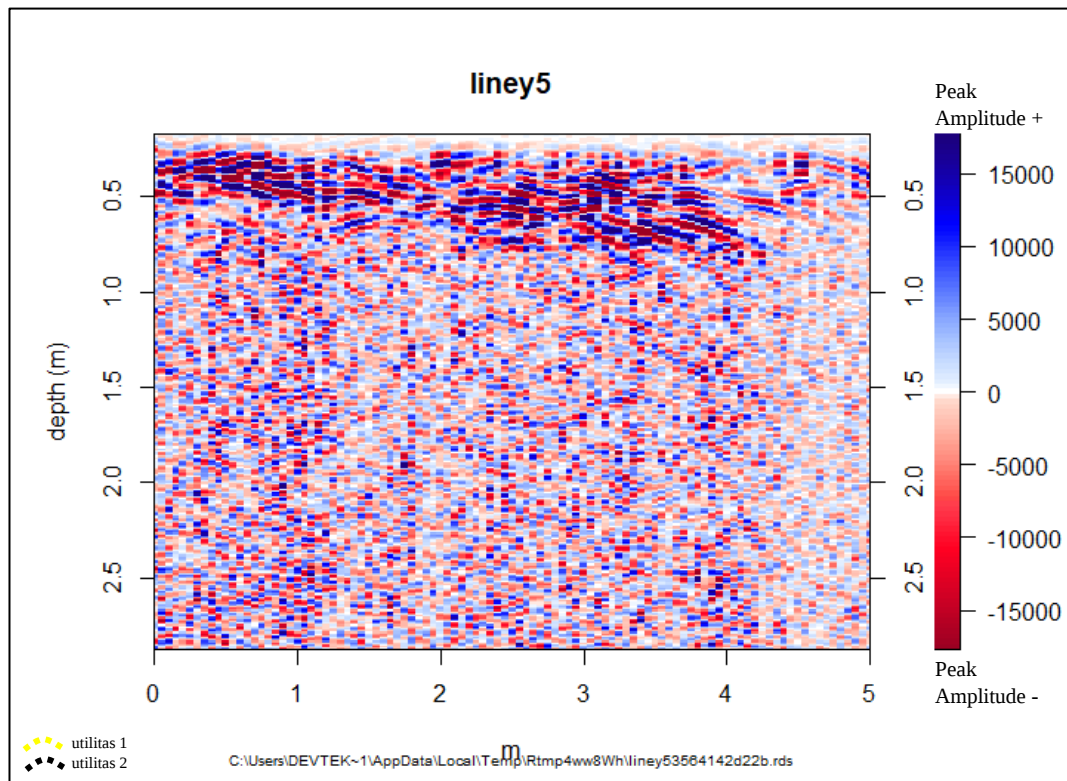
Lintasan 3 sumbu Y



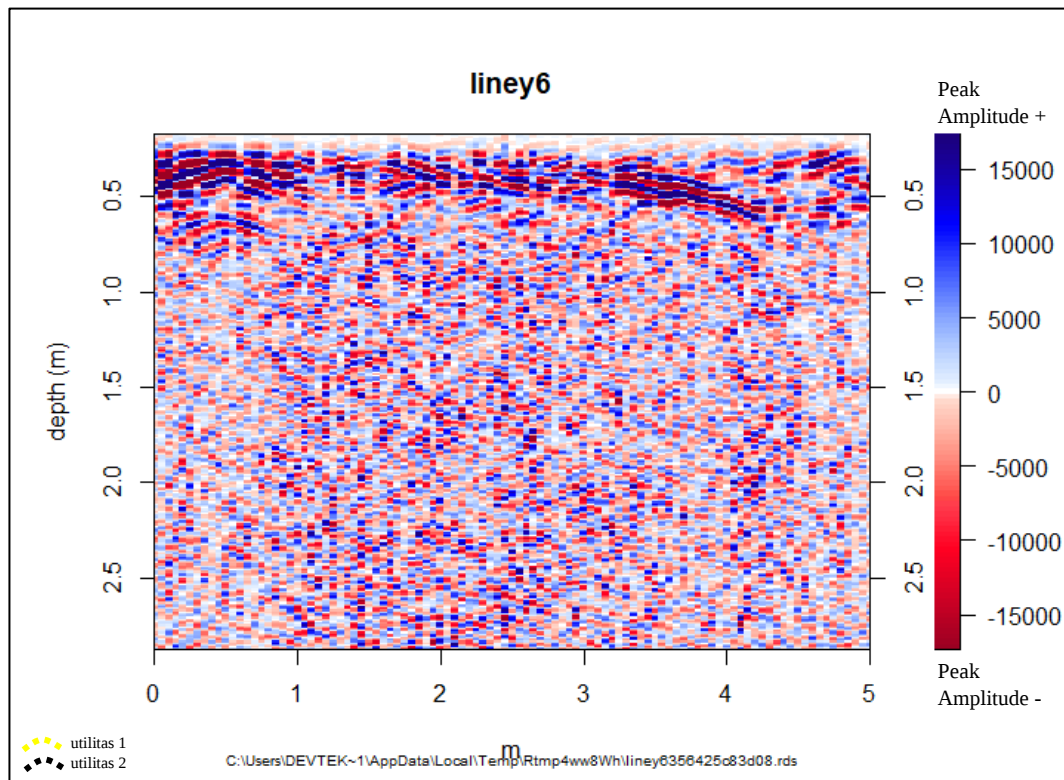
Lintasan 4 sumbu Y



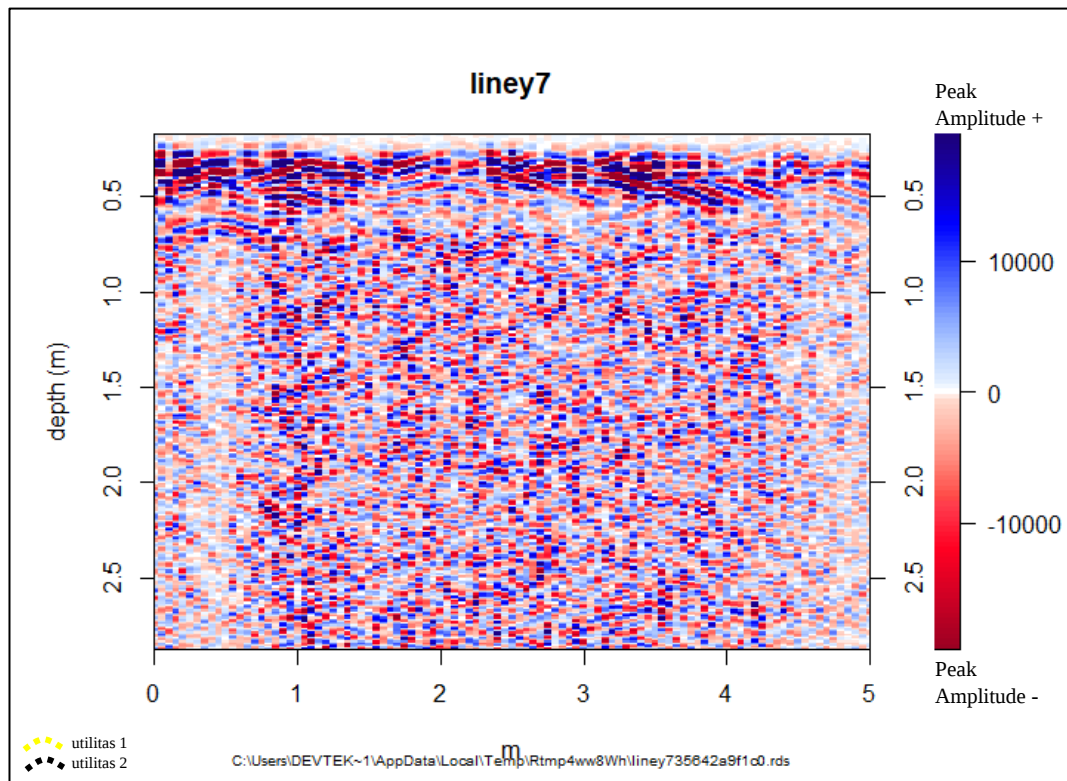
Lintasan 5 sumbu Y



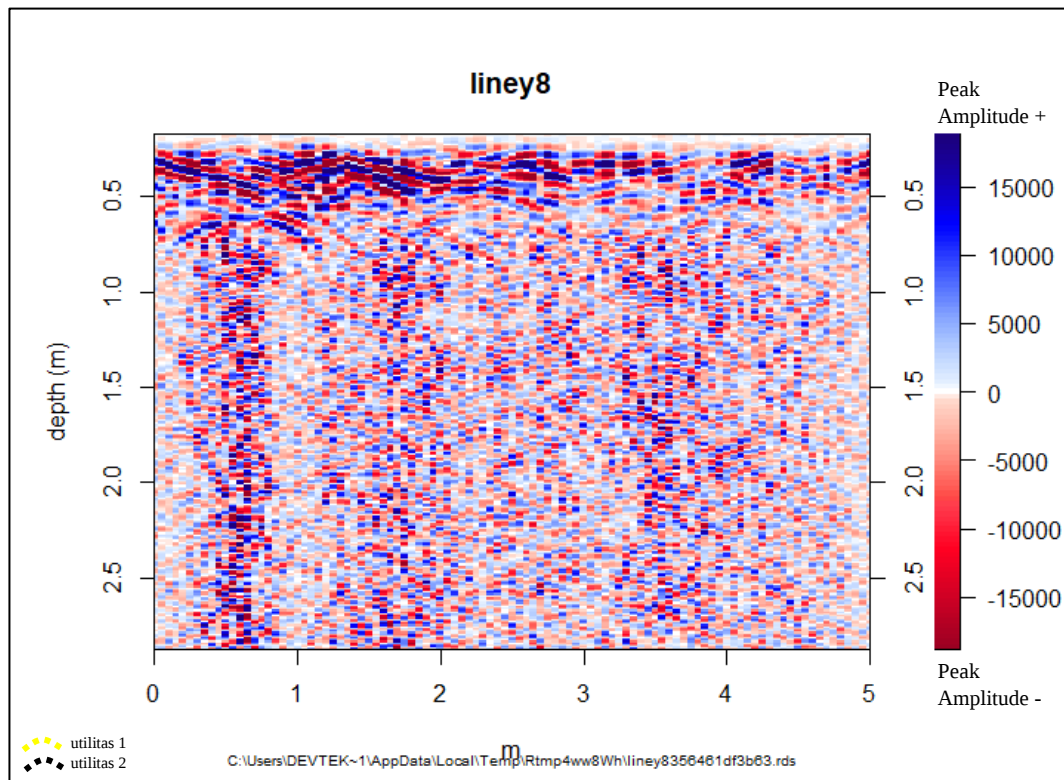
Lintasan 6 sumbu Y



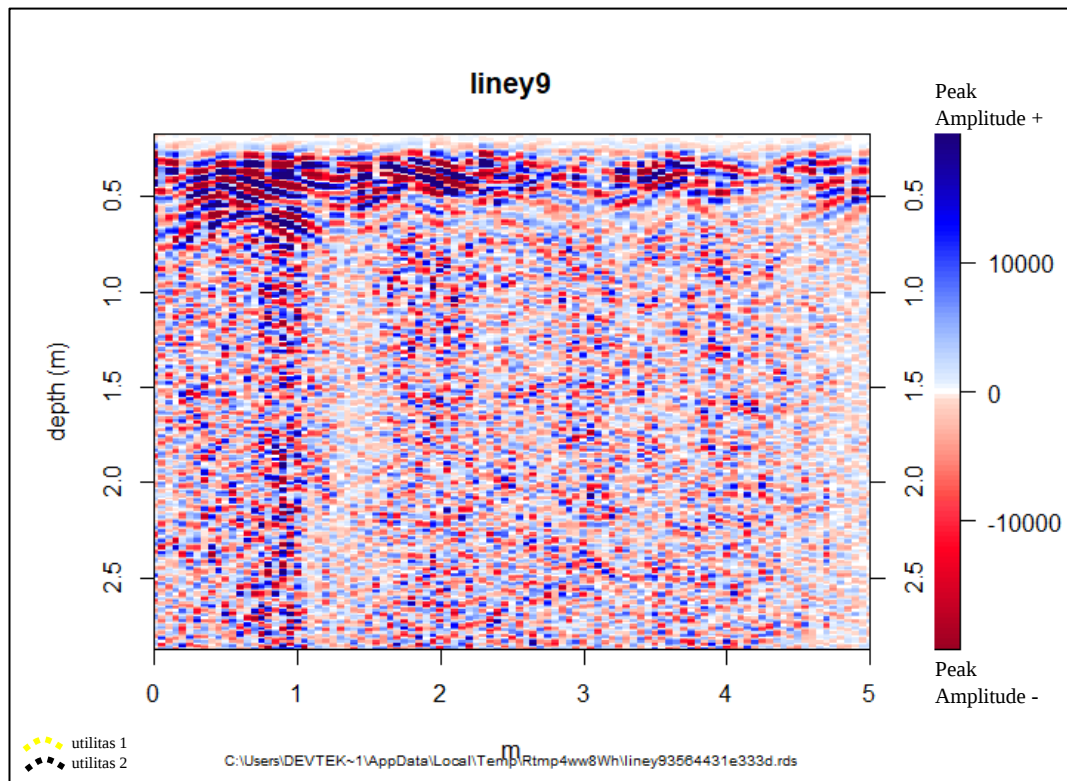
Lintasan 7 sumbu Y



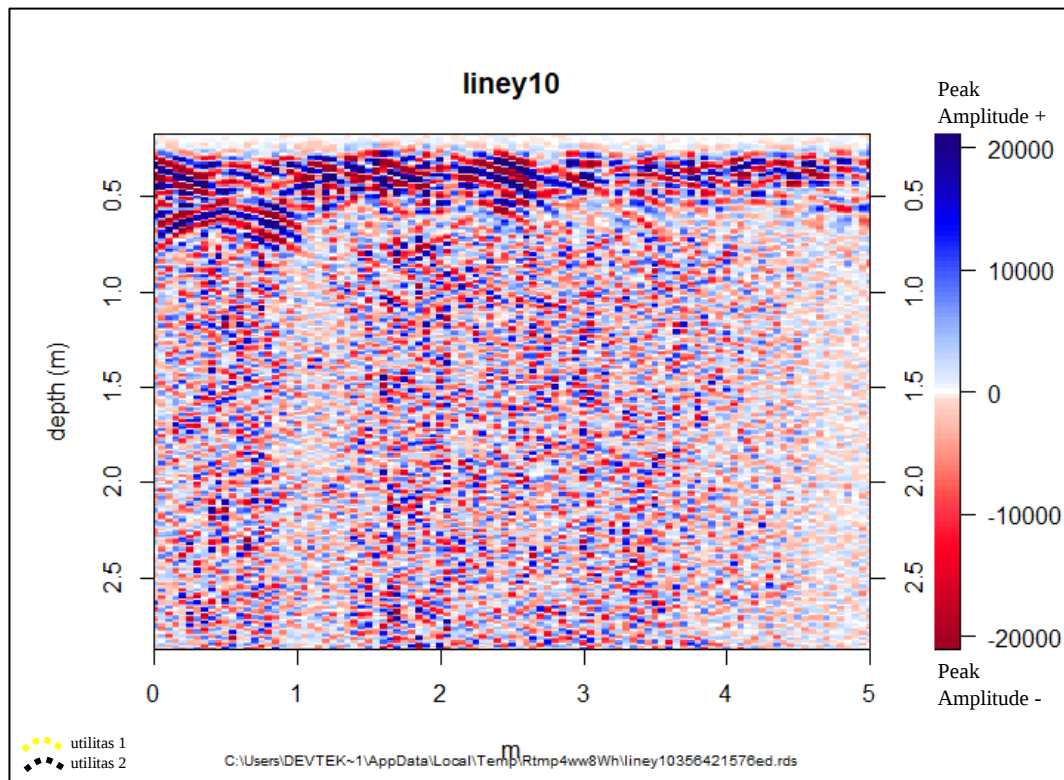
Lintasan 8 sumbu Y



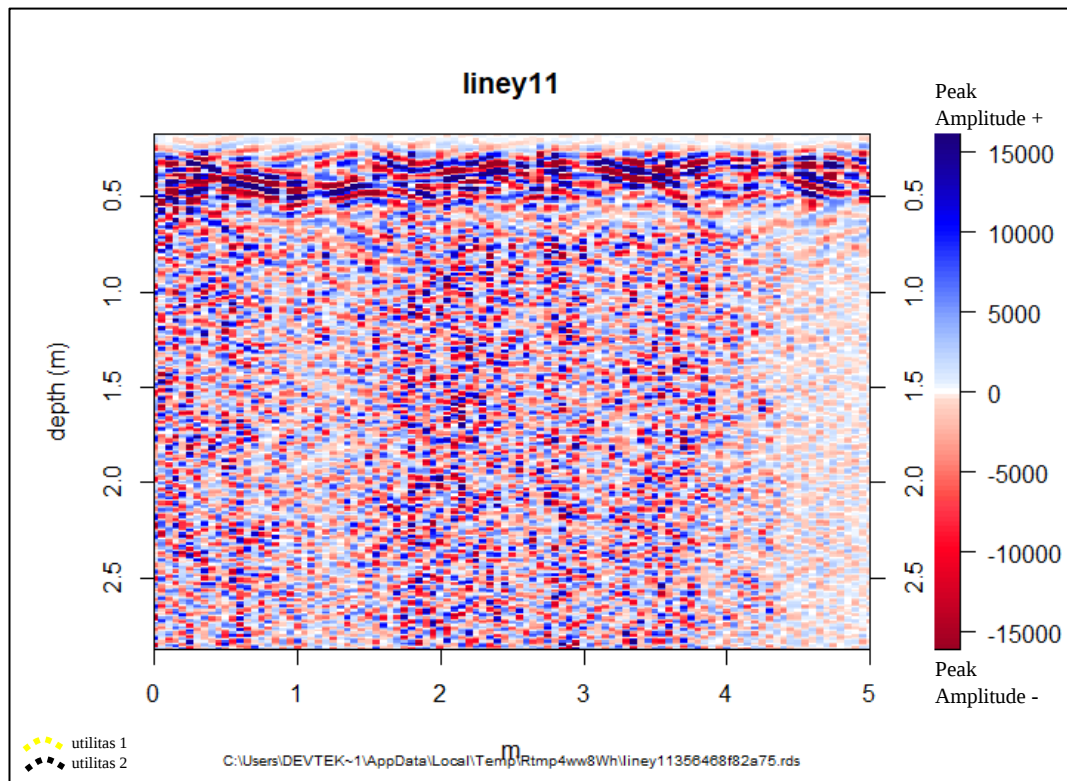
Lintasan 9 sumbu Y



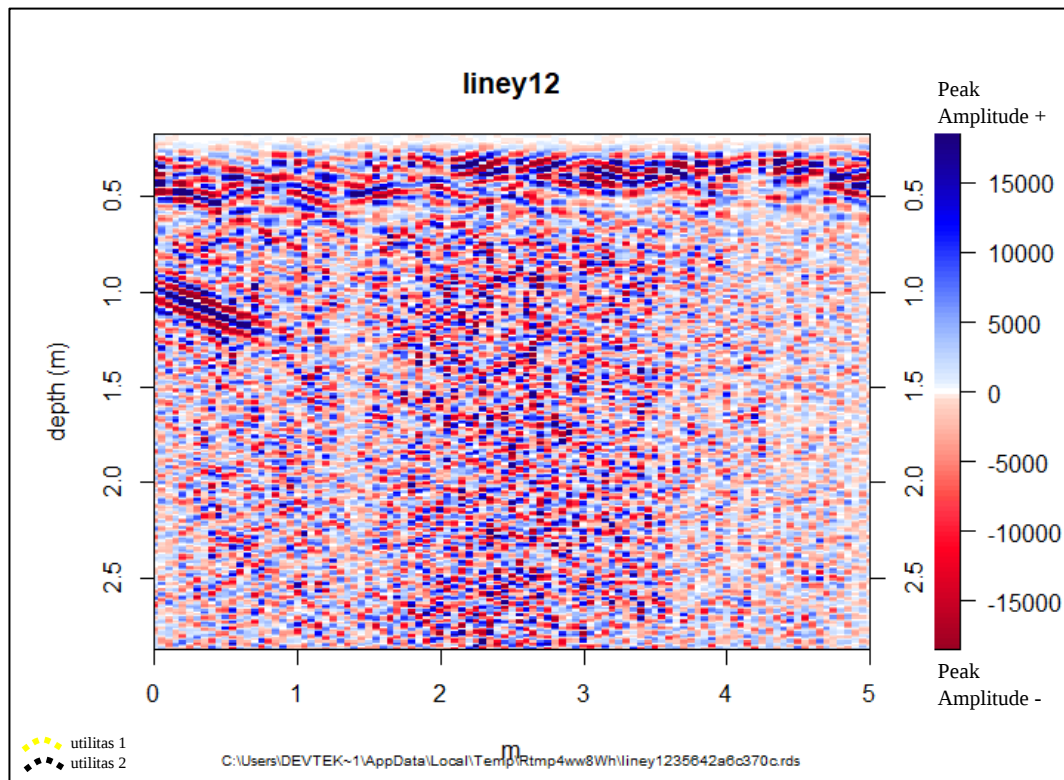
Lintasan 10 sumbu Y



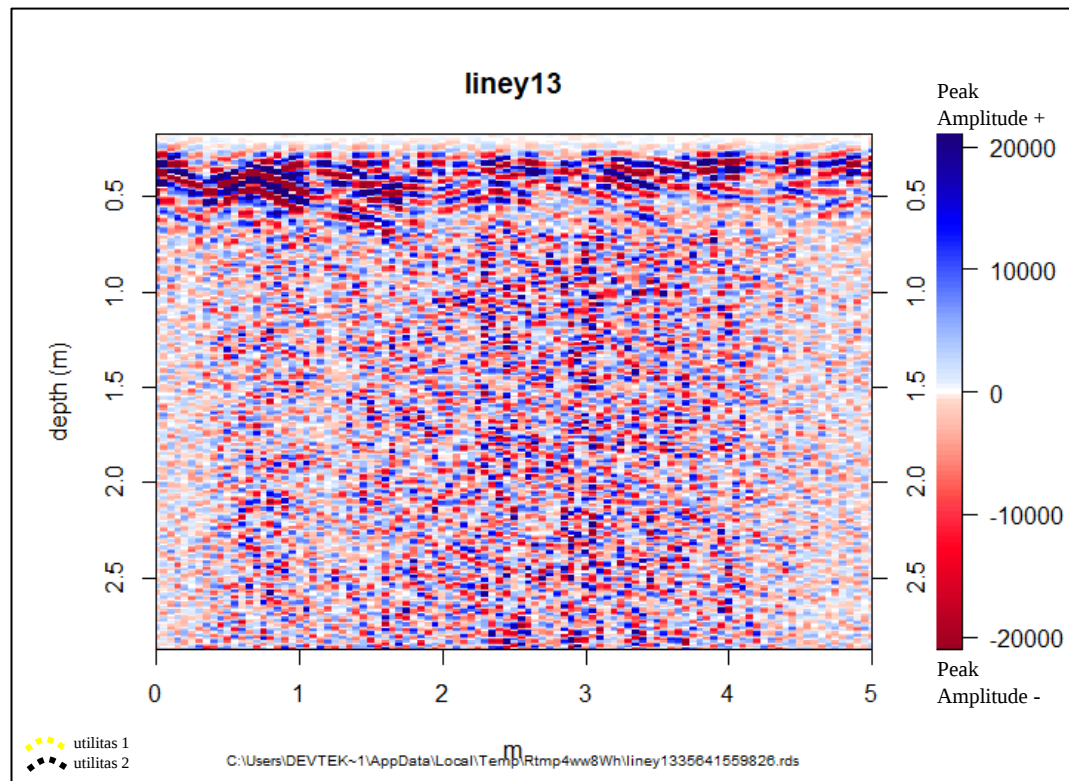
Lintasan 11 sumbu Y



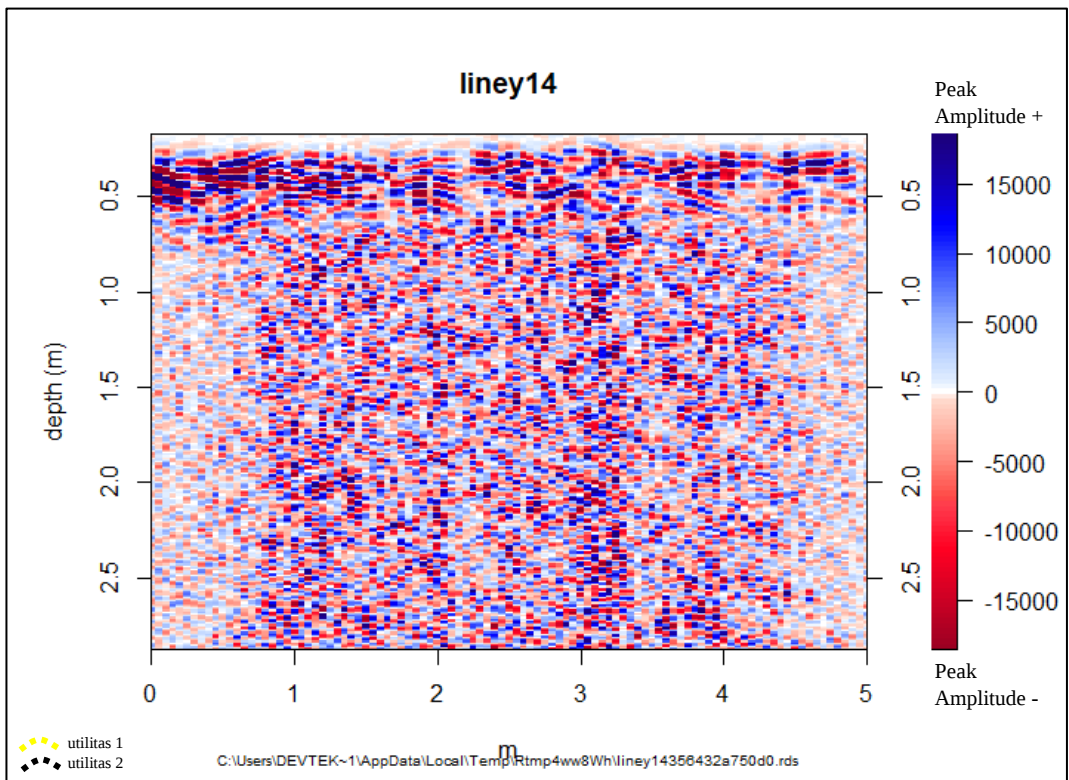
Lintasan 12 sumbu Y



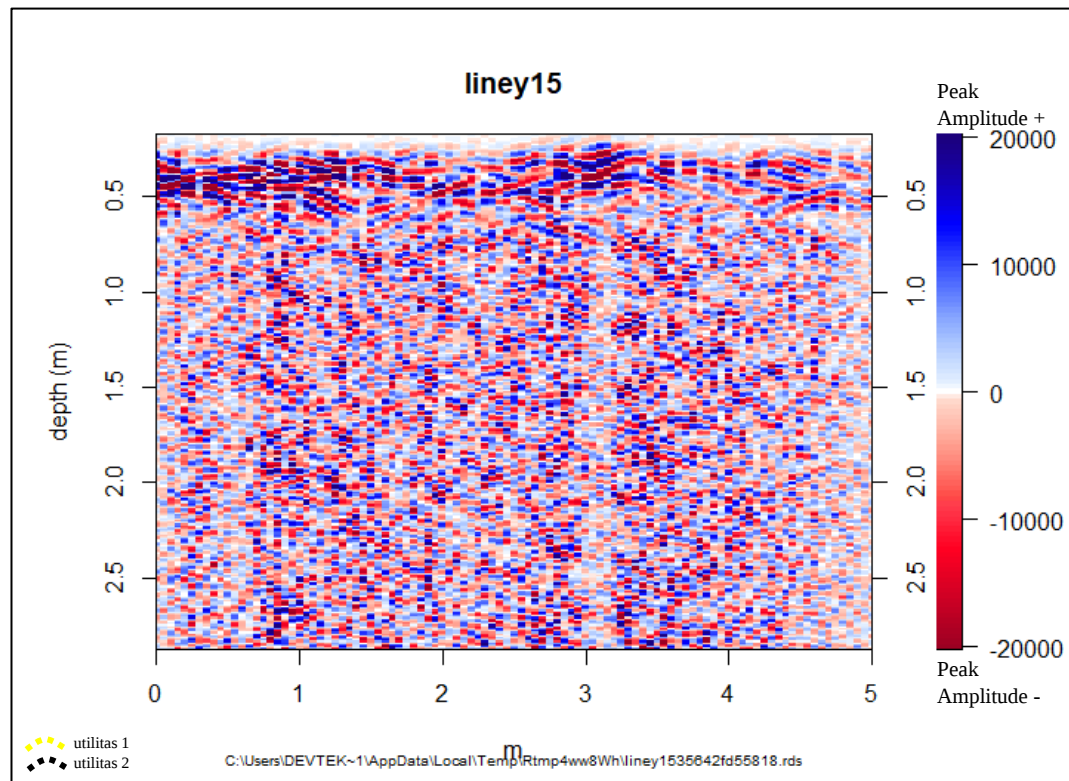
Lintasan 13 sumbu Y



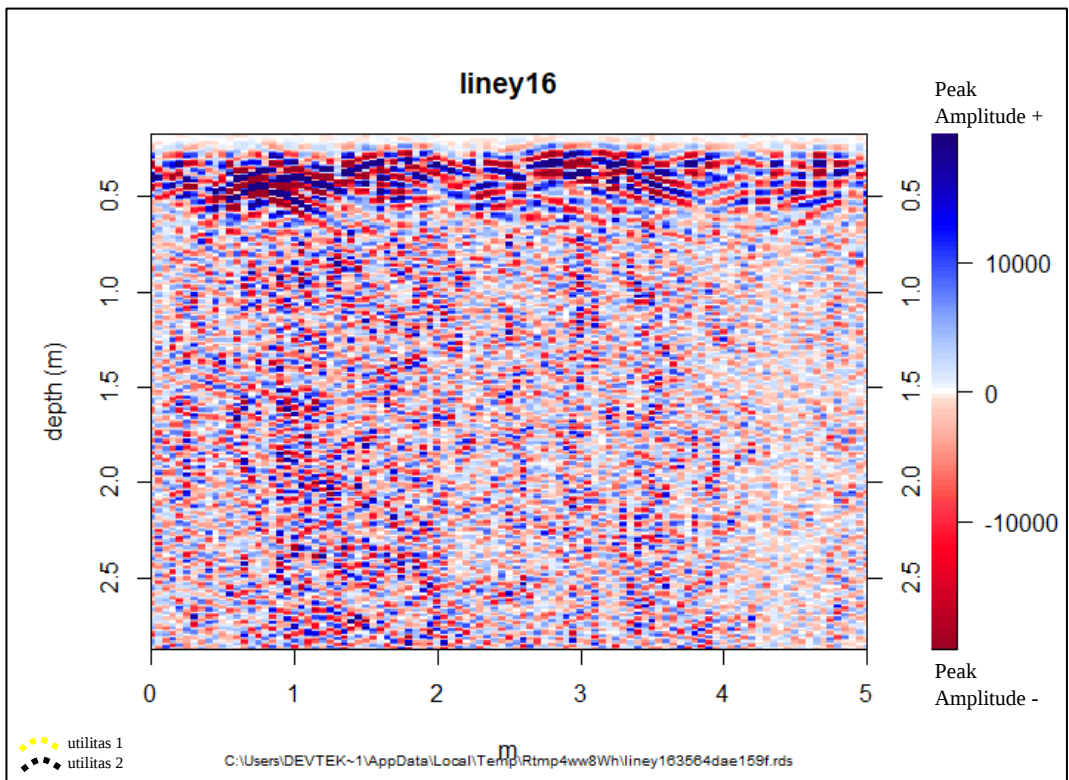
Lintasan 14 sumbu Y



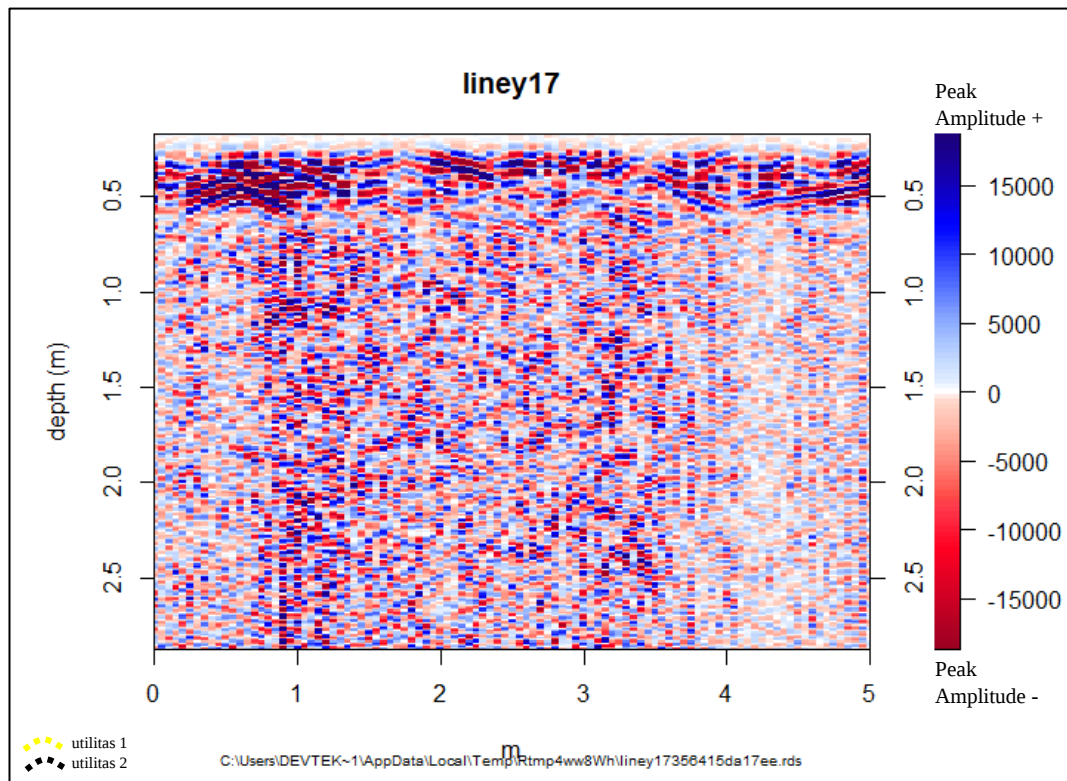
Lintasan 15 sumbu Y



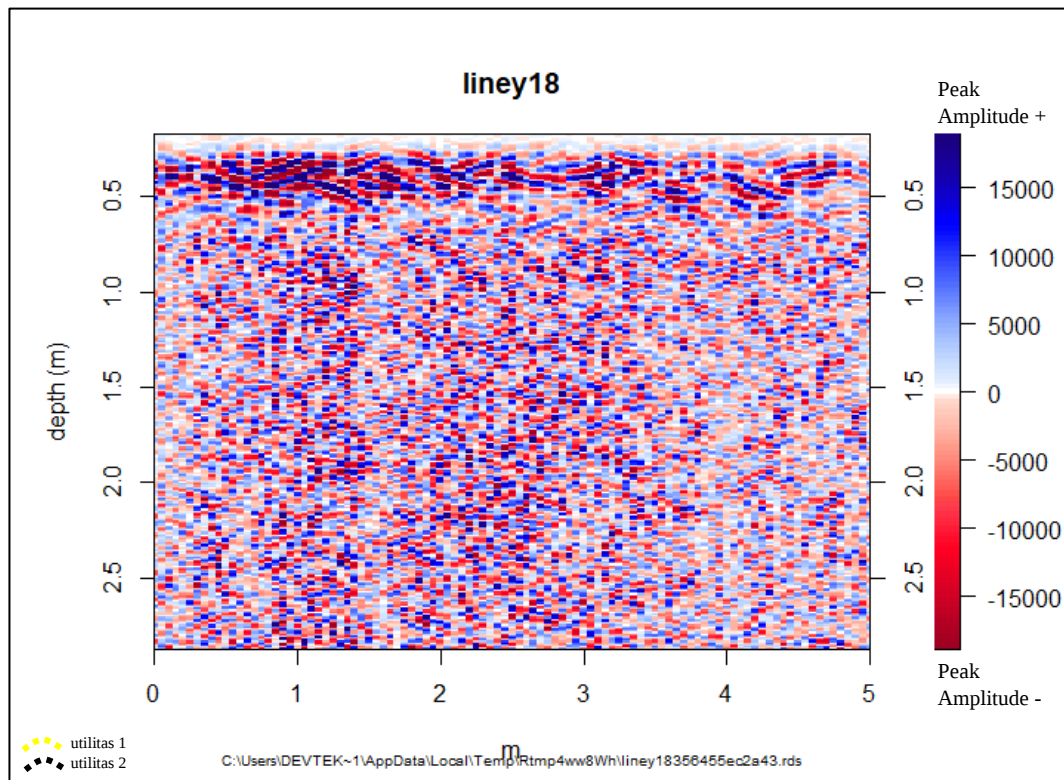
Lintasan 16 sumbu Y



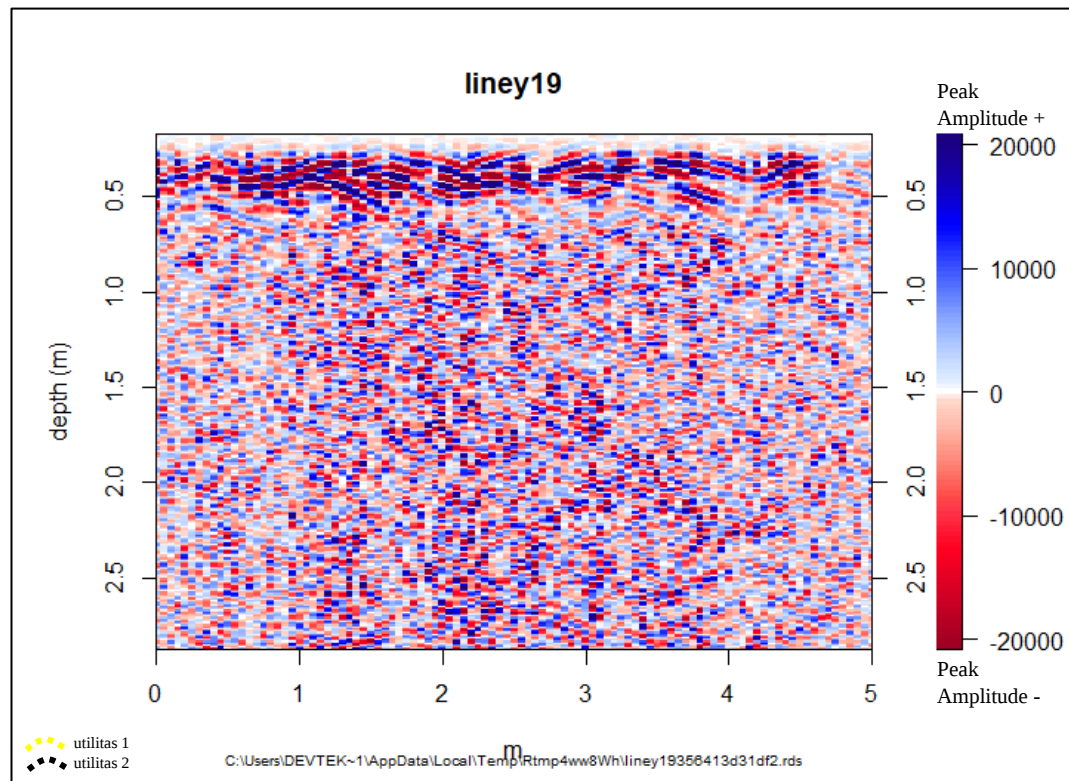
