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LAMPIRAN

Lampiran 1 Dokumentasi Pelaksanaan Penelitian

1.1 Pengambilan Data



Lampiran 2 Kode Pemograman

2.1 Program Training Data

```
import torch
from torch import optim
from torch.nn import CrossEntropyLoss, MSELoss
from tqdm import tqdm
from tensorboardX import SummaryWriter
from src.utility import get_time
from src.model_lib.MultiFTNet import MultiFTNet
```

```

from src.data_io.dataset_loader import get_train_loader

class TrainMain:
    def __init__(self, conf):
        self.conf = conf
        self.board_loss_every = conf.board_loss_every
        self.save_every = conf.save_every
        self.step = 0
        self.start_epoch = 0
        self.train_loader = get_train_loader(self.conf)

    def train_model(self):
        self._init_model_param()
        self._train_stage()

    def _init_model_param(self):
        self.cls_criterion = CrossEntropyLoss()
        self.ft_criterion = MSELoss()
        self.model = self._define_network()
        self.optimizer = optim.SGD(self.model.module.parameters(),
                                    lr=self.conf.lr,
                                    weight_decay=5e-4,
                                    momentum=self.conf.momentum)

        self.schedule_lr = optim.lr_scheduler.MultiStepLR(
            self.optimizer, self.conf.milestones, self.conf.gamma, - 1)

    print("lr: ", self.conf.lr)
    print("epochs: ", self.conf.epochs)
    print("milestones: ", self.conf.milestones)

```

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def _train_stage(self):
    self.model.train()
    running_loss = 0.
    running_acc = 0.
    running_loss_cls = 0.
    running_loss_ft = 0.
    is_first = True
    for e in range(self.start_epoch, self.conf.epochs):
        if is_first:
            self.writer = SummaryWriter(self.conf.log_path)
            is_first = False
        print('epoch {} started'.format(e))
        print("lr: ", self.schedule_lr.get_lr())

        for sample, ft_sample, target in tqdm(iter(self.train_loader)):
            imgs = [sample, ft_sample]
            labels = target

            loss, acc, loss_cls, loss_ft = self._train_batch_data(imgs, labels)
            running_loss_cls += loss_cls
            running_loss_ft += loss_ft
            running_loss += loss
            running_acc += acc

        self.step += 1

    loss_board = running_loss / self.board_loss_every
    self.writer.add_scalar(
        'Training/Loss', loss_board, self.step)
    acc_board = running_acc / self.board_loss_every

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self.writer.add_scalar(
    'Training/Acc', acc_board, self.step)
lr = self.optimizer.param_groups[0]['lr']
self.writer.add_scalar(
    'Training/Learning_rate', lr, self.step)
loss_cls_board = running_loss_cls / self.board_loss_every
self.writer.add_scalar(
    'Training/Loss_cls', loss_cls_board, self.step)
loss_ft_board = running_loss_ft / self.board_loss_every
self.writer.add_scalar(
    'Training/Loss_ft', loss_ft_board, self.step)

running_loss = 0.
running_acc = 0.
running_loss_cls = 0.
running_loss_ft = 0.

time_stamp = get_time()
self._save_state(time_stamp, extra=self.conf.job_name)
self.schedule_lr.step()

time_stamp = get_time()
self._save_state(time_stamp, extra=self.conf.job_name)
self.writer.close()

def _train_batch_data(self, imgs, labels):
    self.optimizer.zero_grad()
    labels = labels.to(self.conf.device)

    if imgs[0].size() == torch.Size([1, 80, 80, 3]):
        imgs[0] = imgs[0].permute(0, 3, 1, 2).float()

```

