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## LAMPIRAN

Lampiran 1 Dokumentasi kalibrasi Sensor *Soil Moisture* dan *Soil Meter*



Lampiran 2 Dokemntasi kalibrasi sensor DHT22 dan HTC-2



### Lampiran 3 Perhitungan delay dan jitter pengujian pertama pada Excel

	A	B	C	D	E	F	G	H
No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Jitter	
1	0	0	0.048695	0.048695	-0.65287	2.715565		
2	0.048695	0.048695	2.76026	2.71565	2.579641	0.131924	-2.447717	
3	2.76026	2.892184	0.131924	0.131924	0	-0.131924		
4	2.892184	2.892184	2.892184	0	0	0		
5	2.892184	2.892184	2.892184	0	0	0		
6	2.892184	2.892184	2.892184	0	0	0		
7	2.892184	2.892184	2.892184	0	-0.000652	0.000652	0.001304	
8	2.892184	2.892184	2.892184	0	0.0075	0.0075	0	
9	2.900336	2.900336	2.900336	0	-0.01199	0.01199	0.02398	
10	2.900336	2.900336	2.900336	0	0	0		
11	2.900336	2.900336	2.911326	0.01199	0.01199	0	-0.01199	
12	2.911326	2.911326	2.911326	0	-0.000436	0.000436	0.000872	
13	2.911326	2.911326	2.912762	0.000436	-0.013227	0.013663	0.02889	
14	2.912762	2.912762	2.926425	0.013663	0.013663	0	-0.013663	
								Total Delay: 0.01822 Total Jitter: 0.007153 Run Delay: 0.007153 Run Jitter: 0.0007164

### Lampiran 4 Perhitungan delay dan jitter pengujian kedua pada Excel

	A	B	C	D	E	F	G	H
No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Jitter	
1	0	0	0.065999	0.065999	0.065999	-0.065999	-0.065999	
2	0.065999	0.065999	0.066152	0.000153	-0.00063	0.007912	0.001411	
3	0.066152	0.066152	0.066934	0.000792	-0.04783	0.048612	0.066934	
4	0.066934	0.066934	0.115546	0.048612	0.046534	0.02086	-0.04348	
5	0.115546	0.115546	0.117614	0.02086	-0.03555	0.045167	0.109166	
6	0.117614	0.117614	0.20321	0.085617	0.058449	0.000172	-0.05827	
7	0.20321	0.20321	0.203403	0.000172	-0.03092	0.031095	0.062018	
8	0.203403	0.203403	0.234499	0.031095	-0.24291	0.274004	0.516913	
9	0.234499	0.234499	0.508502	0.274004	0.212665	0.061339	-0.15133	
10	0.508502	0.508502	0.569841	0.061339	0.061339	0	-0.06134	
11	0.569841	0.569841	0.569841	0	0	0		
12	0.569841	0.569841	0	-0.00019	0.000192	0.000384		
13	0.569841	0.569841	0.570033	-0.000192	-0.0009	0.00109	0.001988	
14	0.570033	0.570033	0.571123	0.00109	-0.03907	0.04016	0.07023	
15	0.571123	0.571123	0.611283	0.04016	0.037512	0.002648	-0.03486	
								Total Delay: 0.018187 Total Jitter: 0.005853 Run Delay: 0.005856 Run Jitter: 0.000583