Lintasan 17 sumbu Y



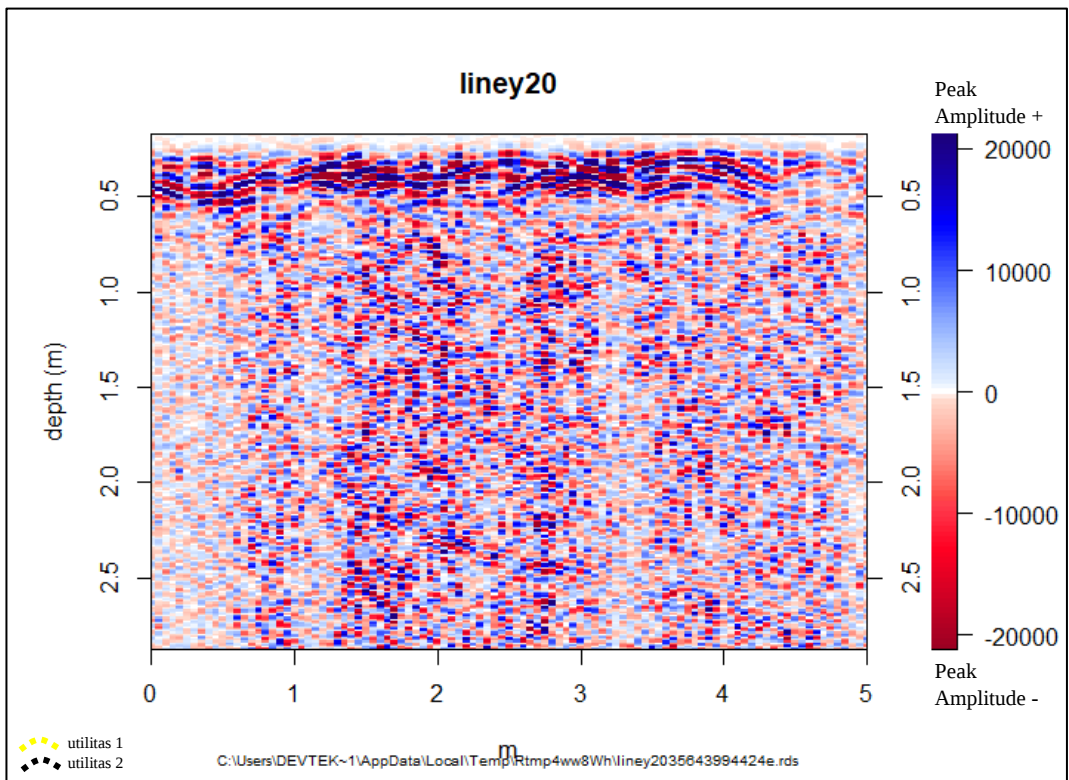
Lintasan 18 sumbu Y



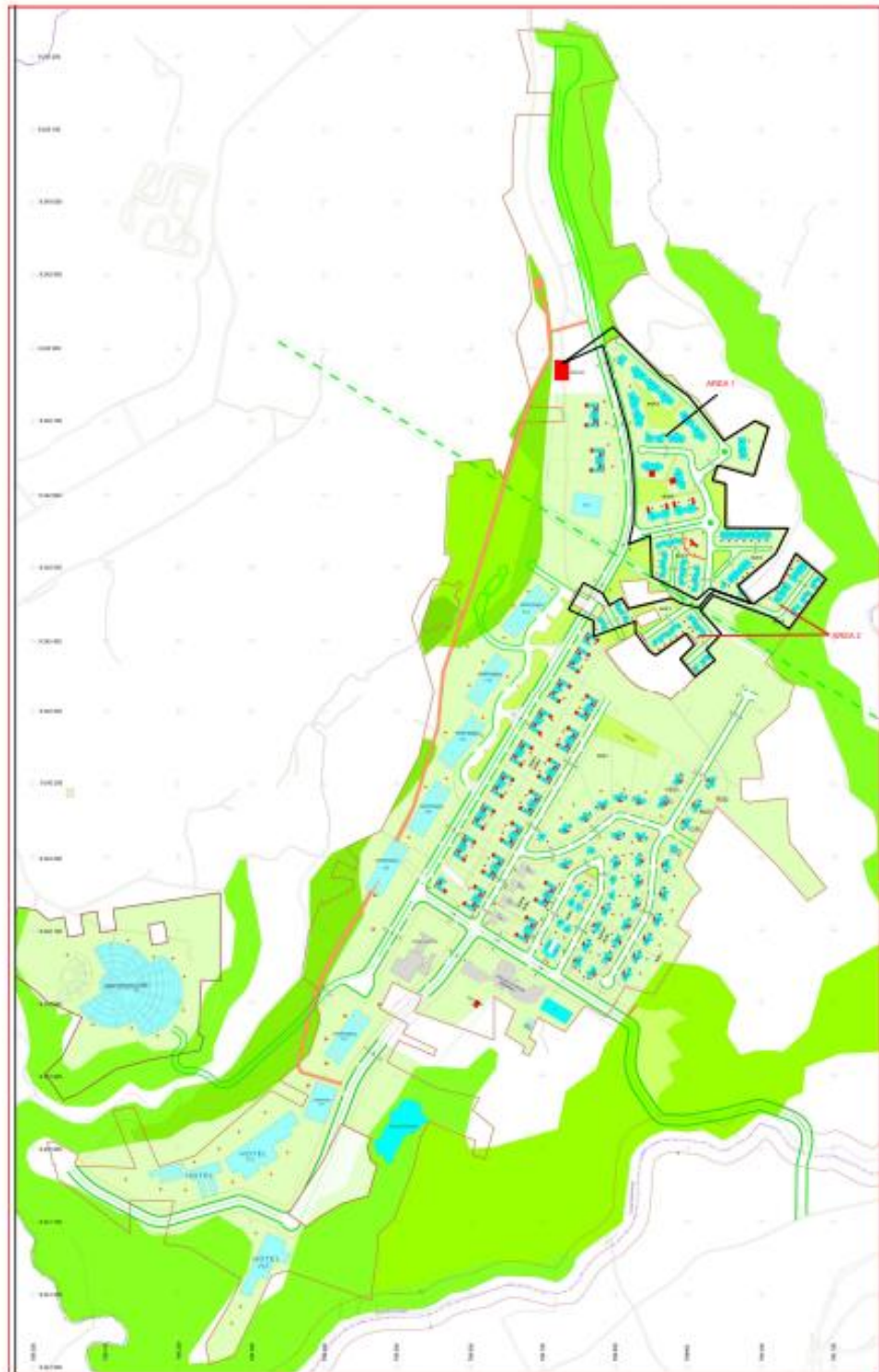
Lintasan 19 sumbu Y



Lintasan 20 sumbu Y



Lampiran 2: Masterplan Area Peneletian



Lampiran 3: Script Pengolahan Data

Script pengolahan data satu lintasan

```
1 #import library
2 library(RGPR)
3
4 #set working directory
5 setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
6
7 #import data
8 line <- readGPR(dsn='linex0.rds')
9 antfreq(line) <- 250
10 antsep(line) <- 0.25
11 pos(line) <- pos(line) *0.05
12 plot(line, col = palGPR("grey"))
13
14 #data cropping
15 line_crop <- line[0:300]
16
17 #time zero correction
18 plot(line_crop[1:100,1])
19 plot(line_crop[19:100,1])
20 line_1 <- line_crop[19:300]
21 plot(line_1[,0:10], type = 'wiggle')
22
23 #dewow
24 plot(line_1[0:100,1])
25 plot(line_1[0:100,1],
26      ylim = c(-10000, 10000))
27 line_dewow <- dewow(line_1,
28                    type = 'Gaussian',