```

else:
    pass

embeddings, feature_map = self.model.forward(imgs[0].to(self.conf.device))

loss_cls = self.cls_criterion(embeddings, labels)
loss_fea = self.ft_criterion(feature_map, imgs[1].to(self.conf.device))
print("loss :", loss_fea)

loss = 0.5*loss_cls + 0.5*loss_fea
acc = self._get_accuracy(embeddings, labels)[0]
loss.backward()
self.optimizer.step()
return loss.item(), acc, loss_cls.item(), loss_fea.item()

def _define_network(self):
    param = {
        'num_classes': self.conf.num_classes,
        'img_channel': self.conf.input_channel,
        'embedding_size': self.conf.embedding_size,
        'conv6_kernel': self.conf.kernel_size}

    model = MultiFTNet(**param).to(self.conf.device)
    model = torch.nn.DataParallel(model, self.conf.devices)
    return model

def _get_accuracy(self, output, target, topk=(1,)):
    maxk = max(topk)
    batch_size = target.size(0)
    _, pred = output.topk(maxk, 1, True, True)
    pred = pred.t()

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correct = pred.eq(target.view(1, -1).expand_as(pred))

ret = []
for k in topk:
    correct_k = correct[:k].view(-1).float().sum(dim=0, keepdim=True)
    ret.append(correct_k.mul_(1. / batch_size))
return ret

def _save_state(self, time_stamp, extra=None):
    save_path = self.conf.model_path
    torch.save(self.model.state_dict(), save_path + '/' +
               ('{}_{}_model_iter-{}.pth'.format(time_stamp, extra, self.step)))

```

2.2 Program Testing

```

import cv2
import numpy as np
import argparse
import warnings
import time
import os

from src.anti_spoof_predict import AntiSpoofPredict
from src.generate_patches import CropImage
from src.utility import parse_model_name

warnings.filterwarnings('ignore')

def detect_faces(image):
    gray = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)

    face_cascade = cv2.CascadeClassifier(cv2.data.harcascades +
    'haarcascade_frontalface_default.xml')

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faces = face_cascade.detectMultiScale(gray, scaleFactor=1.3, minNeighbors=5)
return faces

```

```

def test_image_from_frame(image, model_test, image_cropper, model_dir):
    image_bbox = model_test.get_bbox(image)
    prediction = np.zeros((1, 3))
    test_speed = 0

    for model_name in os.listdir(model_dir):
        h_input, w_input, model_type, scale = parse_model_name(model_name)
        param = {
            "org_img": image,
            "bbox": image_bbox,
            "scale": scale,
            "out_w": w_input,
            "out_h": h_input,
            "crop": True,
        }
        if scale is None:
            param["crop"] = False
        img = image_cropper.crop(**param)
        start = time.time()
        prediction += model_test.predict(img, os.path.join(model_dir, model_name))
        test_speed += time.time() - start

    label = np.argmax(prediction)
    value = prediction[0][label] / 2
    if label == 1:
        result_text = "RealFace Score: {:.2f}".format(value)
        color = (255, 0, 0)

```

```

else:
    result_text = "FakeFace Score: {:.2f}".format(value/2)
    color = (0, 0, 255)

return result_text, color

def detect_video(model_dir, device_id):
    cap = cv2.VideoCapture(0)

    if not cap.isOpened():
        print("Error opening video stream or file")
        return

    model_test = AntiSpoofPredict(device_id)
    image_cropper = CropImage()

    while cap.isOpened():
        ret, frame = cap.read()
        if not ret:
            break

        faces = detect_faces(frame)

        result_text, color = test_image_from_frame(frame, model_test,
            image_cropper, model_dir)

        cv2.putText(
            frame,
            result_text,
            (10, 30),

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        cv2.FONT_HERSHEY_SIMPLEX, 1, color, 2)

cv2.imshow('Face Recognition and Spoofing Detection', frame)

if cv2.waitKey(1) & 0xFF == ord('q'):
    break

cap.release()
cv2.destroyAllWindows()

if __name__ == "__main__":
    desc = "test"
    parser = argparse.ArgumentParser(description=desc)
    parser.add_argument(
        "--device_id",
        type=int,
        default=0,
        help="which gpu id, [0/1/2/3]")
    parser.add_argument(
        "--model_dir",
        type=str,
        default="./resources/anti_spoof_models",
        help="model_lib used to test")

    args = parser.parse_args()

    detect_video(args.model_dir, args.device_id)

```