### Lampiran 5 Perhitungan delay dan jitter pada pengujian ketiga pada Excel

	A	B	C	D	E	F	G	H
No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Jitter	
1	0	0	0.000107	0.000107	-0.00874	0.00885	0.017593	
2	0.000107	0.000107	0.008957	0.008857	-0.02322	0.032074	0.055298	
3	0.008957	0.008957	0.041931	0.032074	-0.086	0.118972	0.204907	
4	0.041931	0.041931	0.159103	0.118972	0.1062142	0.05593	-0.00621	
5	0.159103	0.159103	0.215103	0.08592	0.059817	0.000113	-0.05557	
6	0.215103	0.215103	0.215146	0.000113	-0.00096	0.001071	0.002049	
7	0.215146	0.215146	0.216217	0.001071	-0.04614	0.047212	0.003533	
8	0.216217	0.216217	0.263429	0.047212	0	-0.04721		
9	0.263429	0.263429	0	-0.00671	0.006715	0.001343		
10	0.263429	0.263429	0.270144	0.006715	0.004428	0.002187	-0.00214	
11	0.270144	0.270144	0.272431	0.092287	-0.08072	0.08301	0.164743	
12	0.272431	0.272431	0.355441	0.08301	0.06301	0	-0.06301	
13	0.355441	0.355441	0	0	0	0		
14	0.355441	0.355441	0	0	0	0		
15	0.355441	0.355441	0	0	0	0		
								Total Delay: 0.018187 Total Jitter: 0.005853 Run Delay: 0.005856 Run Jitter: 0.000583



### Lampiran 6 Perhitungan delay dan jitter pada pengujian keempat pada Excel

No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Jitter	A	B	C	D	E	F	G	H	
1	0	0	0.000181	0.000181	0.000097	0.000111	0.000041	9962	9961	55,7905	55,7905	55,79466	0,00046	-0,00058	0,001038	0,001616
2	0.000181	0.000181	0.000292	0.000111	-0,00122	0.00133	0.000447	9963	9962	55,79090	55,79090	55,79796	0,001038	0	-0,00104	
3	0.000292	0.000292	0.001622	0.00133	0.00133	0	-0,00133	9974	9963	55,798	55,798	55,79798	0	-0,02543	0,023143	0,05096
4	0.001622	0.001622	0.001622	0	-0,00016	0.000163	0.000326	9975	9965	55,798	55,798	55,823428	0,02543	-0,06095	0,085382	0,147334
5	0.001622	0.001622	0.001785	0.000163	-0,05459	0.054750	0,109349	9976	9966	55,823413	55,823428	55,90951	0,02543	-1,06502	1,151401	2,21642
6	0.001785	0.001785	0.056541	0.054750	0,109349	0,109349	0,00076	9977	9966	55,823413	55,823428	55,90951	0,02543	-1,06502	1,151401	2,21642
7	0.056541	0.056541	0.056541	0	-0,00267	0,000534	0,000267	9978	9977	55,823413	55,823428	55,90951	0	0	0	0
8	0.056541	0.056541	0.056808	0.000267	-0,00112	0,001388	0,000250	9979	9973	55,823413	55,823428	55,90951	0	0	0	0
9	0.056808	0.056808	0.058196	0.001388	0	-0,00139	0,000196	9980	9978	55,823413	55,823428	55,90951	0	-0,00107	0,001073	0,001246
10	0.058196	0.058196	0.058196	0	-0,0002	0,000196	0,000196	9981	9979	55,823413	55,823428	55,90951	0	-0,00016	0,000161	0,000161
11	0.058196	0.058196	0.058392	0.000196	-0,14249	0,142681	0,285166	9982	9978	55,823413	55,823428	55,90951	0	0	0	0
12	0.058392	0.058392	0.201073	0.142681	0,142577	0,000104	-0,14247	9983	9978	55,823413	55,823428	55,90951	0	0	0	0
13	0.201073	0.201073	0.201177	0,000104	-0,08318	0,083284	0,166464	9984	9978	55,823413	55,823428	55,90951	0	-0,00010	0,000101	0,000122
14	0.201177	0.201177	0.284461	0,083284	0,083284	0	-0,083284	9985	9968	60,06121	60,06121	60,203112	0,1419307	0,130954	0,010953	-0,12
15	0.284461	0.284461	0.284461	0	-0,010953	0,010953	0,010953	9986	9968	60,06121	60,06121	60,214071	0,1419307	0,010953	0	-0,01095
Total Delay: 60,57005 Total Jitter: 60,56985 Rata Delay: 0,006069 Rata Jitter: 0,006069																