29                    w = 1.7)
30 plot(line_dewow[0:80], col = palGPR('grey'))
31
32 #frequency filter
33 spec1D(line_dewow)
34 line_low <- fFilter(line_dewow,
35                   f = c(300, 650),
36                   type = 'low',
37                   plotSpec = TRUE)
38 plot(line_low, col = palGPR('grey'))
39
40 #exponential gain
41 line_gain <- gain(line_low,
42                 type = "exp",
43                 alpha = 0.5,
44                 t0 = (0),
45                 te = (30))
46
47 plot(line_gain[0:80], col = palGPR('grey'))
48
49 #background removal
50 line_backremov <- (rmBackground(line_gain,
51                               w = 6,
52                               FUN = 'mean'))
53
54 plot(line_backremov, col = palGPR('grey'))
```

Script mengekstrak koordinat lokal

```
1 #import library
2 library(RGPR)
3
4 #set working directory
5 setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
6
7 #input lines
8 Lines <- list.files(pattern = "^line.?.sgy")
9 X_lines <- list.files(pattern = 'linex[0-99].*sgy')
10 Y_lines <- list.files(pattern = 'liney[0-99].*sgy')
11
12 #read GPR survey
13 X_survey <- GPRsurvey(X_lines)
14 Y_survey <- GPRsurvey(Y_lines)
15
16 #coordinate Extraction
17 X_position <- seq(0, by = 0.25, length.out = length(X_survey))
18 Y_position <- seq(0, by = 0.25, length.out = length(Y_survey))
19
20 #looping function
21 #define line
22 line <- readGPR(X_lines[[1]])
23
24 #preprocessing
25 antfreq(line) <- 250
26 antsep(line) <- 0.25
27 pos(line) <- pos(line) *0.05
28
29 #variable making
30 E = rep(X_position[1], length(line@traces))
31 N = seq(0, max(pos(line)) - min(pos(line)), by = 0.05)
32 Z = rep(0, length(line@traces))
33
34 #making data frame
35 text.data <- data.frame(E, N, Z)
36 write.table(text.data,
37             file = paste(line@name, '.txt', sep = ' '),
38             quote = FALSE,
39             row.names = FALSE,
40             sep = ',')
41
42 #looping function x
43 for (i in seq_along(X_lines)){
44   line <- readGPR(X_lines[[i]])
45
46   #preprocessing
47   antfreq(line) <- 250
48   antsep(line) <- 0.25
49   pos(line) <- pos(line) *0.05
50
51   #variable making
52   E = rep(X_position[i], length(line@traces))
53   N = seq(0, max(pos(line)) - min(pos(line)), by = 0.05)
54   Z = rep(0, length(line@traces))
55
56   #making data frame
57   text.data <- data.frame(E, N, Z)
58   write.table(text.data,
59               file = paste(line@name, '.txt', sep = ' '),
60               quote = FALSE,
61               row.names = FALSE,
62               sep = ',')
63 }
```

```

64
65 #looping function y
66 #define line
67 line <- readGPR(Y_lines[[1]])
68
69 #preprocessing
70 antfreq(line) <- 250
71 antsep(line) <- 0.25
72 pos(line) <- pos(line) *0.05
73
74 #variable making
75 N = rep(Y_position[1], length(line@traces))
76 E = seq(0, max(pos(line)) - min(pos(line)), by = 0.05)
77 Z = rep(0, length(line@traces))
78
79 #making data frame
80 text.data <- data.frame(N, E, Z)
81 write.table(text.data,
82             file = paste(line@name, '.txt', sep = ' '),
83             quote = FALSE,
84             row.names = FALSE,
85             sep = ',')
86
87 ##
88 for (i in seq_along(Y_lines)){
89   line <- readGPR(Y_lines[[i]])
90
91   #preprocessing
92   antfreq(line) <- 250
93   antsep(line) <- 0.25
94   #pos(line) <- pos(line) *0.05
95
96   #variable making
97   E = seq(0, 5, by = 0.05)
98   N = rep(Y_position[i], length(line@traces))
99   Z = rep(0, length(line@traces))
100
101   #making data frame
102   text.data <- data.frame(E, N, Z)
103   write.table(text.data,
104               file = paste(line@name, '.txt', sep = ' '),
105               quote = FALSE,
106               row.names = FALSE,
107               sep = ',')
108 }