### Lampiran 7 Perhitungan delay dan jitter pada pengujian kelima pada Excel

No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Jitter	A	B	C	D	E	F	G	H	
1	0	0	0.009693	0.009693	0.009503	0.000127	-0,009693	10462	10461	55,7979	55,7979	55,799442	0,001538	-0,04443	0,04568	0,019698
2	0.009693	0.009693	0.009757	0.000127	-0,000686	0,000099	-0,001853	10463	10462	55,79944	55,79944	55,814541	0,04568	0,013187	0,042781	-0,00845
3	0.009757	0.009757	0.070747	0,000999	-0,05455	0,035544	0,110095	10464	10463	55,814541	55,814541	55,878191	0,021781	0,020604	0,012177	-0,00845
4	0.070747	0.070747	0.126291	0,055544	0,054005	0,001476	-0,05230	10465	10464	55,878191	55,878191	55,890318	0,012177	0,01591	0,00556	-0,01101
5	0.126291	0.126291	0.127777	0,001479	-0,08533	0,05678	0,172081	10466	10465	55,890317	55,890317	55,899554	0,012177	0,011745	0,118933	0,23554
6	0.127777	0.127777	0.21455	0,08678	0,086685	9,50E-05	-0,086695	10467	10466	55,890317	55,890317	55,908085	0,012177	-3,14625	3,26428	0
7	0.21455	0.21455	0.214645	9,50E-05	-0,08283	0,082925	0,125755	10468	10467	55,890317	55,890317	55,908089	0,012177	-0,00014	0,00014	-0,26425
8	0.214645	0.214645	0.27757	0,062925	-0,49058	0,553508	1,044093	10469	10468	55,890317	55,890317	55,908089	0,012177	-1,00974	2,019748	
9	0.27757	0.27757	0.831079	0,553509	0,553509	0	-0,553501	10470	10469	55,890317	55,890317	55,908089	0,012177	-1,00974	2,019748	
10	0.831079	0.831079	0,831079	0	0	0	-0,00018	10471	10469	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
11	0.831079	0.831079	0,831079	0	0	0	-0,00018	10472	10471	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
12	0.831079	0.831079	0,831079	0	-0,00018	0,000176	0,000352	10473	10472	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
13	0.831079	0.831079	0,831079	0	-0,00018	0,000176	0,000352	10474	10473	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
14	0.831079	0.831079	0,831255	0,000176	4,40E-05	0,000152	8,00E-05	10475	10474	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
15	0.831255	0.831255	0,831387	0,000132	-0,00181	0,001937	0,003742	10476	10475	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
16	0.831387	0.831387	0,831324	0,0001937	-0,02012	0,022054	0,042171	10477	10476	55,890317	55,890317	55,908089	0,012177	-0,00013	0,00013	-0,00018
Total Delay: 60,60093 Total Jitter: 61,47957 Rata Delay: 0,003783 Rata Jitter: 0,002568																

### Lampiran 8 Perhitungan delay dan jitter pengujian keenam pada Excel

No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Jitter	A	B	C	D	E	F	G	H	
1	0	0	0.204365	0.204365	0.000129	-0,204136	-0,000129	10407	10406	60,42054	60,42054	60,420536	0	0	0	0
2	0.204365	0.204365	0.204494	0,000129	6,20E-05	5,00E-05	-0,000129	10408	10407	60,42054	60,42054	60,420536	0	-0,00021	0,00021	0,000426
3	0.204494	0.204494	0,204561	6,70E-05	-0,00096	0,001025	0,001983	10409	10408	60,42054	60,42054	60,420539	0,000213	-0,12193	0,322164	0,244115
4	0.204561	0.204561	0,205586	0,000125	-0,03307	0,040497	0,067169	10410	10409	60,42054	60,42054	60,420539	0,000213	-0,046937	0,000187	-0,04672
5	0.205586	0,205586	0,239683	0,0004097	0,022878	0,011219	-0,01166	10411	10410	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	0,000595
6	0,239683	0,239683	0,2404494	0,0004097	0,022878	0,011219	-0,01166	10412	10411	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
7	0,2404494	0,2404494	0,241779	0,0004097	0,022878	0,011219	-0,01166	10413	10412	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
8	0,241779	0,241779	0,244424	0,0004097	0,022878	0,011219	-0,01166	10414	10413	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
9	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10415	10414	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
10	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10416	10415	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
11	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10417	10416	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
12	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10418	10417	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
13	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10419	10418	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
14	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10420	10419	60,59001	60,59001	60,590194	0,000167	-0,0002	0,000191	-0,000595
15	0,244424	0,244424	0,244424	0,0004097	0,022878	0,011219	-0,01166	10421	10420	60,59001	60,59001	60,590194	0,000167	-		