```

Script menggabungkan koordinat

```
1 #import library
2 library(RGPR)
3
4 #set working directory
5 setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
6
7 #input lines
8 Lines <- list.files(pattern = "^linex.*?.sgy")
9 Lines_Survey <- GPRsurvey(Lines)
10
11 #extract coord
12 Coord <- readTopo(list.files(pattern = "^linex.*?.txt"))
13
14 #assign coord
15 Lines_coord <- Lines_Survey
16 a <- Lines_Survey@coords[1:length(Coord)]
17 a <- Coord
18 coords(Lines_coord) <- Coord
19 coords(Lines_Survey) <- Coord
20 plot(Lines_coord)
21
22 # Saving Lines y
23 for (i in seq_along(Lines_coord)){
24   setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
25   writeGPR(Lines_coord[[i]],
26           fpath = file.path('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01',
27                             'processing', name(Lines_coord[[i]])),
28           type = 'rds',
29           overwrite = TRUE)
30   setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
31 }
```

Script velocity analysis

```
1 #import library
2 library(RGPR)
3
4 #set working directory
5 setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
6
7 #input lines
8 Lines <- list.files(pattern = "^line.*?.sgy")
9 Lines_Survey <- GPRsurvey(Lines)
10
11 #extract coord
12 Coord <- readTopo(list.files(pattern = "^line.*?.txt"))
13
14 #assign coord
15 Lines_coord <- Lines_Survey
16 coords(Lines_coord) <- Coord
17 plot(Lines_coord)
18
19 #velocity analysis
20 line <- Lines_coord[['linex0']]
21 plot(line[0:80], addAnn = FALSE)
22
23 #locate
24 xy <- locator(type = 'l')
25
26 #hyperbola fit
27 hyp <- hyperbolaFit(xy)
28
29 #smooth plotting
30 plot(line[0:80], addAnn = FALSE)
31 points(xy, pch = 20, col = 'black')
32 hyperbolaPlot(hyp, col = 'red', lwd = 2, ann = TRUE)
33
34 #define velocity
35 vel <- 0.0481
```

Script pengolahan data seluruh lintasan

```
1 #import library
2 library(RGPR)
3
4 #set working directory
5 setwd('D:/SKRIPSI/Data/GPR_Data/GPR_Data_ALFIAN/Grid01')
6
7 #input lines
8 Lines <- list.files(pattern = "^line.*?.rds")
9 Lines_Survey <- GPRsurvey(Lines)
10
11 #define velocity
12 vel <- 0.0481
13
14 #preprocessing
15 for (i in seq_along(Lines_Survey)){
16   Lines_Survey[[i]] <- Lines_Survey[[i]][19:300]
17   vel(Lines_Survey[[i]]) <- vel
18 }
19
20 #processing
21 Lines_proc <- papply(Lines_Survey,
22   prc = list(dewow = list(type = 'Gaussian', w = 1.7),
23     ffilter = list(f = c(300, 650), type = 'low', plotspec = TRUE),
24     gain = list(type = "exp", alpha = 0.5, t0 = (0), te = (30)),
25     rmBackground = list(w = 6, FUN = 'mean'))
26
27 #time to depth conversion
28 for (i in seq_along(Lines_proc)){
29   Lines_proc[[i]] <- convertTimeToDepth(Lines_proc[[i]])
30 }
31
32 #plot 3D
33 plot3DRGL(Lines_proc)
34
35 for (i in seq(Lines_proc)){
36   setwd("D:/Skripsi/Hasil")
37   writeGPR(Lines_proc[[i]],
38     fpath = file.path("D:/Skripsi/Hasil", name(Lines_proc[[i]])),
39     type = 'rds',
40     overwrite = TRUE)
41 }
42
43 #Interpolate slice
44 SXY <- interpSlices(Lines_proc, dx = 0.05, dy = 0.05, dz = 0.02, h = 6, extend = FALSE)
45
46 #Plot
47 plot(SXY[,17], col = palGPR("slice"), asp = 1)
48
49 a <- Lines_proc[[1]]
50 plot(a)
```

Lampiran 4: Persamaan Maxwell

Persamaan Maxwell yang digunakan dalam metode georadar:

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (1.1a)$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \quad (1.1b)$$

$$\nabla \cdot \mathbf{D} = q \quad (1.1c)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (1.1d)$$

Hubungan antara intensitas medan dengan fluks yang terjadi pada medium dinyatakan oleh persamaan berikut:

$$\mathbf{B} = \mu \mathbf{H} \quad (2.2a)$$

$$\mathbf{D} = \varepsilon \mathbf{E} \quad (2.2b)$$

$$\mathbf{J} = \sigma \mathbf{E} = \frac{\mathbf{E}}{\rho} \quad (2.2c)$$

Maka persamaan Maxwell dapat dituliskan kembali sebagai berikut:

$$\nabla \times \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial t} \quad (2.3a)$$

$$\nabla \times \mathbf{H} = \sigma \mathbf{E} + \varepsilon \frac{\partial \mathbf{E}}{\partial t} \quad (2.3b)$$

$$\nabla \cdot \mathbf{E} = 0 \quad (2.3c)$$

$$\nabla \cdot \mathbf{H} = 0 \quad (2.3d)$$

Dengan menggunakan identitas vektor ($\nabla \times (\nabla \times \mathbf{x}) = \nabla(\nabla \cdot \mathbf{x}) - \nabla^2 \mathbf{x}$), dimana $\mathbf{x}$ adalah $\mathbf{E}$ dan $\mathbf{H}$:

$$\nabla \times (\nabla \times \mathbf{E}) = \nabla(\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} \quad (2.4a)$$

$$\nabla \times (\nabla \times \mathbf{H}) = \nabla(\nabla \cdot \mathbf{H}) - \nabla^2 \mathbf{H} \quad (2.4b)$$

Maka persamaan (2.4a) dan (2.4b) menjadi:

$$\nabla \times (\nabla \times \mathbf{E}) = -\nabla^2 \mathbf{E} \quad (2.5a)$$

$$\nabla \times (\nabla \times \mathbf{H}) = -\nabla^2 \mathbf{H} \quad (2.5b)$$

Maka dapat dituliskan sebagai berikut:

$$\nabla \times (\nabla \times \mathbf{E}) = -\mu\sigma \frac{\partial \mathbf{E}}{\partial t} - \mu\epsilon \frac{\partial^2 \mathbf{E}}{\partial t^2} \quad (2.6a)$$

$$\nabla \times (\nabla \times \mathbf{H}) = -\mu\sigma \frac{\partial \mathbf{H}}{\partial t} - \mu\epsilon \frac{\partial^2 \mathbf{H}}{\partial t^2} \quad (2.6b)$$

Dengan mensubstitusikan persamaan (2.5) ke persamaan (2.6) maka dapat dituliskan sebagai berikut:

$$\nabla \times (\nabla \times \mathbf{E}) + \mu\sigma \frac{\partial \mathbf{E}}{\partial t} + \mu\epsilon \frac{\partial^2 \mathbf{E}}{\partial t^2} = 0 \quad (2.7a)$$

$$\nabla \times (\nabla \times \mathbf{H}) + \mu\sigma \frac{\partial \mathbf{H}}{\partial t} + \mu\epsilon \frac{\partial^2 \mathbf{H}}{\partial t^2} = 0 \quad (2.7b)$$

Maka kita dapatkan persamaan gelombang untuk medan listrik dan medan magnet sebagai berikut:

$$\nabla^2 \mathbf{E} - \mu\sigma \frac{\partial \mathbf{E}}{\partial t} - \mu\epsilon \frac{\partial^2 \mathbf{E}}{\partial t^2} = 0 \quad (2.8a)$$

$$\nabla^2 \mathbf{H} - \mu\sigma \frac{\partial \mathbf{H}}{\partial t} - \mu\epsilon \frac{\partial^2 \mathbf{H}}{\partial t^2} = 0 \quad (2.8b)$$

Dalam pendekatan metode magnetotellurik biasa digunakan medan elektromagnetik yang bervariasi secara sinusoidal terhadap waktu. Secara matematis dapat dituliskan sebagai berikut:

$$\mathbf{E} = \mathbf{E}_0 e^{i\omega t - kz} \quad (2.9a)$$

$$\mathbf{H} = \mathbf{H}_0 e^{i\omega t - kz} \quad (2.9b)$$

Dengan mensubstitusikan persamaan (2.9) ke dalam persamaan (2.8) maka diperoleh:

$$\begin{aligned}
\nabla^2 \mathbf{E} - \mu\sigma \frac{\partial \mathbf{E}}{\partial t} - \mu\varepsilon \frac{\partial^2 \mathbf{E}}{\partial t^2} &= 0 \\
\nabla^2 \mathbf{E} - \mu\sigma \frac{\partial \mathbf{E}_0 e^{i\omega t - kz}}{\partial t} - \mu\varepsilon \frac{\partial^2 \mathbf{E}_0 e^{i\omega t - kz}}{\partial t^2} &= 0 \\
\nabla^2 \mathbf{E} - i\omega\mu\sigma \mathbf{E}_0 e^{i\omega t - kz} - i\omega\mu\varepsilon \frac{\partial \mathbf{E}_0 e^{i\omega t - kz}}{\partial t} &= 0 \\
\nabla^2 \mathbf{E} - i\omega\mu\sigma(\mathbf{E}) - i^2\omega^2\mu\varepsilon(\mathbf{E}) &= 0
\end{aligned} \tag{2.10}$$

Dan,

$$\begin{aligned}
\nabla^2 \mathbf{H} - \mu\sigma \frac{\partial \mathbf{H}}{\partial t} - \mu\varepsilon \frac{\partial^2 \mathbf{H}}{\partial t^2} &= 0 \\
\nabla^2 \mathbf{H} - \mu\sigma \frac{\partial \mathbf{H}_0 e^{i\omega t - kz}}{\partial t} - \mu\varepsilon \frac{\partial^2 \mathbf{H}_0 e^{i\omega t - kz}}{\partial t^2} &= 0 \\
\nabla^2 \mathbf{H} - i\omega\mu\sigma \mathbf{H}_0 e^{i\omega t - kz} - i\omega\mu\varepsilon \frac{\partial \mathbf{H}_0 e^{i\omega t - kz}}{\partial t} &= 0 \\
\nabla^2 \mathbf{H} - i\omega\mu\sigma(\mathbf{H}) - i^2\omega^2\mu\varepsilon(\mathbf{H}) &= 0
\end{aligned} \tag{2.11}$$

Karena, $i^2 = -1$ atau $i = \sqrt{-1}$, maka:

$$\nabla^2 \mathbf{E} - i\omega\mu\sigma(\mathbf{E}) + \omega^2\mu\varepsilon(\mathbf{E}) = 0 \tag{2.12a}$$

$$\nabla^2 \mathbf{H} - i\omega\mu\sigma(\mathbf{H}) + \omega^2\mu\varepsilon(\mathbf{H}) = 0 \tag{2.12b}$$

Atau,

$$\nabla^2 \mathbf{E} = (i\omega\mu\sigma - \omega^2\mu\varepsilon)\mathbf{E} \tag{2.13a}$$

$$\nabla^2 \mathbf{H} = (i\omega\mu\sigma - \omega^2\mu\varepsilon)\mathbf{H} \tag{2.13b}$$

Perambatan dalam medium bumi (material bumi memiliki nilai konduktifitas $10^{-3} S/m \leq \sigma \leq 10^3 S/m$ dan nilai permitivitas ε dianggap sama dengan ε_0) dan gelombang yang merambat memiliki frekuensi rendah ($f < 10 \text{ kHz}$) maka $\sigma \gg \varepsilon\omega$, sehingga persamaan (2.13) menjadi:

$$\nabla^2 \mathbf{E} = i\omega\mu\sigma\mathbf{E} \tag{2.14a}$$

$$\nabla^2 \mathbf{H} = i\omega\mu\sigma\mathbf{H} \tag{2.14b}$$

Atau:

$$k^2 \mathbf{E} - i\omega\mu\sigma \mathbf{E} = 0 \quad (2.15a)$$

$$k^2 \mathbf{H} - i\omega\mu\sigma \mathbf{H} = 0 \quad (2.15b)$$

Dimana k merupakan bilangan gelombang.

Lampiran 5: Bilangan Gelombang (k)

Nilai k diperoleh dari:

$$\nabla^2 \mathbf{E} = \mu\sigma \frac{\partial \mathbf{E}}{\partial t} + \mu\varepsilon \frac{\partial^2 \mathbf{E}}{\partial t^2}$$

$$\frac{\partial^2 (\mathbf{E}_0 e^{ikz} e^{i\omega t})}{\partial z^2} = \mu\sigma \frac{\partial (\mathbf{E}_0 e^{ikz} e^{i\omega t})}{\partial t} + \mu\varepsilon \frac{\partial^2 (\mathbf{E}_0 e^{ikz} e^{i\omega t})}{\partial t^2}$$

$$-ik \frac{\partial (\mathbf{E}_0 e^{ikz} e^{i\omega t})}{\partial z} = \mu\sigma i\omega \mathbf{E}_0 e^{ikz} e^{i\omega t} + i\omega\mu\varepsilon \frac{\partial (\mathbf{E}_0 e^{ikz} e^{i\omega t})}{\partial t}$$

$$k^2 \mathbf{E}_0 e^{ikz} e^{i\omega t} = i\omega\mu\sigma \mathbf{E}_0 e^{ikz} e^{i\omega t} - \omega^2 \mu\varepsilon \mathbf{E}_0 e^{ikz} e^{i\omega t}$$

$$k^2 \mathbf{E} = i\omega\mu\sigma \mathbf{E} - \omega^2 \mu\varepsilon \mathbf{E}$$

$$k^2 \mathbf{E} = (i\omega\mu\sigma - \omega^2 \mu\varepsilon) \mathbf{E}$$

$$k^2 = (i\omega\mu\sigma - \omega^2 \mu\varepsilon)$$

Karena nilai $\varepsilon < \sigma$, maka:

$$k^2 = i\omega\mu\sigma$$

Atau:

$$k = \sqrt{i\omega\mu\sigma} \tag{2.16}$$

Lampiran 6: Skin Depth (δ)

$$k = \sqrt{i\omega\mu\sigma}$$

$$k = \sqrt{i}\sqrt{\omega\mu\sigma}$$

Diketahui:

$$\frac{1+i}{\sqrt{2}} = \sqrt{i}$$

$$\frac{(1+i)^2}{2} = i$$

$$\frac{1+2i+i^2}{2} = i$$

$$1 + i + i^2 = i$$

$$1 + i - 1 = i$$

$$i = i \text{ (TERBUKTI)}$$

Maka,

$$k = \frac{1+i}{\sqrt{2}} \sqrt{\omega\mu\sigma}$$

$$k = \sqrt{\frac{\omega\mu\sigma}{2}} + i \sqrt{\frac{\omega\mu\sigma}{2}}$$

$$k = \sqrt{\frac{\omega\mu\sigma}{2}}$$

Sehingga,

$$\delta = \frac{1}{\text{Re}(k)} = \sqrt{\frac{2}{\omega\mu\sigma}}, \text{ dimana } \sigma = \frac{1}{\rho}, \text{ maka:}$$

$$= \sqrt{\frac{2\rho}{\mu\omega}}, \text{ dimana } \mu = 4\pi \times 10^{-7} \text{ dan } \omega = 2\pi f = \frac{2\pi}{T}$$

$$= \sqrt{\frac{2\rho}{(4\pi \times 10^{-7})(\frac{2\pi}{T})}}$$

$$\begin{aligned}
&= \sqrt{\frac{\rho T}{(4\pi^2 \times 10^{-7})}} \\
&= \frac{1}{2\pi} \sqrt{\frac{\rho T}{(10^{-1} \cdot 10^{-6})}} \\
&= \frac{1}{2\pi} \sqrt{\rho T 10 \cdot 10^6} \\
&= \frac{1}{2\pi} 10^3 \sqrt{\rho T 10} \\
&= \frac{1}{2\pi} 3,16(10^3) \sqrt{\rho T} \\
&= 503 \sqrt{\frac{\rho}{f}} \text{ (m)} \tag{2.17}
\end{aligned}$$

Lampiran 7: Dokumentasi Akuisisi Data