## Lampiran 9 Perhitungan delay dan jitter pengujian ketujuh pada Excel

	A	B	C	D	E	F	G	H
1	No.	Time	Time 1	Time 2	Delay	Delay 1	Delay 2	Time
2	1	0	0.059915	0.059915	-0.13226	0.192178	0.324441	9441
3	2	0.059915	0.059915	0.242098	0.192178	0.153142	0.039036	-0.14111
4	3	0.252093	0.252093	0.291129	0.039036	0.038935	0.000101	-0.03583
5	4	0.291129	0.291129	0.291121	0.000101	-0.00069	0.000794	0.001487
6	5	0.29123	0.29123	0.292024	0.000794	-0.04128	0.042072	0.08335
7	6	0.292024	0.292024	0.334096	0.042072	0.008999	0.033473	0.024874
8	7	0.334096	0.334096	0.347569	0.033473	0.014226	0.019245	0.005017
9	8	0.367569	0.367569	0.366814	0.019245	-0.23244	0.251686	0.484127
10	9	0.366814	0.366814	0.6935	0.251686	0.248939	0.002277	-0.48623
11	10	0.6935	0.6935	0.641227	0.002277	-0.02682	0.029548	0.056369
12	11	0.641227	0.641227	0.670775	0.029548	0.029459	8.90E-05	-0.02937
13	12	0.670775	0.670775	0.670664	8.90E-05	-0.03443	0.034517	0.068945
14	13	0.670664	0.670664	0.705381	0.034517	-1.01096	0.045478	2.056439
15	14	0.705381	0.705381	1.750859	0.045478	1.045478	0	-1.04548

Total Delay 69.15268 Total Jitter 60.32926

Mean Delay 0.096364 Mean Jitter 0.096364

## Lampiran 10 Program pengirim pada Arduino IDE

```
#include <SPI.h>
#include <LoRa.h>
#include <DHT.h>

#define relay1Pin 4 // Heater
#define relay2Pin 5 // Fan
#define ss 2
#define rst 13
#define dio0 14
#define en 32
#define dhtPin 15
#define kadarAirPin A0

DHT dht(dhtPin, DHT22);
int counter = 0;

void setup() {
    pinMode(relay1Pin, OUTPUT);
    pinMode(relay2Pin, OUTPUT);
    pinMode(en, OUTPUT);
    digitalWrite(en, LOW);

    Serial.begin(115200);
    (!Serial);

    1.println("LoRa Sender");
}
```



```

LoRa.setPins(ss, rst, dio0);

while (!LoRa.begin(915E6)) {
    Serial.println("LoRa Initializing...");
    delay(500);
}

LoRa.setSyncWord(0xF3);
Serial.println("LoRa Initializing OK!");
dht.begin();
}

void loop() {
    Serial.print("Sending packet: ");
    Serial.println(counter);

    float suhu = dht.readTemperature();
    float kelembapan = dht.readHumidity();

    int sensorValue = analogRead(kadarAirPin);
    int kadarAir = map(sensorValue, 4092, 0, 0, 100);

    Serial.print("suhu: ");
    Serial.print(suhu);
    Serial.print("°C, kelembapan: ");
    Serial.print(kelembapan);
    Serial.print("%, kadarAir: ");
    Serial.println(kadarAir);

    String sensorData = String(suhu, 1) + "," + String(kelembapan)
+ "," + kadarAir;

    LoRa.beginPacket();
    LoRa.print(sensorData);
    LoRa.endPacket();

    counter++;
    delay(2000); // Send data every 2 seconds

    // Control Relay 1 based on conditions
    if (suhu < 40 || kelembapan > 70 || kadarAir > 14) {
        digitalWrite(relay1Pin, LOW); // Relay 1 ON
        se {
            gitalWrite(relay1Pin, HIGH); // Relay 1 OFF
    }
}

```



```
// Control Relay 2 based on conditions
if (suhu > 60) {
    digitalWrite(relay2Pin, LOW); // Relay 2 ON
} else {
    digitalWrite(relay2Pin, HIGH); // Relay 2 OFF
}
```

### Lampiran 11 Program penerima pada Arduino IDE

```
#include <SPI.h>
#include <LoRa.h>
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
#include <WiFi.h>
#include <HTTPClient.h>

const char* ssid = "sals";
const char* password = "salsabilaa21";
const String host = "api.thingspeak.com";
const String apiKey = "11SVWWIFIILAIZAYN"; // Ganti dengan API
Key ThingSpeak Anda

LiquidCrystal_I2C lcd(0x27, 20, 4); // Alamat I2C dan ukuran LCD
16x2

void setup() {
    // Connect to Wi-Fi
    WiFi.begin(ssid, password);
    while (WiFi.status() != WL_CONNECTED) {
        delay(1000);
        Serial.println("Connecting to WiFi...");
    }
    Serial.println("Connected to WiFi");

    // Initialize the LoRa Enable pin
    pinMode(32, OUTPUT);
    // LoRa chip is Active Low
    digitalWrite(32, LOW);

    initialize Serial Monitor
    Serial.begin(115200);
    if (!Serial)
```



```

// Setup LoRa transceiver module
LoRa.setPins(2, 13, 14); // Ganti pin sesuai dengan konfigurasi
ESP32
while (!LoRa.begin(915E6)) {
    Serial.println("LoRa Initializing...");
    delay(500);
}

// Change sync word to match the sender
LoRa.setSyncWord(0xF3);
Serial.println("LoRa Initializing OK!");

// Initialize LCD
lcd.init();
lcd.backlight();
lcd.setCursor(0, 0);
lcd.print("LoRa Receiver");
}

void loop() {
    int packetSize = LoRa.parsePacket();

    if (packetSize) {
        while (LoRa.available()) {
            String receivedData = LoRa.readString();
            Serial.print("Data diterima: ");
            Serial.println(receivedData);

            // Split the received data into temperature, humidity, and
            // soil moisture
            float suhu, kelembapan;
            int kadarAir;
            if (sscanf(receivedData.c_str(), "%f,%f,%d", &suhu,
                       &kelembapan, &kadarAir) == 3) {
                // Display data on the LCD
                lcd.clear();
                lcd.setCursor(0, 0);
                lcd.print("suhu: ");
                lcd.print(suhu);
                lcd.print("C");
                lcd.setCursor(0, 1);
                lcd.print("kelembapan: ");
                lcd.print(kelembapan);
                lcd.print("%");
            }
        }
    }
}

```



```

        delay(2000); // Display temperature and humidity for 2
seconds

        lcd.clear();
        lcd.setCursor(0, 0);
        lcd.print("kadarAir: ");
        lcd.print(kadar air);
        lcd.print("%");
        lcd.setCursor(0, 1);
        lcd.print("");

        // Send data to ThingSpeak
        sendToThingSpeak(suhu, kelembapan, kadarAir);
    }
}
}

void sendToThingSpeak(float suhu, float kelembapan, int kadarAir)
{
    HTTPClient http;

    String data = "field1=" + String(suhu, 1) + "&field2=" +
String(kelembapan) + "&field3=" + String(kadarAir);
    String url = "http://" + host + "/update";

    http.begin(url);
    http.addHeader("Content-Type", "application/x-www-form-
urlencoded");
    http.addHeader("X-THINGSPEAKAPIKEY", apiKey);

    int httpResponseCode = http.POST(data);
    if (httpResponseCode > 0) {
        Serial.print("HTTP Response code: ");
        Serial.println(httpResponseCode);
    } else {
        Serial.println("Error sending data to ThingSpeak");
    }

    http.end();
}

```

